Session 3: Instruments, Platforms and Deployment Options

15:15-17:00 Session 3: Instruments, Platforms and Deployment Options Co-chairs: Junhong Wang and Mike Hardesty

- Talks (all 30 minutes)
- Reference Radiosonde Options, Junhong Wang NCAR
- Measurements of Temperature, Water Vapor, Clouds, and Winds Derived from Ground-Based Remote Sensors; Measurements of the Surface Radiation Balance, *Jim Liljgren ANL*
- GPS Atmospheric Sensing, Chris Rocken NCAR
- GCOS reference UA observation network: LUAMI intercomparison campaign, *Franz H. Berger, DWD*

Tuesday 23rd May 8:30-10:00 Special Discussion Session: Emerging Instrument Options from Manufacturers 10:00-10:30 Coffee break 10:30-12:00 Session 3 continued

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Reference Radiosonde System Options for Climate Studies: Introduction for discussions

Junhong (June) Wang NCAR/EOL/T^{II}MES

Co-authors: Frank Schmidlin, Holger Voemel, Mark Paige, Joe Focundo, Jim Fitzgibbon ...



Outlines

- Goals
- Requirements
- Sensor options (T, WV, P, wind and other variables)

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- Integration
- Challenges to make a reference system
- Challenges to maintain long-term stability
- Summary

Goals of Upper-Air Reference Network

- Provide long-term, high-quality climate records
- Serve to constrain and calibrate data from more spatiallycomprehensive global observing systems (inc. satellites)
- Measure a larger suite of corelated climate variables than can be provided as benchmark observations

Long term stability

►• Accuracy

Multiple variables



From Seidel and Thorne's talk

Requirements

	Temperature	Water Vapor	Pressure	Vector Wind	Ozone
Priority (1-4)	1	1	1	2	2
Measurement Range	100-350 K	0.1 ppm to 55 g/kg	1 to 1100 hPa	0 – 300 m/s	0.005-20 ppmV
Vertical Range	0 km to stratopause	0 to ~30 km	0 km to stratopause	0 km to stratopause	Surface to 100 km
Vertical Resolution	0.1 km (surface to ~30 km) 0.5 km (above ~30 km)	0.05 km (surface to 5 km) 0.1 km (5 to ~30 km)	0.1 hPa	0.05 km in troposphere 0.25 km in stratosphere	0.5 km in stratosphere 1 km in troposphere
Precision	0.2 K	0.1 g/kg in lowertroposphere0.001 g/kg in uppertroposphere0.1 ppm stratosphere	0.1 hPa	0.5 m/s in troposphere 1.0 m/s in stratosphere	
Accuracy	0.1 K in troposphere 0.2 K in stratosphere	0.5 g/kg in lower troposphere 0.005 g/kg in upper troposphere 0.1 ppm stratosphere	0.1 hPa	1.0 m/s ¹	3% total column 5% stratosphere 5% troposphere
Long-Term Stability	0.05 K ¹	11%	0.1 hPa	0.5 m/s in troposphere 1.0 m/s in	0.2% total column 0.6% stratosphere 1% troposphere
				stratosphere	

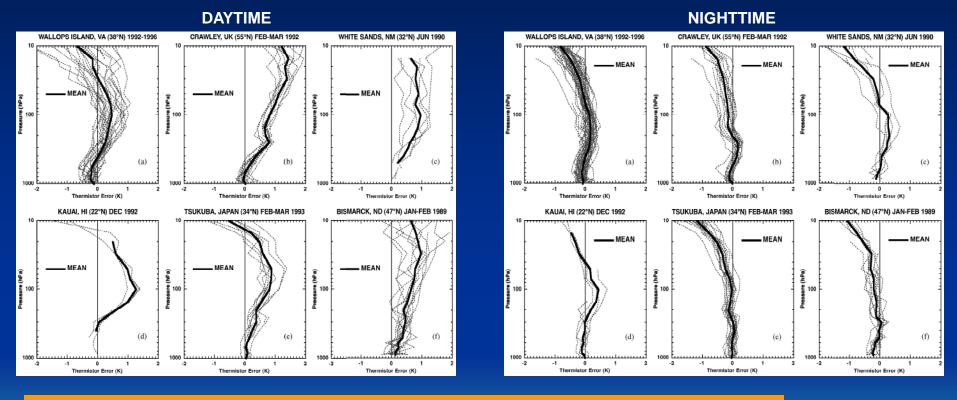
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Temperature

