

Suggestions for potential ground based observing systems to be used in GRUAN operations.

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Upper Air Development, Met Office

Next Generation Upper-Air Network

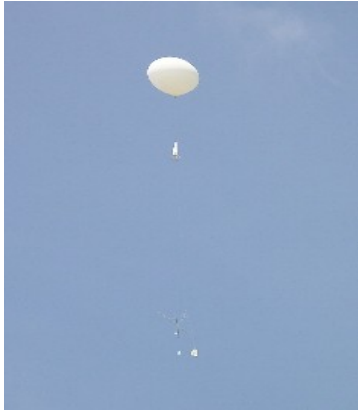
- ‘Large-scale’ project to produce costed options for the future (2010 – 2020)
- Benefits
- Optimize current network with surface and weather radar
- Meet User Requirements. (i.e. Higher spatial and temporal resolution)
- Reduce costs or deliver more for similar cost



**FUND – Future Upper-air Network Development +
COST Action ES0702: European Ground-Based
Observations of Essential Variables for Climate and
Operational Meteorology (EG-CLIMET)**



Camborne – Demonstration ‘Test’ Site.





Ground based remote sensing

- Provides higher temporal resolution than is feasible with radiosondes, but height coverage, stability and vertical resolution may be much lower than ideally required. However can indicate nature of errors /changes in radiosonde performance. Can provide evidence on representativeness errors of radiosondes.
- Wind profilers come closest to similar accuracy to radiosondes, but vertical resolution in stated GCOS user requirements seems extremely high compared to any operational use, although can be delivered by GPS radiosondes. Why???
- Satisfactory cloud measurements require use of laser ceilometers and cloud radars in addition to radiometers
- Useful surface based remote sensing of the upper troposphere and tropopause is only possible through VHF wind profilers and higher powered lidars, which may not be suitable for widespread use at the moment.

Basic variables in the troposphere



- 1 in operational use,
- 2 long term scientific deployments
- 3 Short term deployments

Temperature profile	Height range	Vertical resolution	Accuracy	Stability	Limitations
Microwave Radiometer ²	0-5 Km?	At 1 km About 500m	0.5 K?	1 K?	Not in moderate or heavy rain
Infrared Spectrometer ²	0-5 Km?	At 1 km probably similar to microwave	0.3 K ?	0.3K?	Cannot see through cloud.

Will have different day-night characteristics to radiosondes.

Basic variables in the troposphere



- 1 in operational use,
- 2 long term scientific deployments
- 3 Short term deployments

Water vapour profile	Height range	Vertical resolution	Accuracy	Stability	Limitations
Microwave Radiometer ²	0-5 Km?	At 1 km About 750m	About 6 per cent	?	Not in moderate or heavy rain
Infrared Spectrometer ²	0-5 Km?	At 1 km probably slightly better than microwave	?	?	Cannot see through cloud.

Will have different day-night characteristics to radiosondes.
GPS Integrated water vapour can be used to verify absolute accuracy.



Basic variables in the troposphere

- 1 in operational use,
- 2 long term scientific deployments
- 3 Short term deployments

Wind profile	Height range	Vertical resolution	Accuracy	Stability	Limitations
Wind profiler ¹	0-5 Km [UHF] 1-16 km [VHF]	100 m in PBL To 500 m at upper levels	Better than 1 ms ⁻¹ in each component	?	Operational Monitoring Needs improving Birds, ground clutter, interference
Optical doppler lidar ²	0-3 Km?	50 m	?	?	Cannot see through cloud.



Basic variables in the troposphere

- 1 in operational use,
- 2 long term scientific deployments
- 3 Short term deployments

Cloud profile	Height range	Vertical resolution	Accuracy	Stability	Limitations
Laser ceilometer ¹	0-12?? Km depends on specification]	10 to??m	Cloud base Heights similar to vertical resolution	?	Good for cloud base, but limited when low cloud present
Cloud radar ²	0-12 Km?	15 m to 100m	Cloud top will be poorer than vertical resolution	?	Can see through cloud, but is sensitive to small cloud drops



Variables not discussed here

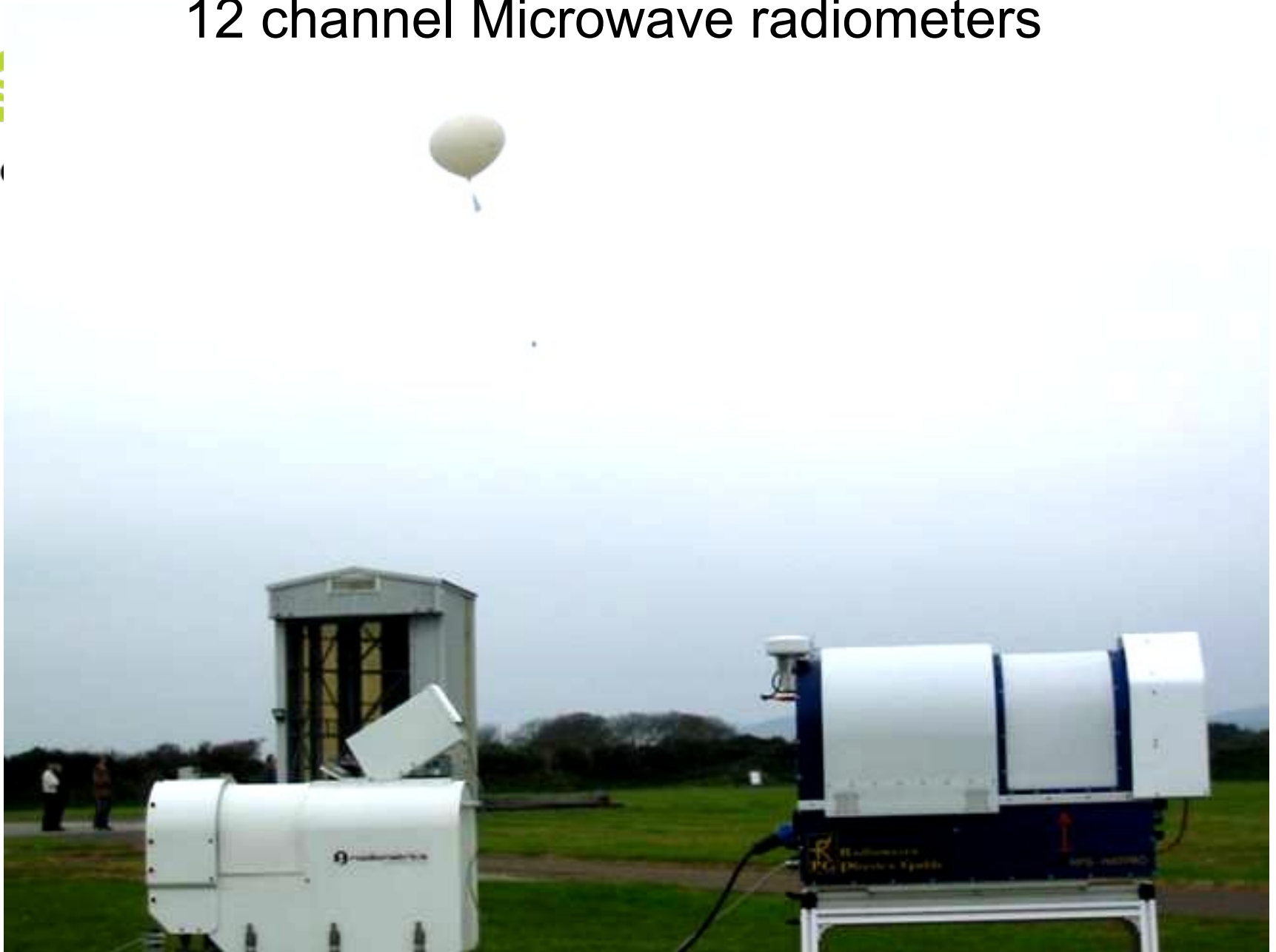
- Radiation... see BSRN presentation
- Ozone, carbon dioxide, Methane... see GAW
- Lower stratosphere water vapour needs specialised instrumentation not yet available in near operational state
- Aerosol - sun photometers, etc



Instrumentation considered [can be purchased through commercial tender]

- Microwave radiometer
- Infrared spectrometer
- GPS water vapour
- Wind profiler, UHF
- Optical doppler lidar
- Laser ceilometer
- Cloud radar

12 channel Microwave radiometers



Radiometer Physics HATPRO

Humidity And Temperature PROfiler

- Filter bank Design – Fast!
- 22-29 GHz – humidity/cloud
- 51-58 GHz – temperature
- Beamwidth: 3.5° at 22 GHz
- Noise: 0.3-0.4 K for $\tau=1.0$ s
- Absolute system stability: 1.0K
- Thermal stability: < 0.02 K
- Rain sensor and shutter (including a dew-blower)
- Pressure, humidity, temperature sensors
- IR-radiometer



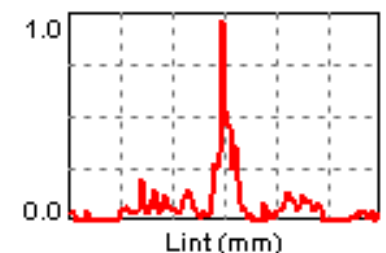
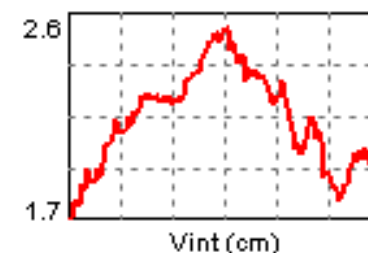
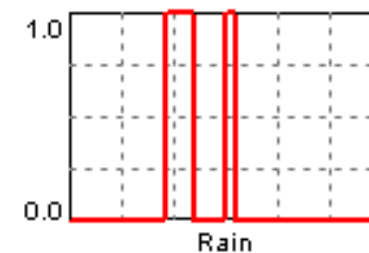
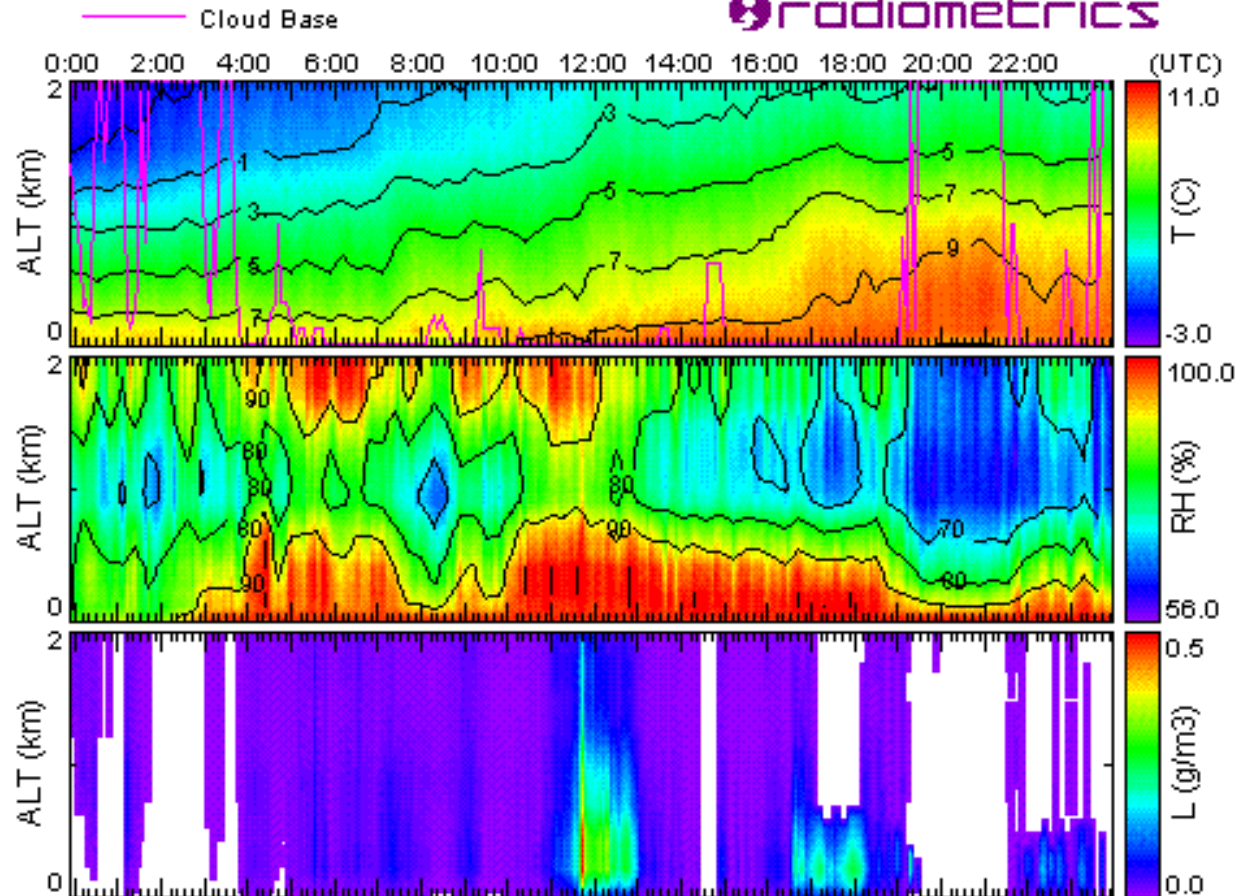
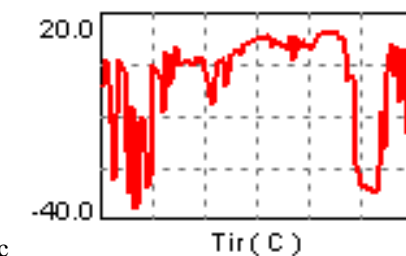
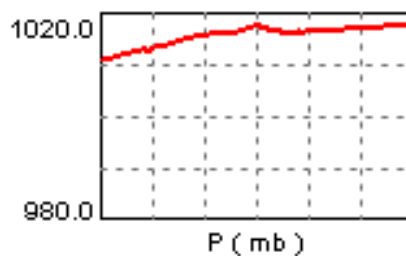
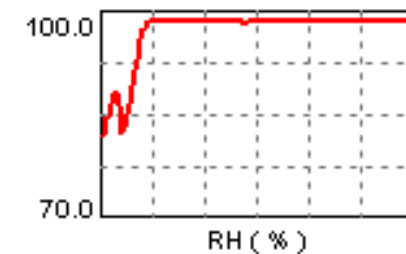
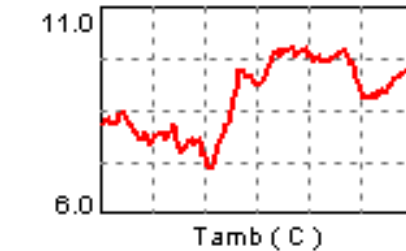


Microwave radiometer output received at Exeter

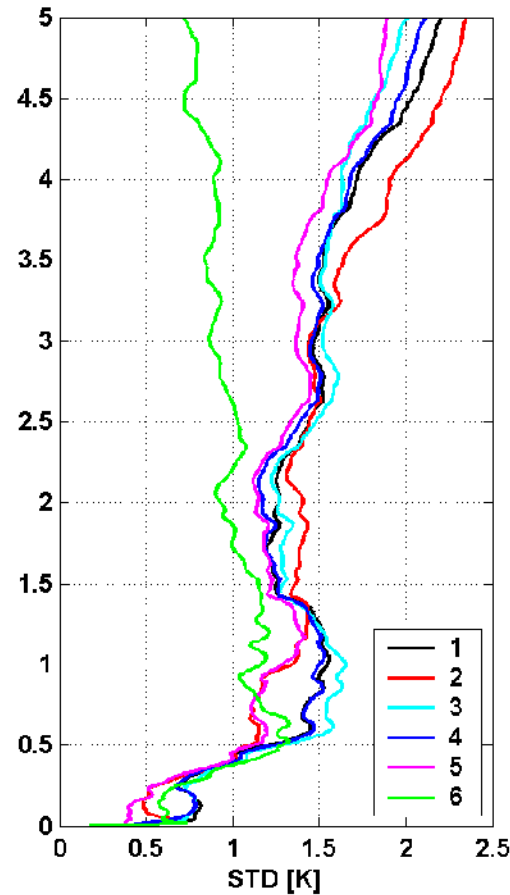
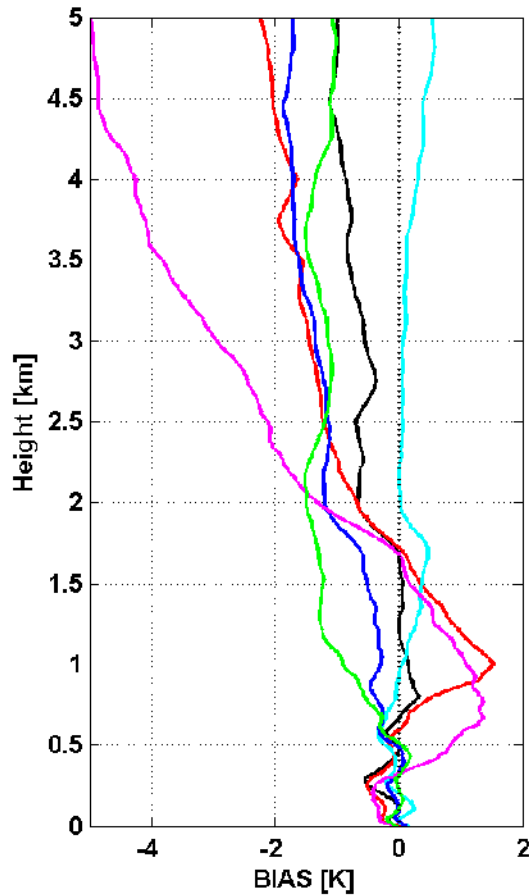
Met (

From: 23:52:33 01/21/08
To: 23:52:33 01/22/08

radiometrics



Statistics of Temperature Profiles

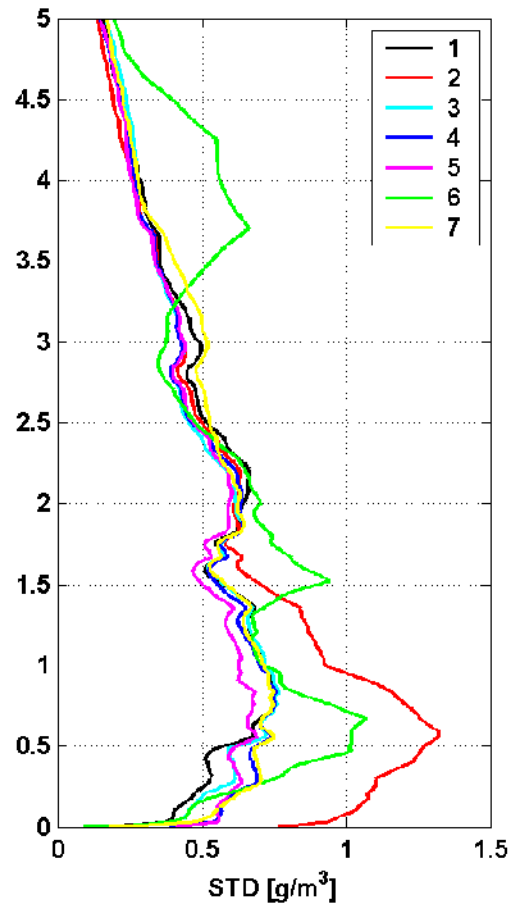
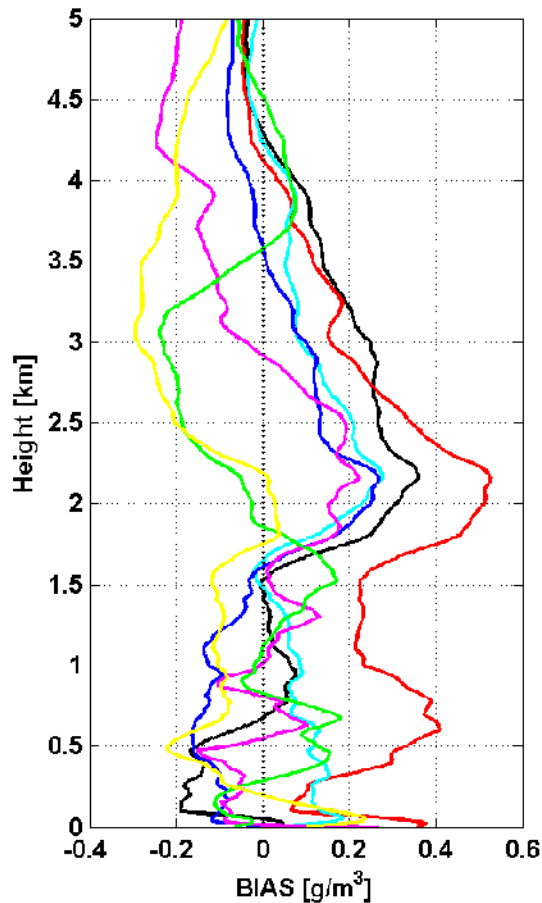


Retrieval accuracy for:

- 1) NN
- 2) NNelev
- 3) M-REG
- 4) S-REG
- 5) S-REGelev
- 6) 1D-VAR

Left: Temperature Bias
Right: Temperature StDev

Statistics of Humidity Profiles



Retrieval accuracy for:

- 1) NN
- 2) NNelev
- 3) M-REG
- 4) S-REG
- 5) S-REGelev
- 6) 1D-VAR
- 7) OEM

Left: Vapour Density Bias
Right: Vap. Den. StDev

Compare 2 Radiometrics Profilers during LAUNCH

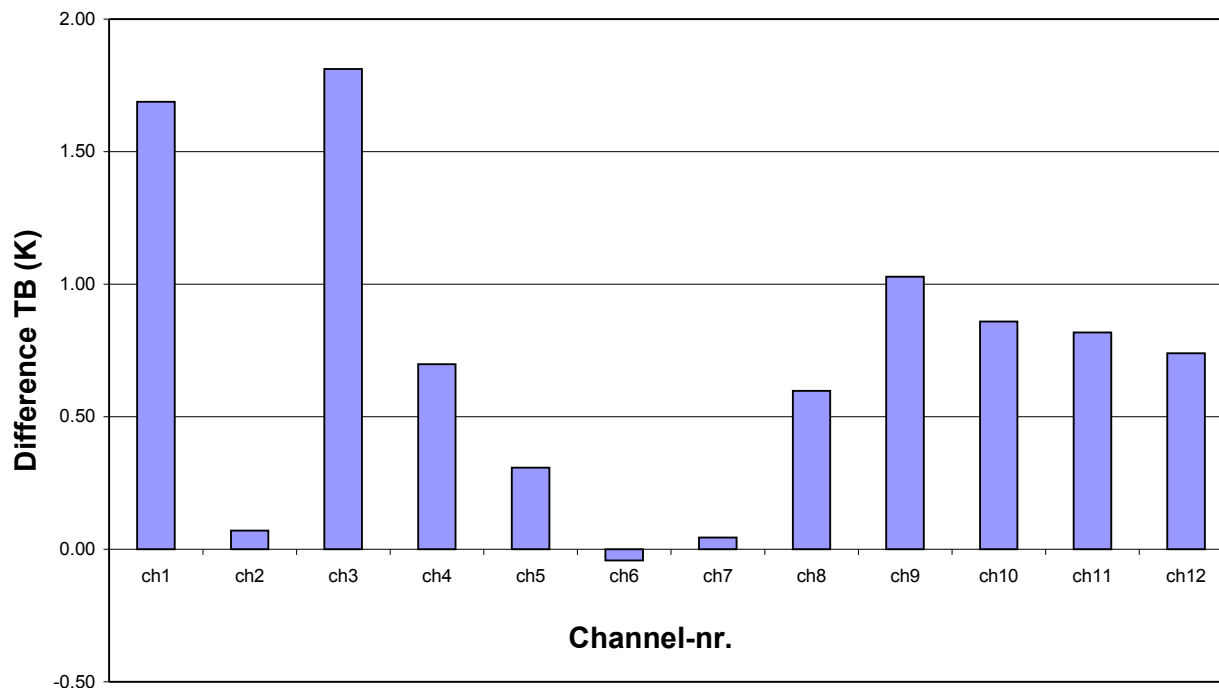
Mean value of TB difference MWP(DWD) - MWP(IMAA) (31.08.-07.09.2005)

IMAA TB prepared by F.Madonna, IMAA Potenza

Mean TB difference ~1.6 - 1.8 K at 22.23 GHz and 23.83 GHz

Mean TB difference < 1 K for other channels

Mean TB difference < 0.1 K at 23.03, 51.25 and 52.28 GHz



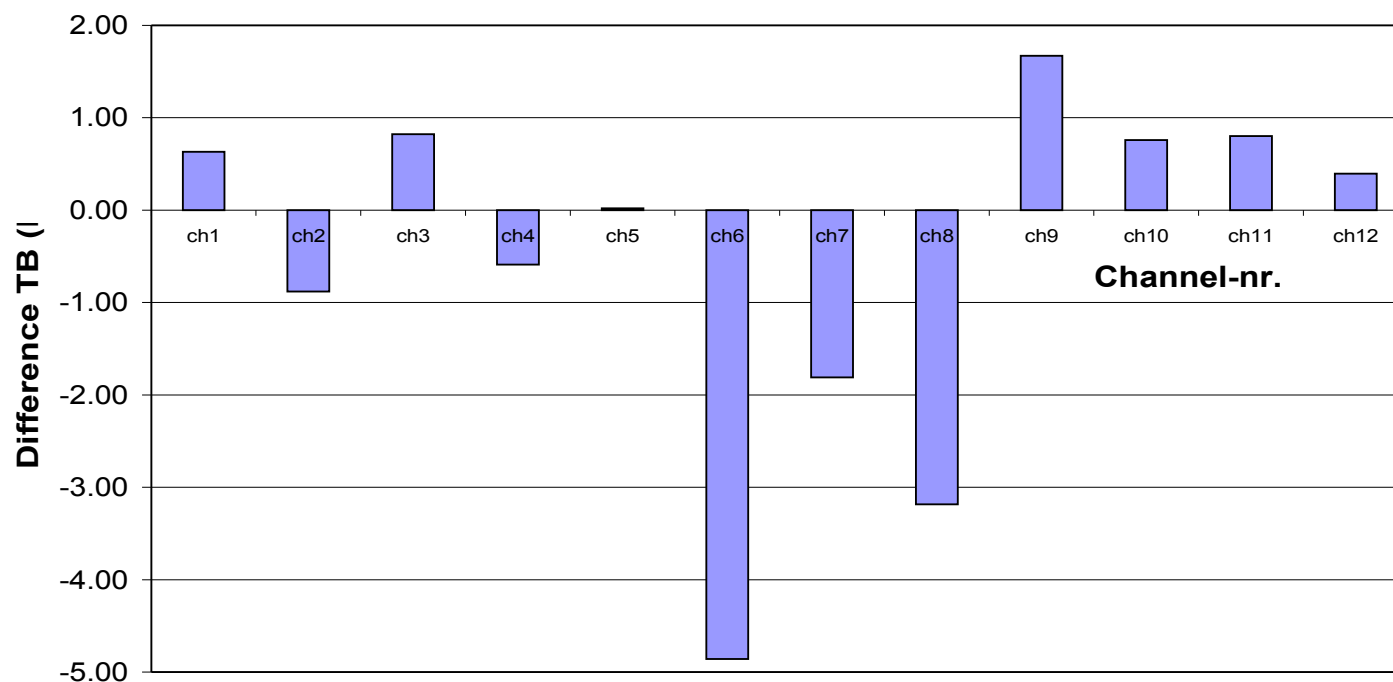
Compare Radiometrics and HATPRO during LAUNCH

Mean value of TB difference MWP(DWD) - HATPRO (18.10.-31.10.2005)

HATPRO TB provided by U.Löhnert, University Munich

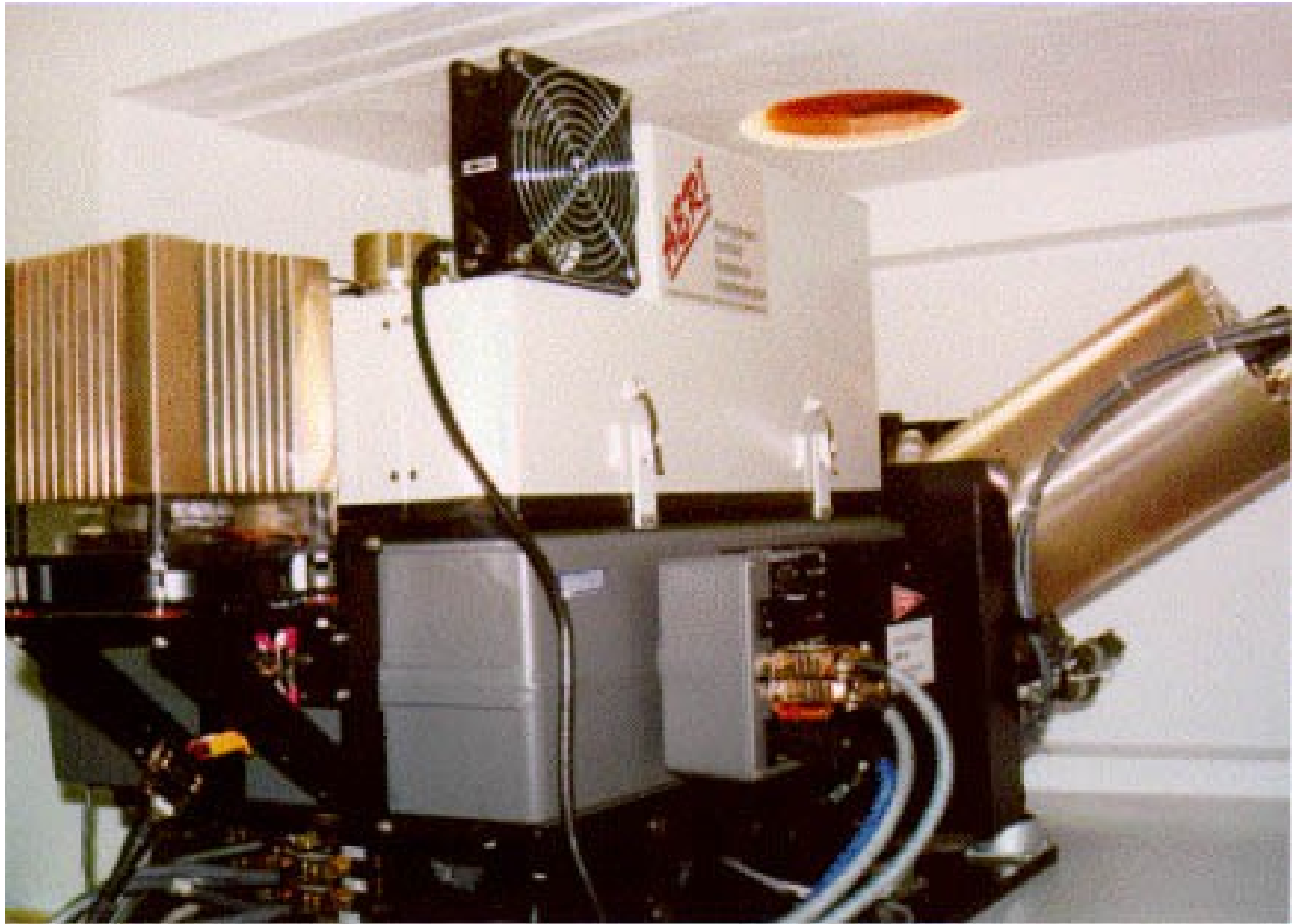
Abs Mean TB difference ~1.8 - 5 K for V band channels between 51 and 55 GHz

Abs Mean TB difference < 0.8 K for other channels



HATPRO TB
closer to newer
Radiometrics
Profiler at
 $\nu > 55\text{GHz}$

Atmospherically Emitted Radiance Interferometer (AERI)