Sonde	Sensor	Measurement Range (°C)	Precision Resolution (°C)	Accuracy (°C)	Long-Term Stability (°C/decade)
Requirements		-170 ~ 77	0.2	0.1/0.2 in TR/ST	0.05
NASA ATM	3-thermistor			0.2/0.2-0.3 in TR/ST	
Sippican multi- thermistor	3 aluminized chips				
Vaisala RS92	Aluminized capacitance	-90 ~ 60	0.2/0.3/0.5 (1080-100/100- 20/20-3 hPa) 0.1	0.5 (total)	
Sippican LMS-5	Aluminized chip thermistor				
Graw DFM-97	Aluminized bead thermistor				
Meisei RS-01G	Aluminized bead thermistor	-85 ~ 40	? ?	0.5	
Meteolabor SRSD-C34	Thermocouple	-100 ~ 60	? 0.01	0.1	
Modem M2K2	White bead thermistor	-90 ~ 55	? 0.1	0.5	NCAR

Temperature

Error of the white rod thermistor in comparison to NASA/ATM at six locations

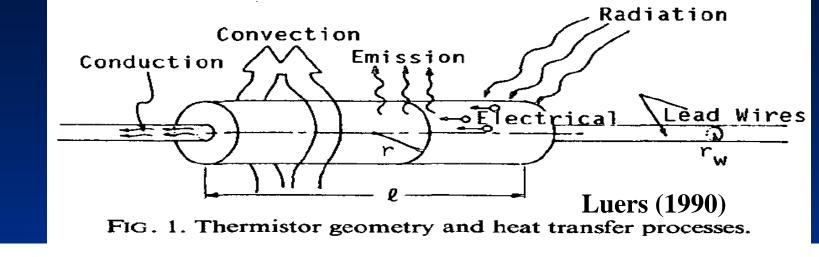


- 1. Daytime radiation error is the most significant one.
- 2. Errors vary with locations.

From Frank Schmidlin



Radiation errors



$mC(dT/dt) = q_{abs} - q_{emit} + q_{conv} + q_{elec} + q_{cond}$

Option #1: Multi-thermistor Technology

- Simultaneously solving multiple heat balance equations;
- Each with different emissivity and absorptivity values;
- Conduction and thermal lag error correction are included;
- Knowledge of the environmental radiative background is not necessary.

Optional #2: Better radiation corrections

- Radiation sensors on the sonde
- Calculating radiation flux profiles with observed cloud, aerosol and other parameters

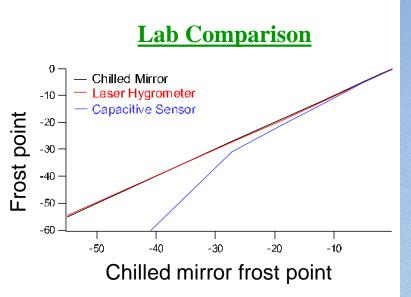


Water Vapor

Measurement Range	Precision	Accuracy	Long-Term Stability	
	\sim \sim	0.5/0.005 g/kg in LT/UT 0.1 ppm in ST	1%/decade	