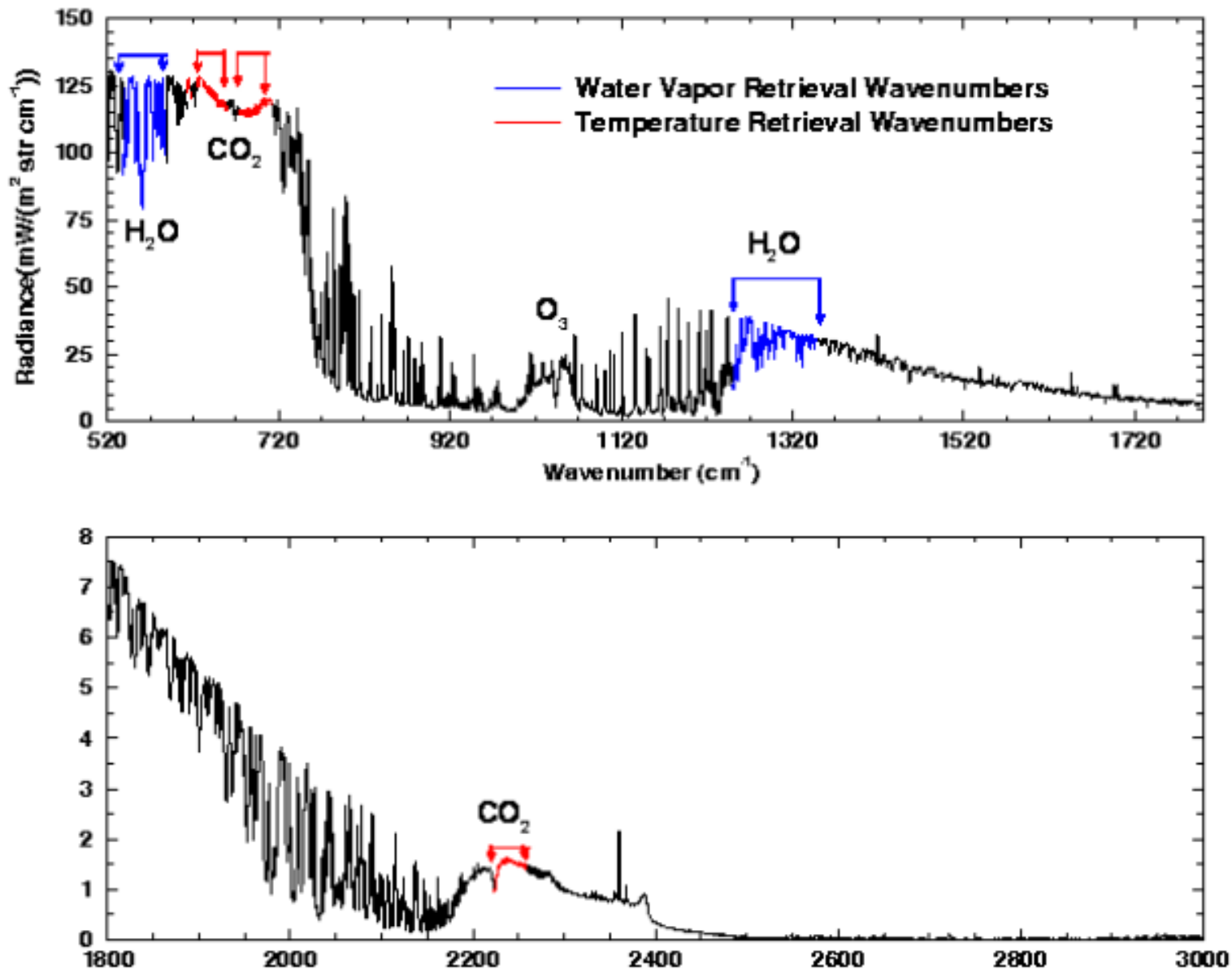


Atmospherically Emitted Radiance Interferometer (AERI)

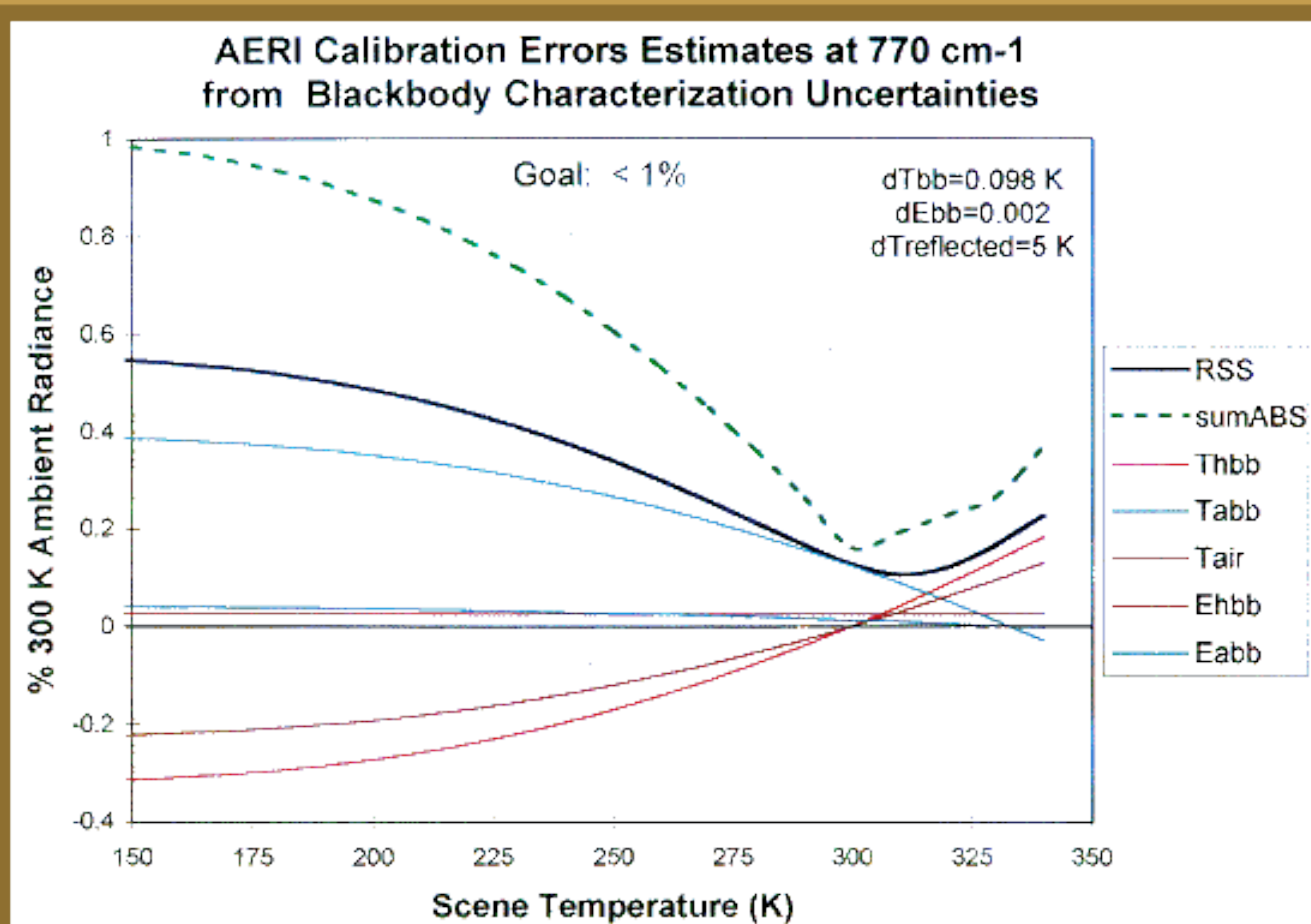




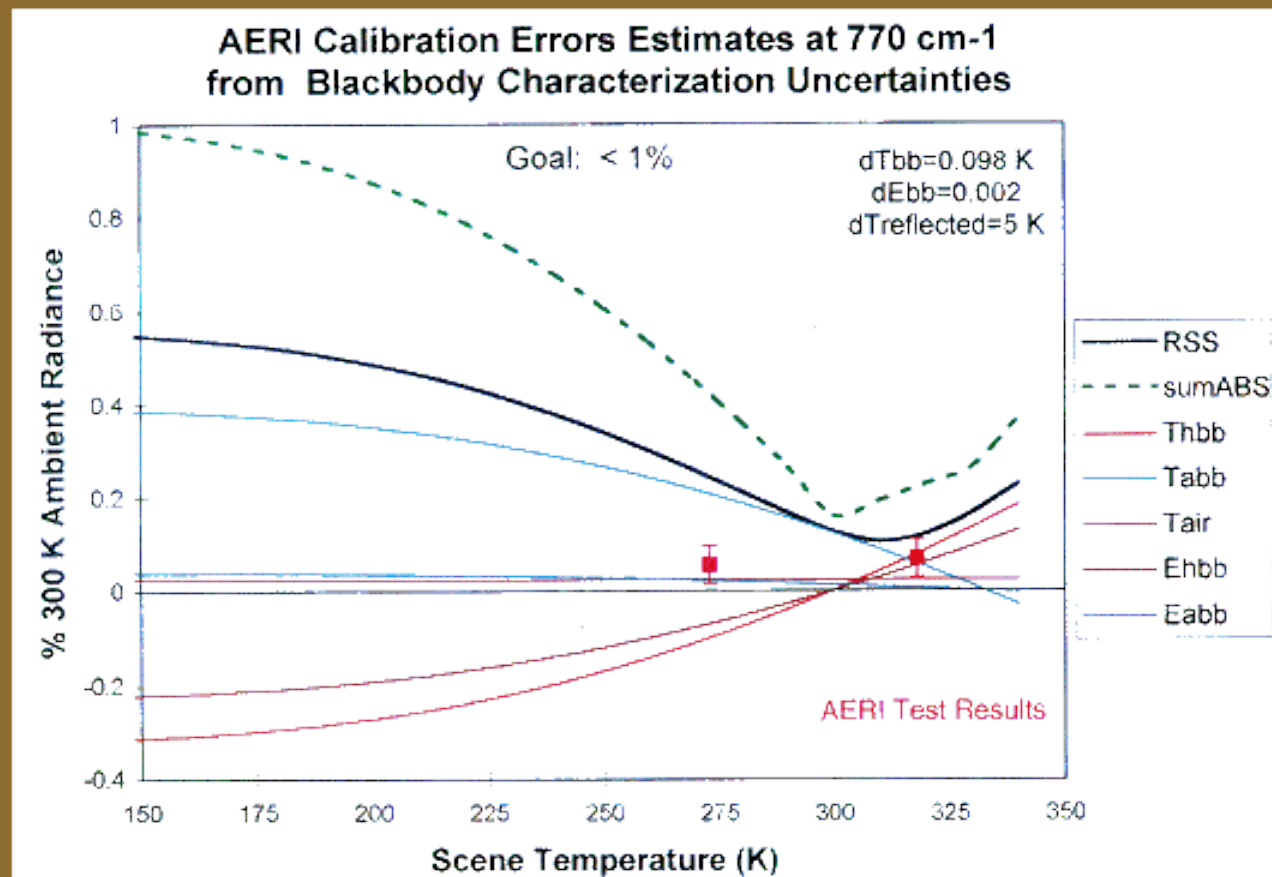
AERI Radiance Channel 1 and 2



AERI Calibration Error Estimates



Calibration Results Compared to Goals

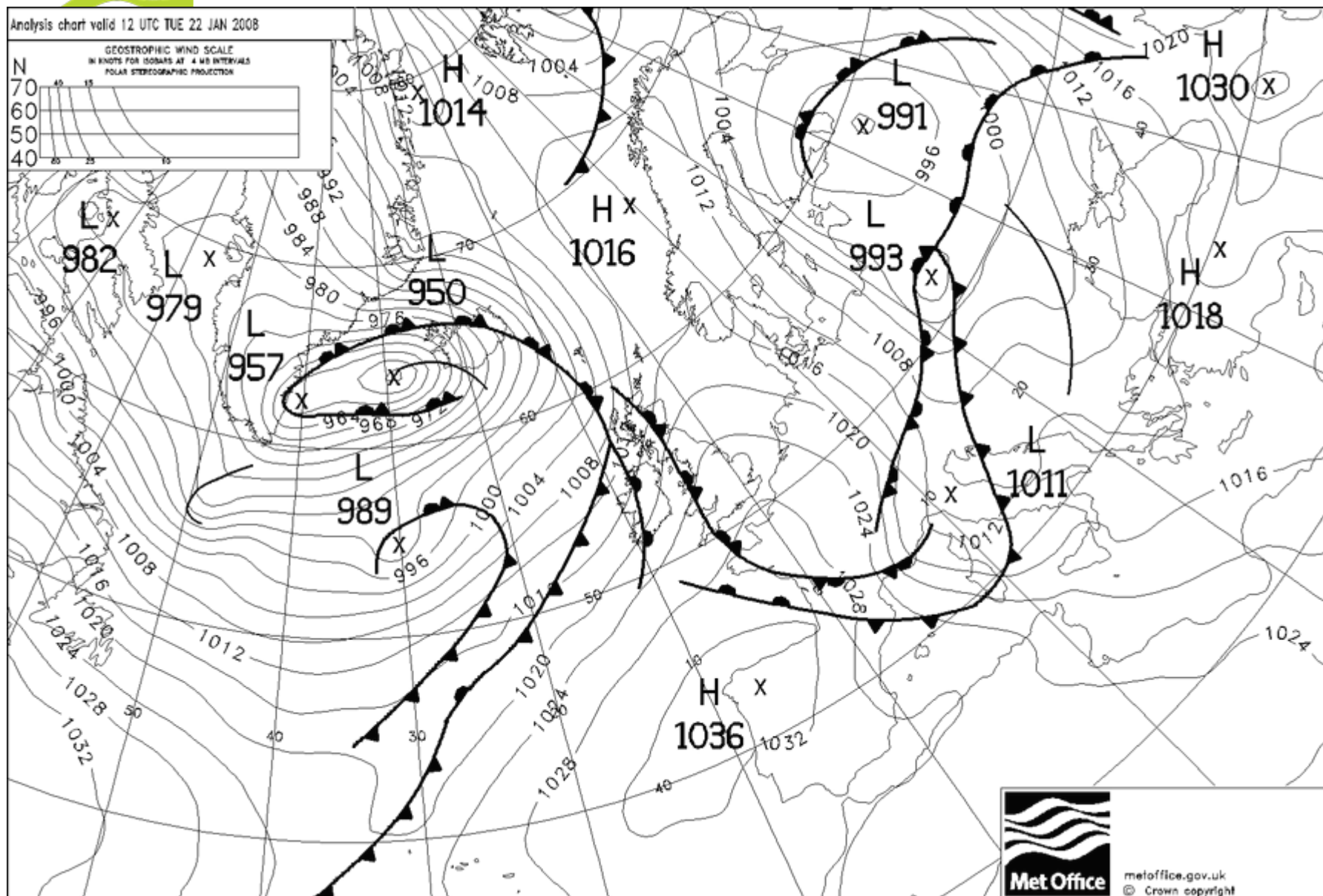
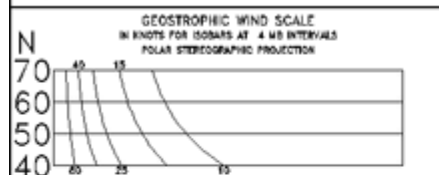