	Claimed accuracy	Calibration	Limitations	Dynamic range	Histor y	Cost	Ease of use	Engineering
CFH	0.5°C DP/FP 4-9%	++	No "wet" clouds	++	+	- (0)	0	research / small series
Snow White	0.1°C DP/FP		Some clouds RH > 3-6% No ST	0	+	•	++	production small series
Lyman- alpha (FLASH)	9%	+	Night time only Descent only No LT	+	ο		+	research i small series
TDL (MayComm)	5% 0.5 ppmv	o	Discontinuation of laser used	+).		(++)	Proof of concept
TDL (SW)	2%	0	Impacts of cloud droplets	+) -		?	No field testing
Polymer (Vaisala RS92)	1% RH	-	No ST Large radiation error Chemical contamination Hard to trace sensor/calibration changes	-	+	++	+ (++)	Large scale production

940 nm Balloon Borne Hygrometer M.E. Paige, JOAT 22, 1219-1224 (2005).



- Accuracy 2.5%, Precision 1.0%
- Noise levels (1 sec)
 Altitude Low High
 2 mb 0.9 mb
 (-72 C) (-77 C)
- 2 m optical path

• 500 – 750 mW power consumption

• 230 g weight (with batteries)

Improvements have been subsequently made in electronics and lasers

From Mark Paige

WESTCOTT - RULER

Pressure

Sonde	Sensor	Measurement Range (hPa)	Precision (hPa)	Accuracy (hPa)	Long-Term Stability (hPa/decade)
Requirements		1-1100	0.1	0.1?	0.1
Vaisala RS92	Capacitive silicon	3-1080	0.5/0.3 in TR/ST	1.5/0.6 (total)	
Graw DFM-97					
Meisei RS-01G	Aneroid capsule	5-1040	?	1	
Meteolabor SRSD-C34	Hypsometer	5-1100		0.2 (unstable)	
iMet-1	Piezoresistive	2-1070		1.8/0.5 (>/< 400 hPa)	

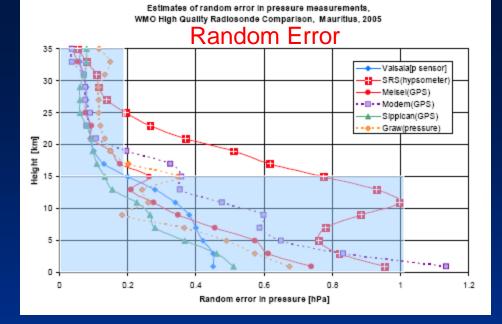
Q:

• Do we need a pressure sensor?

• Are precision and accuracy requirement set too high for troposphere?

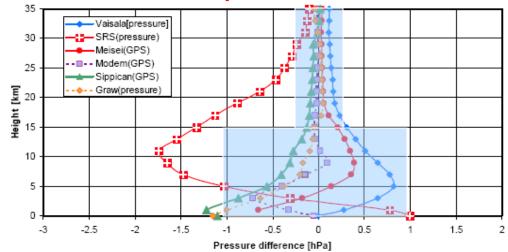


Systematic and random errors in pressure (WMO 2005)



Systematic differences in pressure sensor measurements referenced to the average of the GPS radiosondes at upper levels and the correct fit to surface pressure near the surface, WMO High Quality Radiosonde Comparison, Mauritius

Systematic Error



Requirements: 1 hPa in Troposphere 0.2 hPa in Stratosphere



Geopotential height intercomparison (WMO radiosonde intercomparison results, Vacoas, Mauritius, 2-25 Feb. 2005)

- 1. < 5% missing GPS data
- 2. GPS-geopotential height is more accurate that calculated from pressure sensors for Z > 16 km, but similar for Z < 16 km.
- 3. Random error for GPH_GPS is ≤ 15 m and does not vary with height, but that for GPH_P increases with heights.
- 4. The conversion from geometric to geopotential heights is essential for the comparison.
- 5. "GPS heights are suitable to replace geopotential from pressure sensors at all heights, i.e. a pressure sensor is no longer a necessity for a best quality radiosonde. The reproducibility of the GPS geopotential heights at 32 km was an order of magnitude better than the reproducibility of the heights from the best pressure sensors."

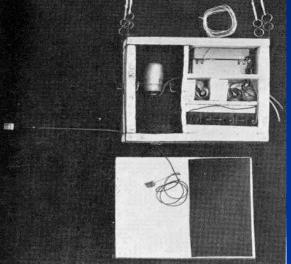


GPS wind

Sonde	Measurem ent Range (m/s)	Precision (m/s)	Accuracy (m/s)	Long-Term Stability (m/s/decade)	Position accuracy (m horizontal/vertical)
Requirements	0-300	0.5/1.0 in TR/ST	1.0	0.5/1.0 in TR/ST	
Vaisala RS92			0.2		10/20
Sippican LMS-5					
Graw DFM-97					
Meisei RS-01G					
Meteolabor SRSD-C34			0.12		2.5/5
Modem M2K2			0.15		10/
iMet-1			1.0		5/15
WMO 2005		0.05/0.1 in TR/ST			
		Quarter			
	GF	PS Receiver		GPS Antenna	NCAR

Other special radiosondes

Electricity: Electric field probe





An RS80 radiosonde with ozone sensor.

Ozonesonde:

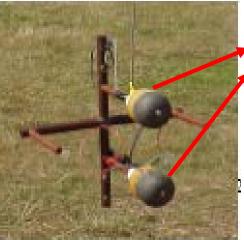
ozone profiles

Radioactivity sonde: B and γ radioactivity



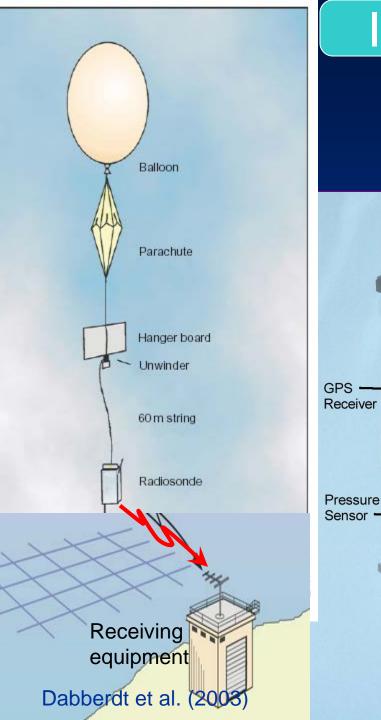
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In-cloud measurements: changes in charge, aerosols



"The housing is that originally supplied to house the small plastic toy contained within a children's confectionery KinderEgg. The outer chocolate enclosure and foil coating must first be removed."

http://www.atd.ucar.edu/homes/junhong/MT11B_radiosondes.pdf from UK_Met officAR



Integration as a system

GPS Antenna

400 MHz

Transmitter

Temperature Sensor

- Smart and careful design to minimize extra errors,
- High performance and multi-channel transmitter,
- Digital and reliable data transmission and reception,
- Flexible infrastructure to host additional sensors
- Mobility and portability



Challenges of making a sonde as a reference

Select best sensors

(laboratory standards, target specifications, reliable calibration)

Take extraordinary procedures to produce the best data (ventilation, radiation, ...)

Calibrate to NIST (in-house/in-field) and keep a detailed metadata

Inter-compare multiple sensors and systems (redundancy, pre-launch check, "Consensus ref. concept"...)

Real-time data quality monitoring and careful post data QC

Effective communications among different stakeholders (operational center, data center, manufactures, data users ...)



Comparisons of prelaunch radiosonde and surface data (both in field and post-processing)

Compare Radiosonde Data to Surface Data System

<u>Surface Data System</u> <u>Values</u>		<u>Sonde</u> <u>Values</u>		Sonde Sensor Offsets
Pressure (mb) 833.2	-	833.8	=	-0.6 mb
Air Temp (C) 18.6	-	18.4	=	<mark>0.2</mark> C
Humidity (%) 34.4	-	31.5	=	2,9 %
Time of Last Surface Data Measurement				

Compare the sonde sensor values above to the Surface Data System values.