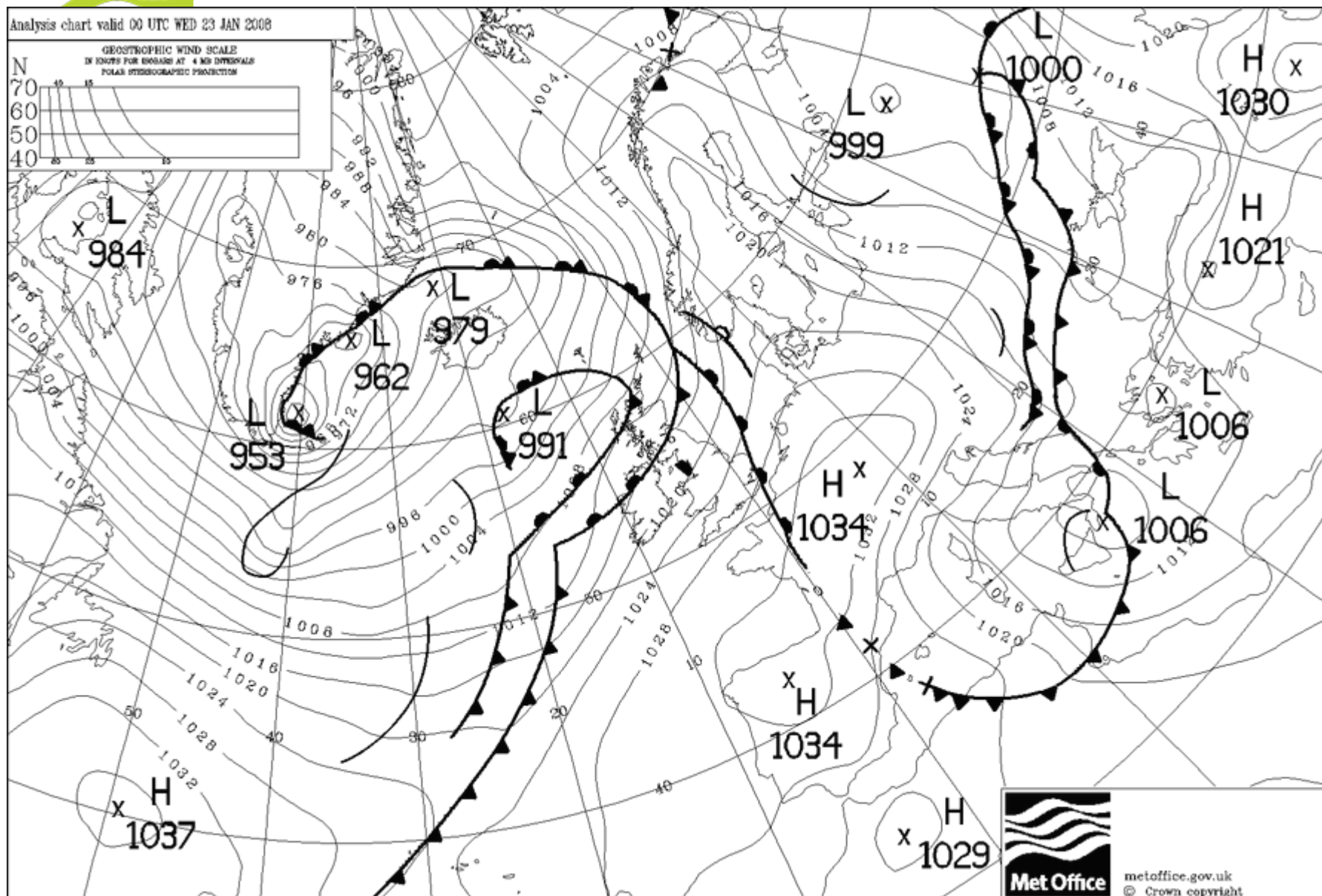
GPS water vapor



Analysis chart valid 12 UTC TUE 22 JAN 2008

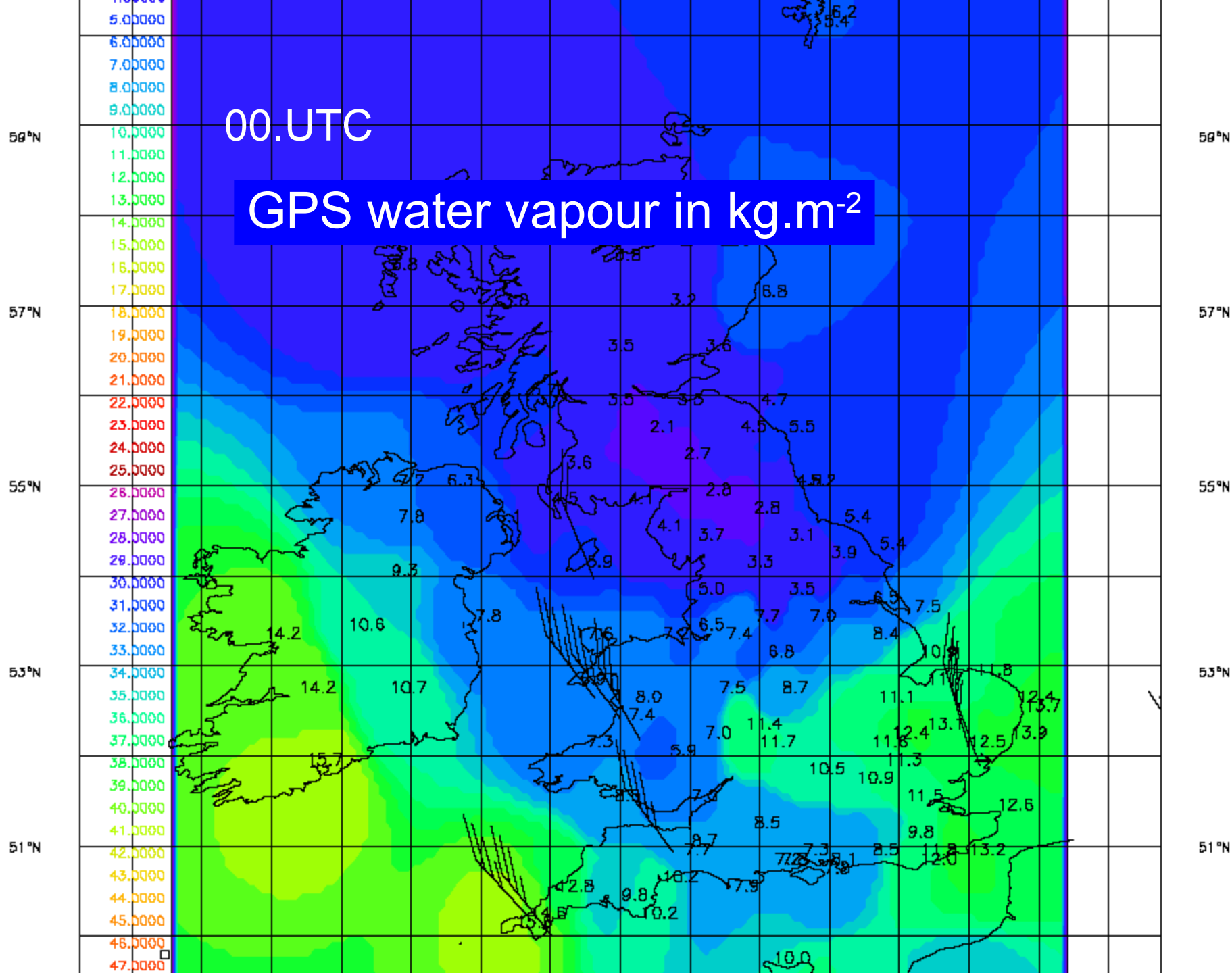


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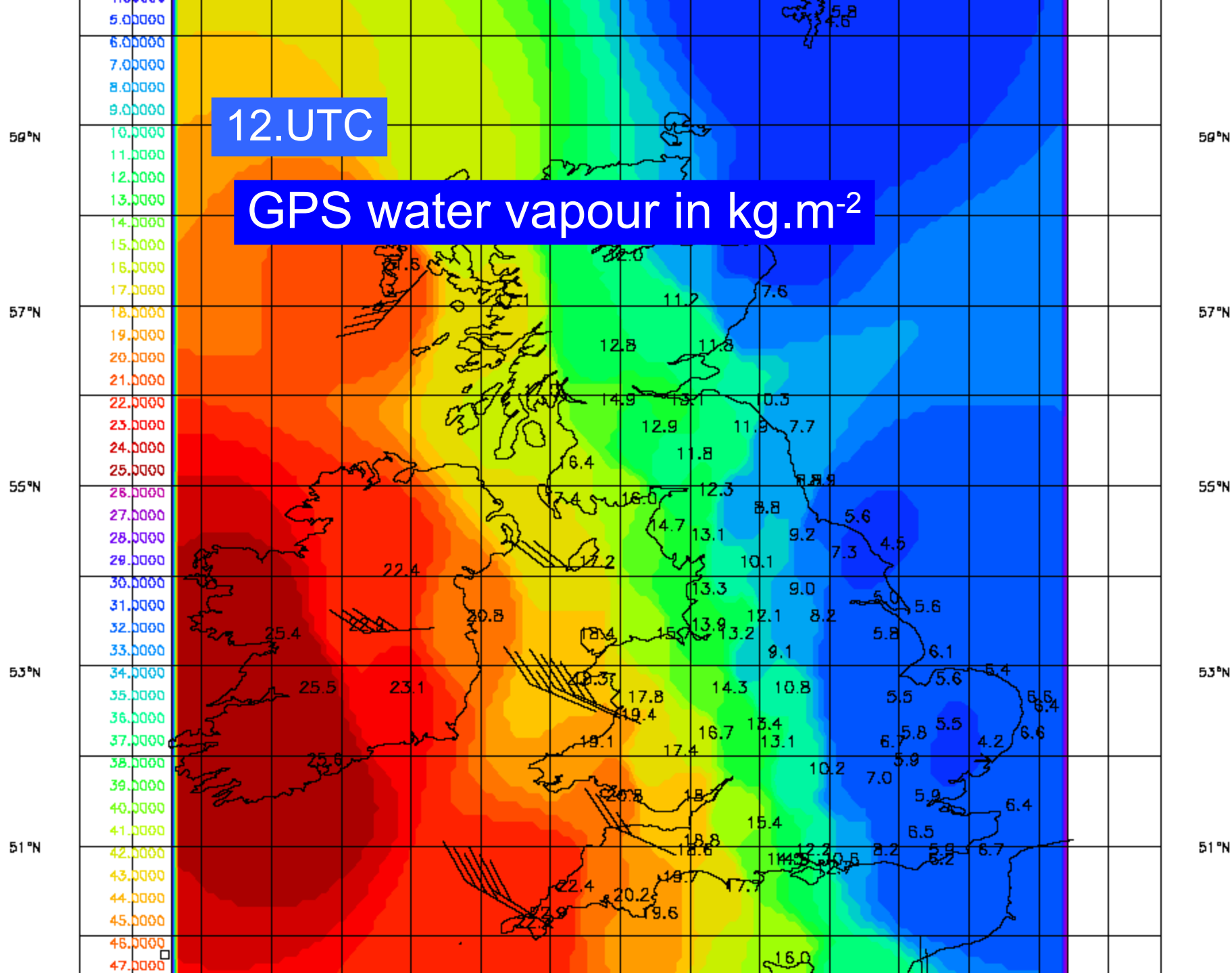
00.UTC

GPS water vapour in kg.m^{-2}



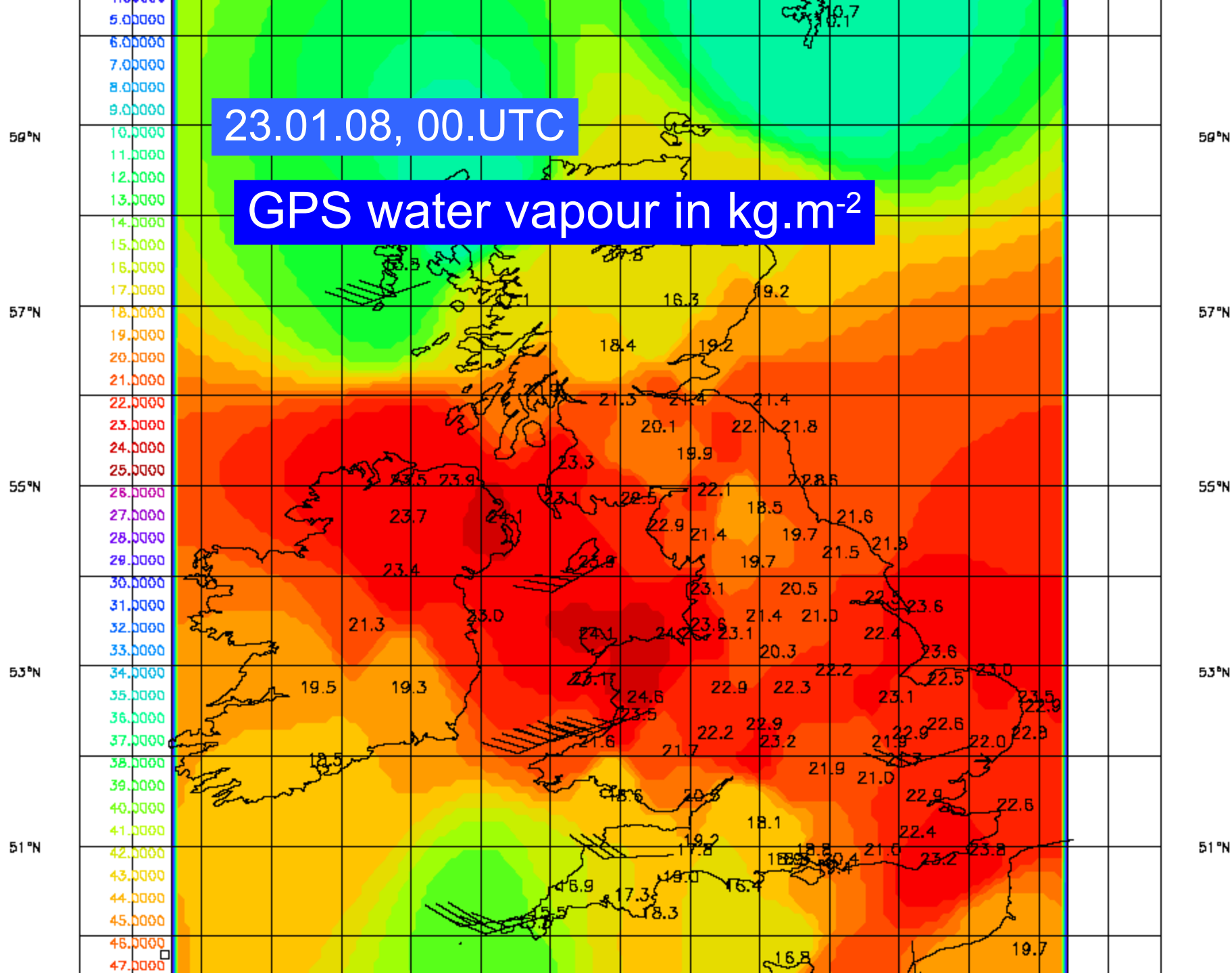
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GPS water vapour in kg.m^{-2}

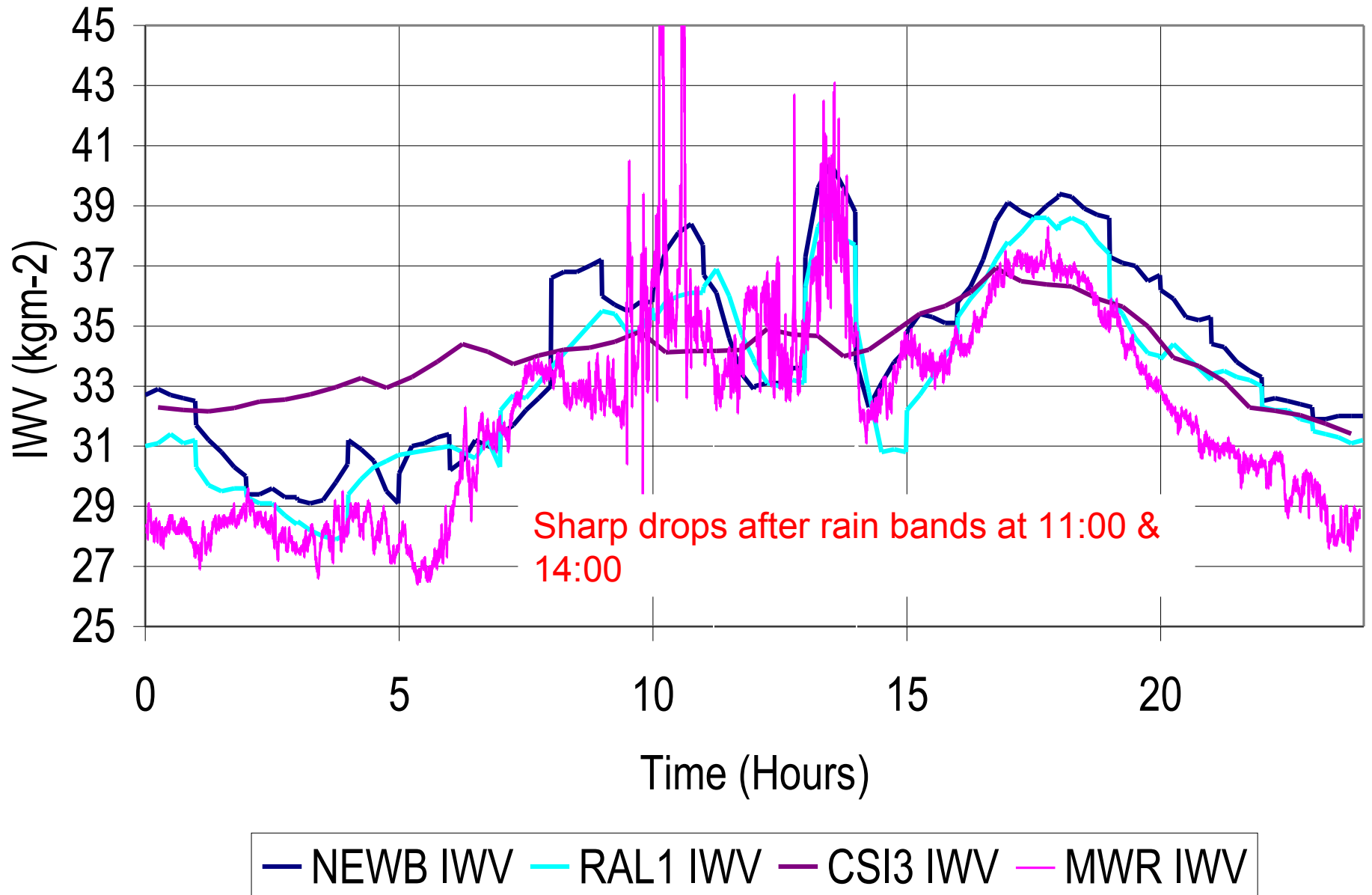


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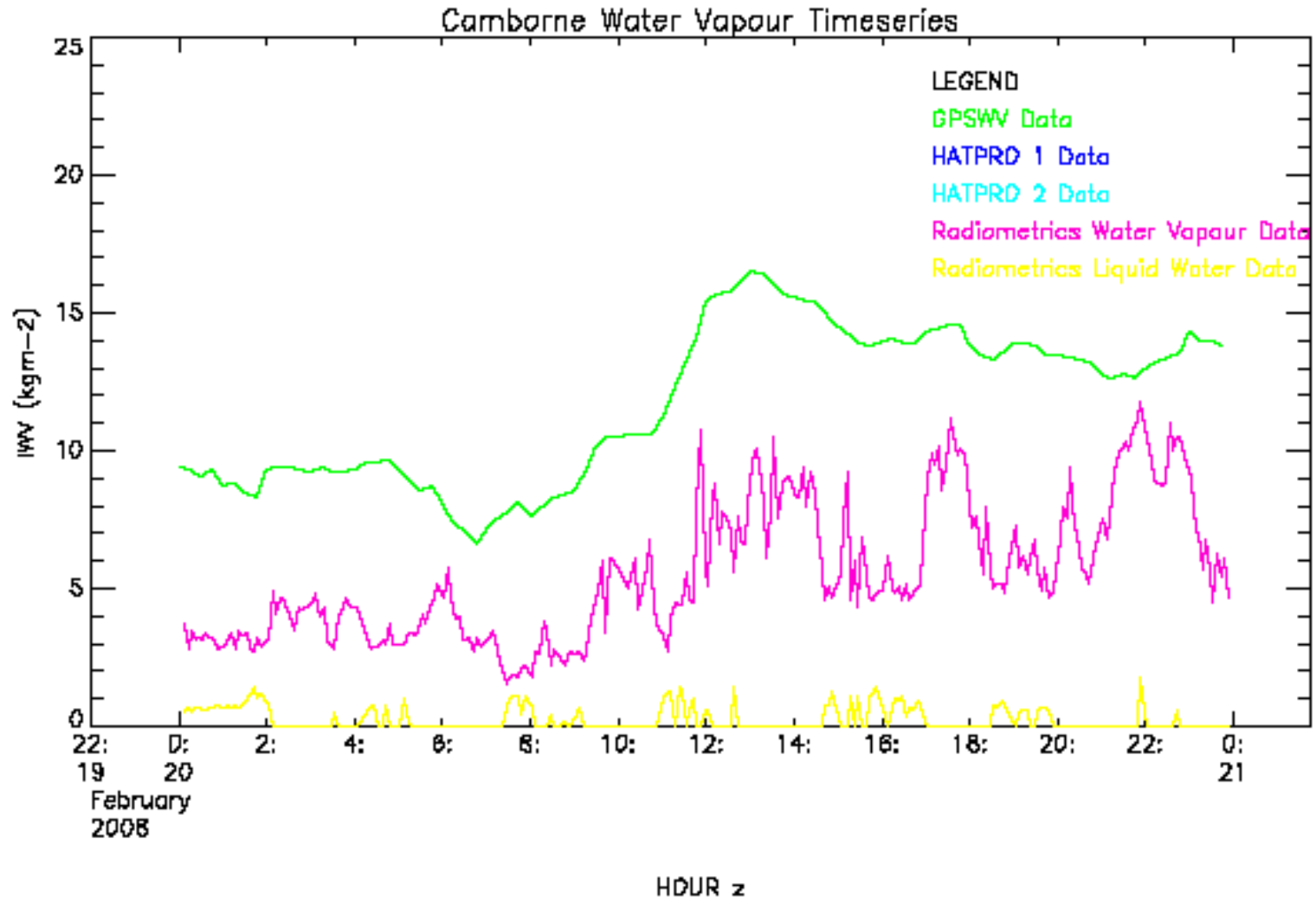
GPS water vapour in kg.m⁻²



IWV Comparison 240605