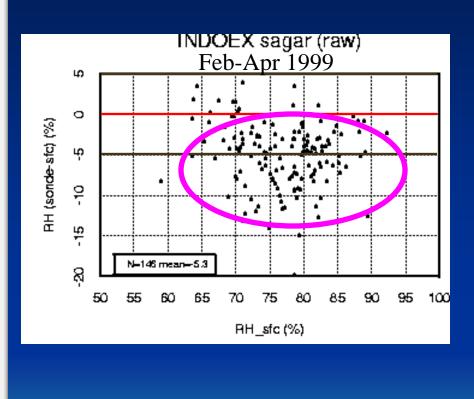
Acceptable Sonde Sensor Offset Limits: Humidity 10 %

Click: "<u>Continue</u>" if Sonde Offset values are reasonable.

Click: "Bad Sonde!" if the values indicate a bad sensor. This choice will return you to the 'Prepare Radiosonde' display.

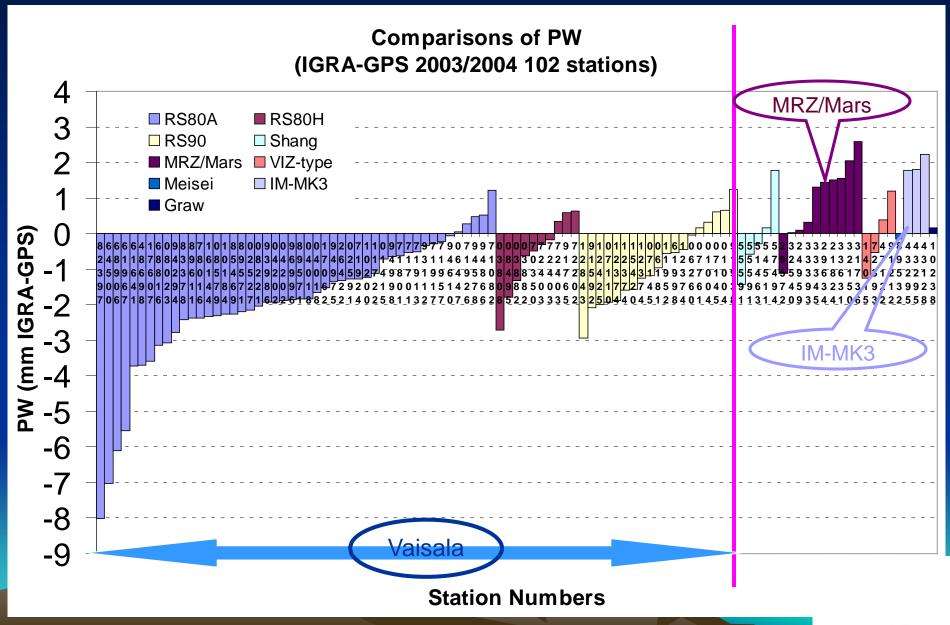


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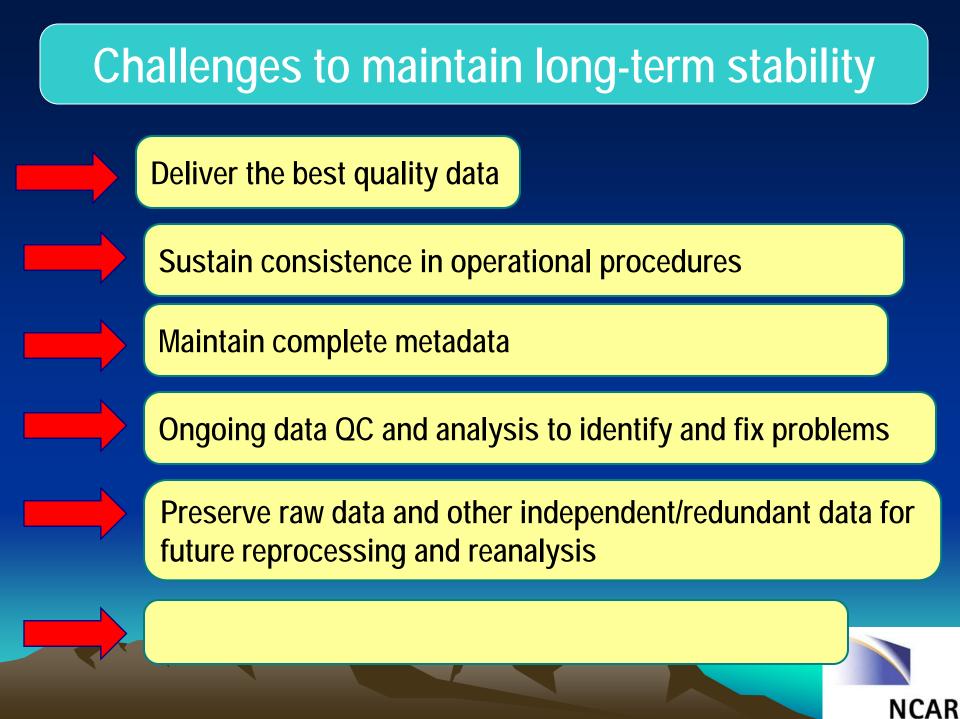




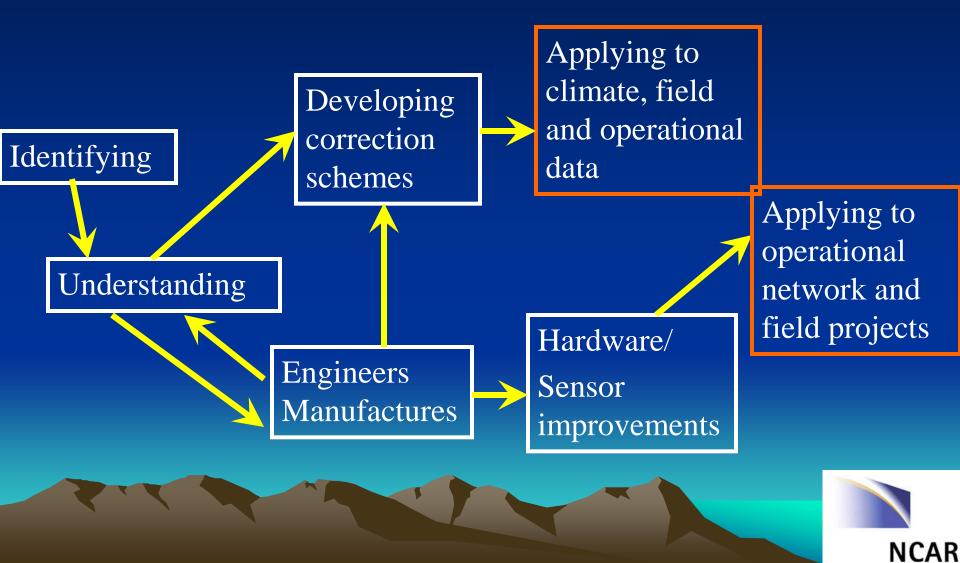
Comparison of GPS- and radiosonde-PW at 102 stations



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Generic Approach for Studying Sounding Characteristics, Biases and Impacts



Summary

- > Temperature: multi-thermistor or better radiation corrections
- **Water vapor:** TDL, dew/frost-point hygrometer, Polymer
- Pressure/height: any or no pressure sensor
- GPS wind: any (cost and size)
- Other variables: ozone and what else?
- Integration: sensor module design, transmitter, mobility, portability ...

"Reference": best sensors, extraordinary procedures, calibration, inter-comparisons, real-time data quality monitoring, effective communications ...

"Long-term stability": best quality, consistence, metadata, data QC and analysis, redundancy ...