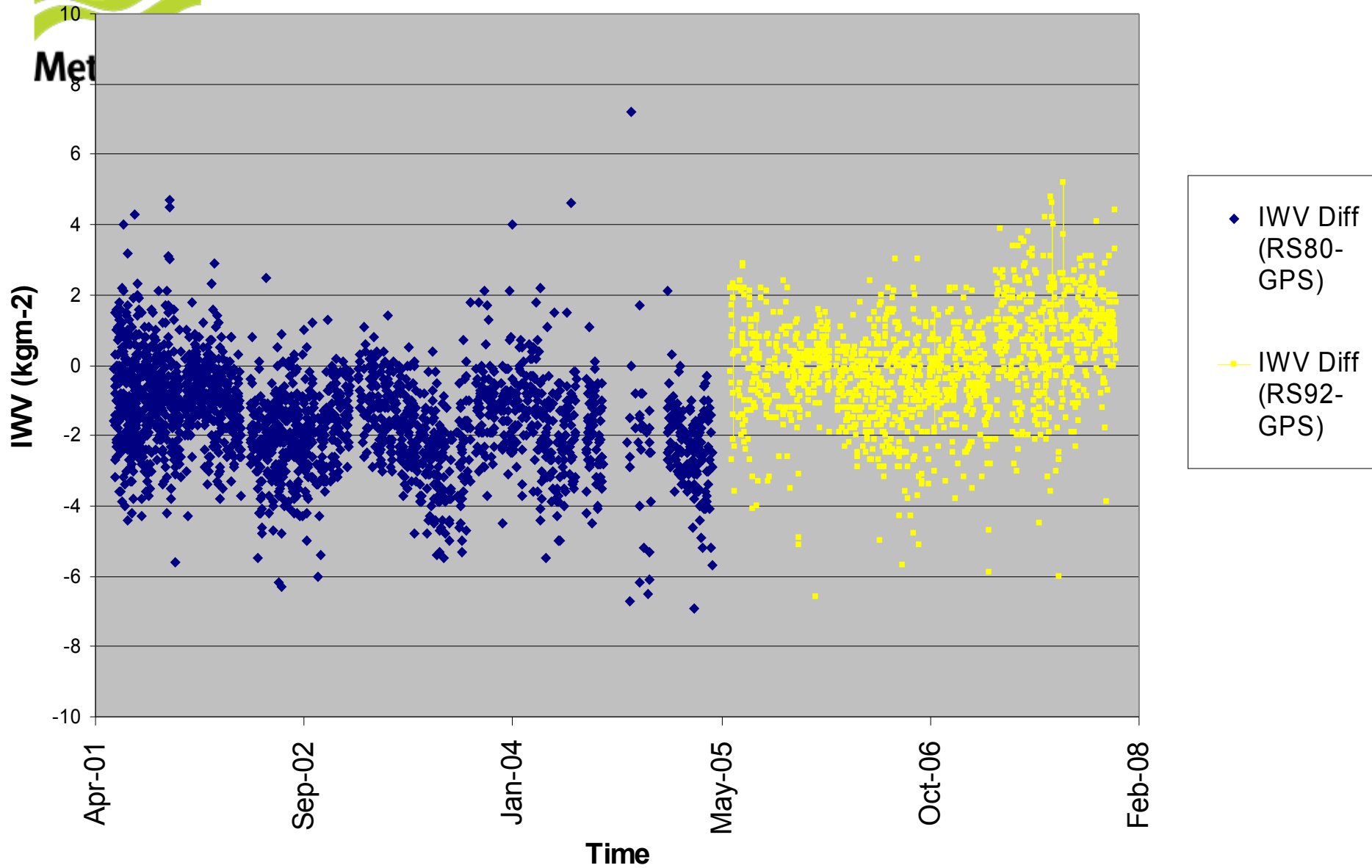


Recent FUND Plot GPS vs. MP3008 MWR

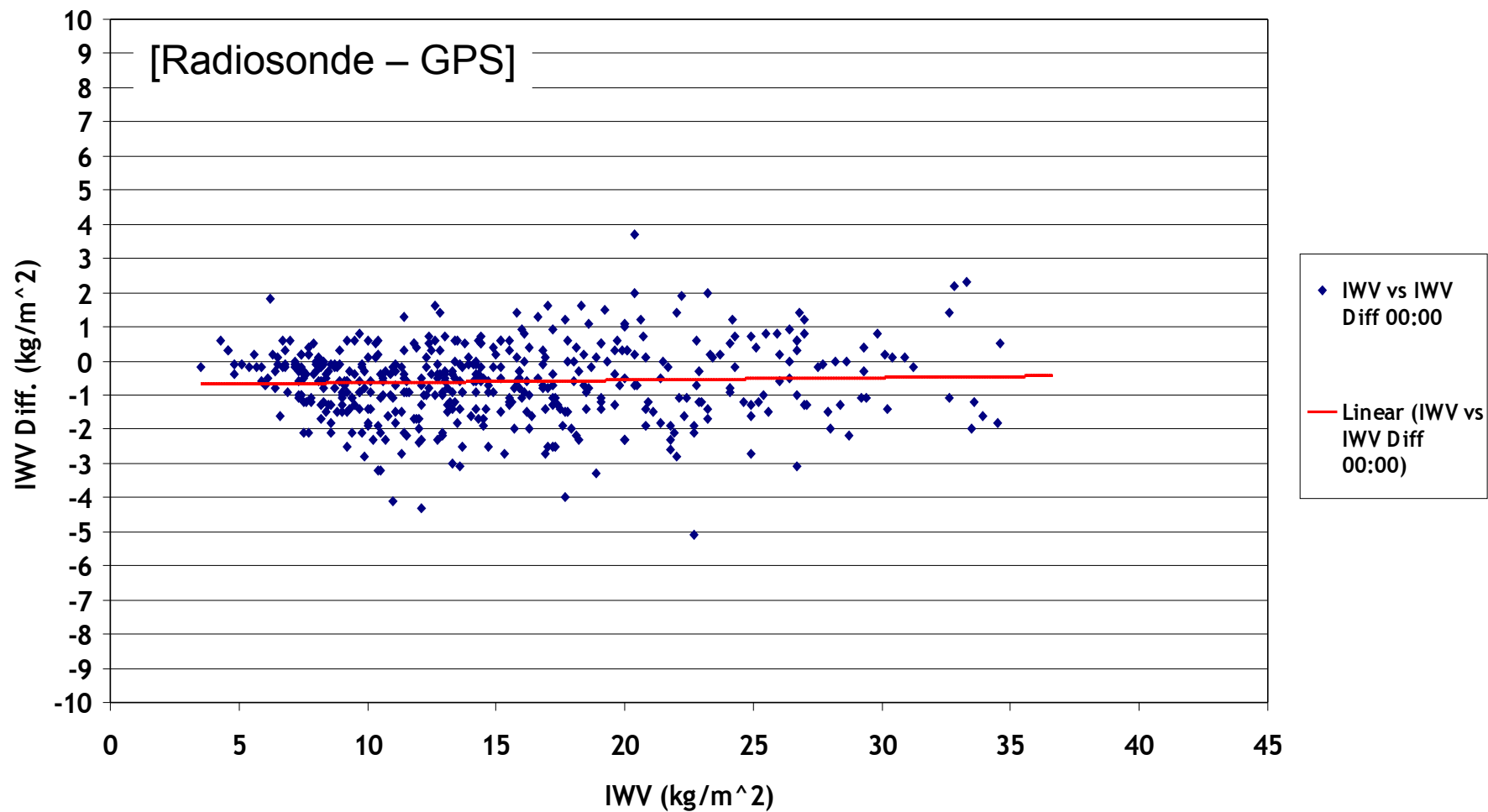




Long Term Trend of IWV Difference (RS-GPS) Trend of IWV at Camborne June 2001 - Dec 2007

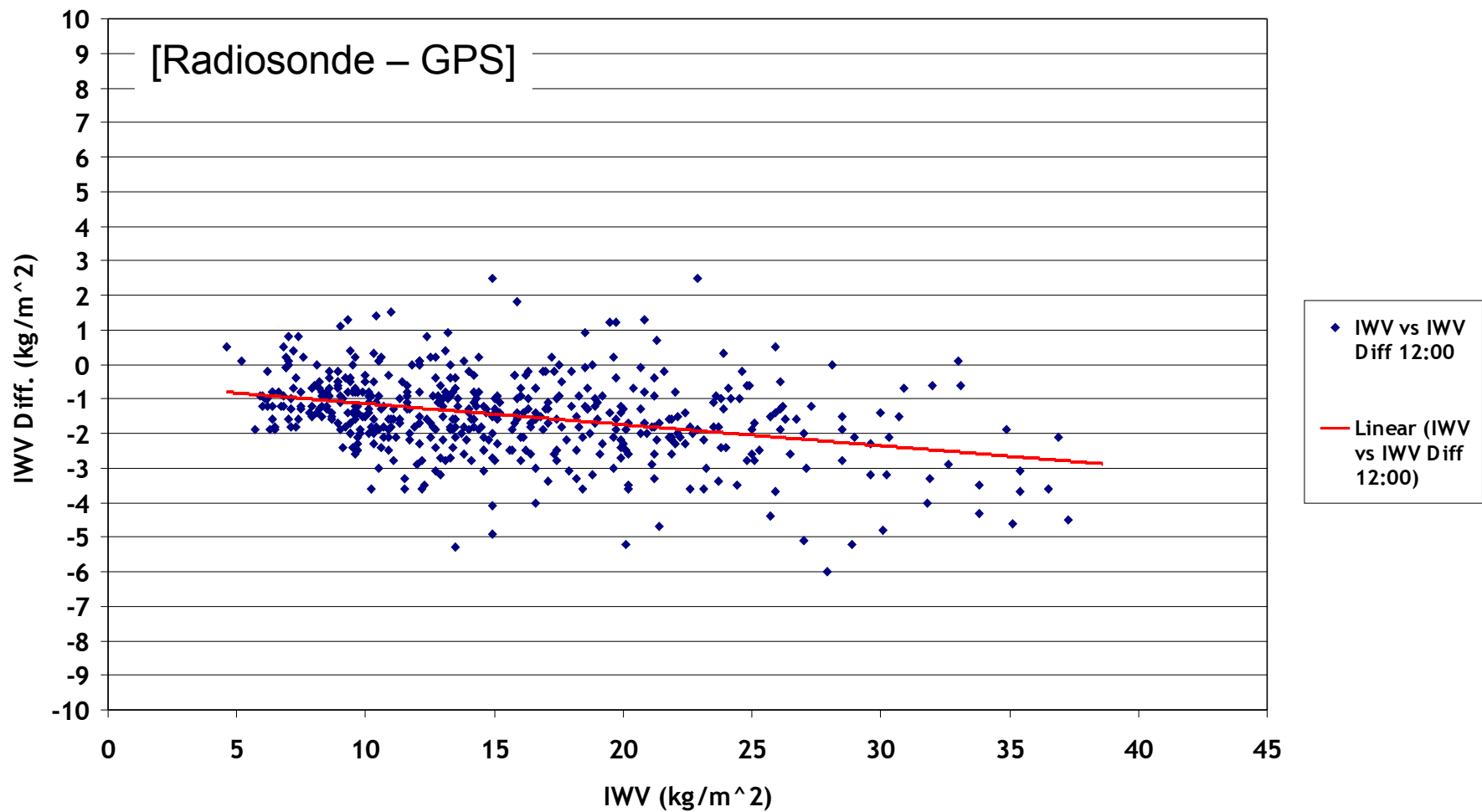


IWV vs IWV Difference (RS-GPS) CAM B, HERS + LERW Combined
00:00 Monthly Averages 2005





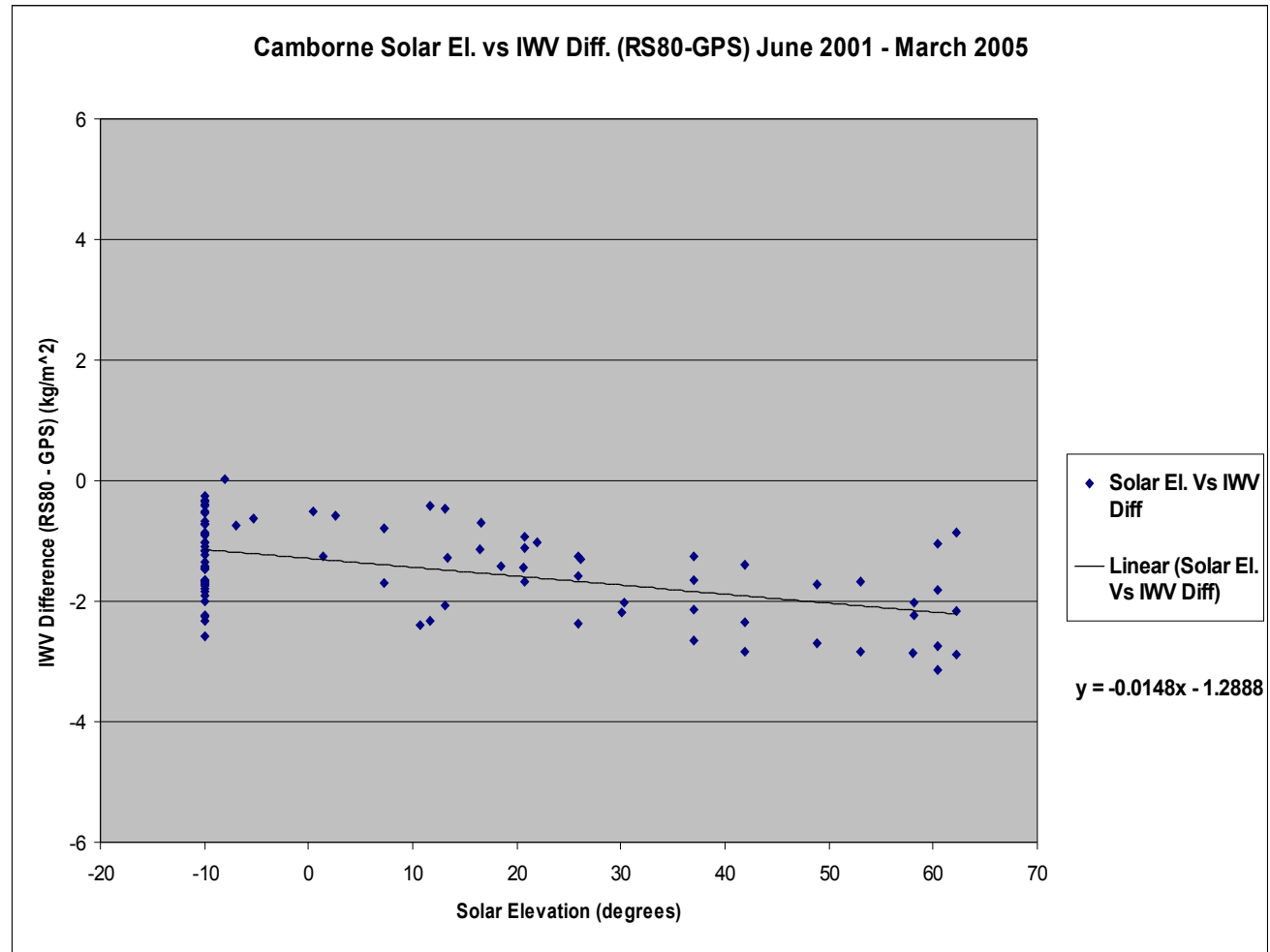
IWV vs IWV Difference (RS-GPS) CAM B, HERS + LERW Combined 12:00 Monthly Averages 2005



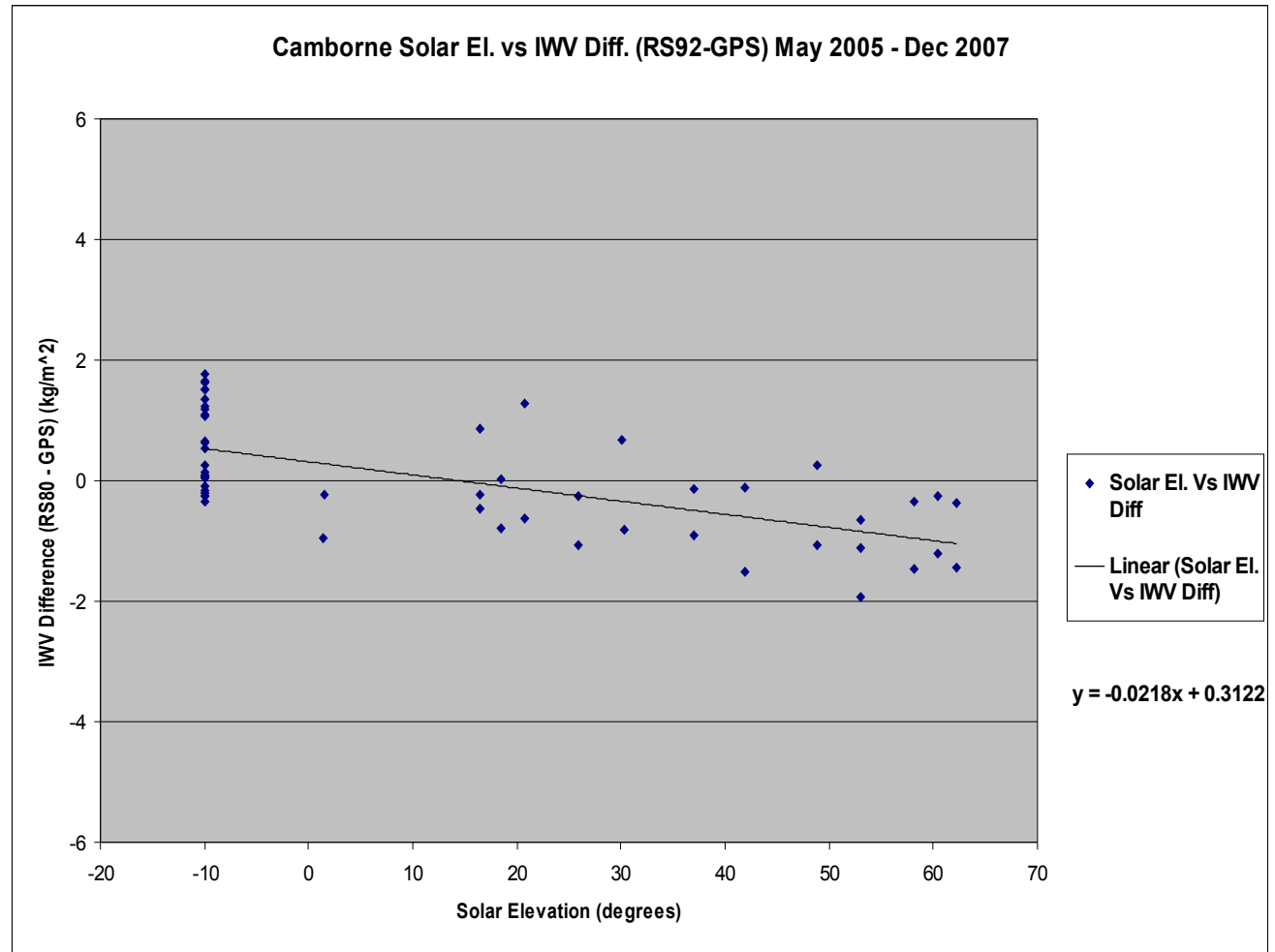
1200 w \times 0×4 \tilde{Q} ctas cloud cover $\Xi \mathbb{W} \oplus$ vs $\Xi \mathbb{W} \oplus \infty \times \blacktriangle \times \times \sim$ B 8 RS80-G + S^9 2003



Vaisala RS80 –GPS at Camborne



Vaisala RS92 –GPS at Camborne





Jenoptik Laser ceilometer

Start inf

Timeplot

State

Clouds

20080122_Camborne_CHM070044.nc

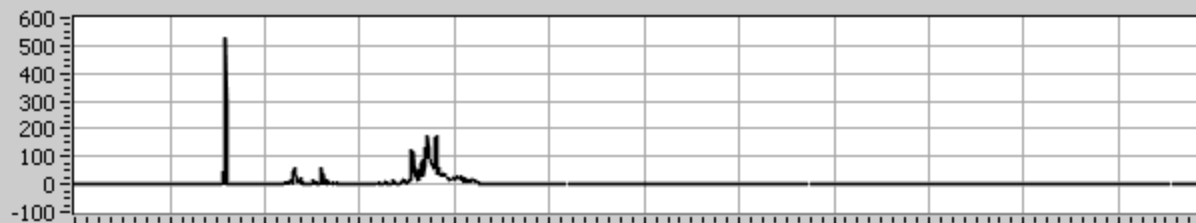
load

Save

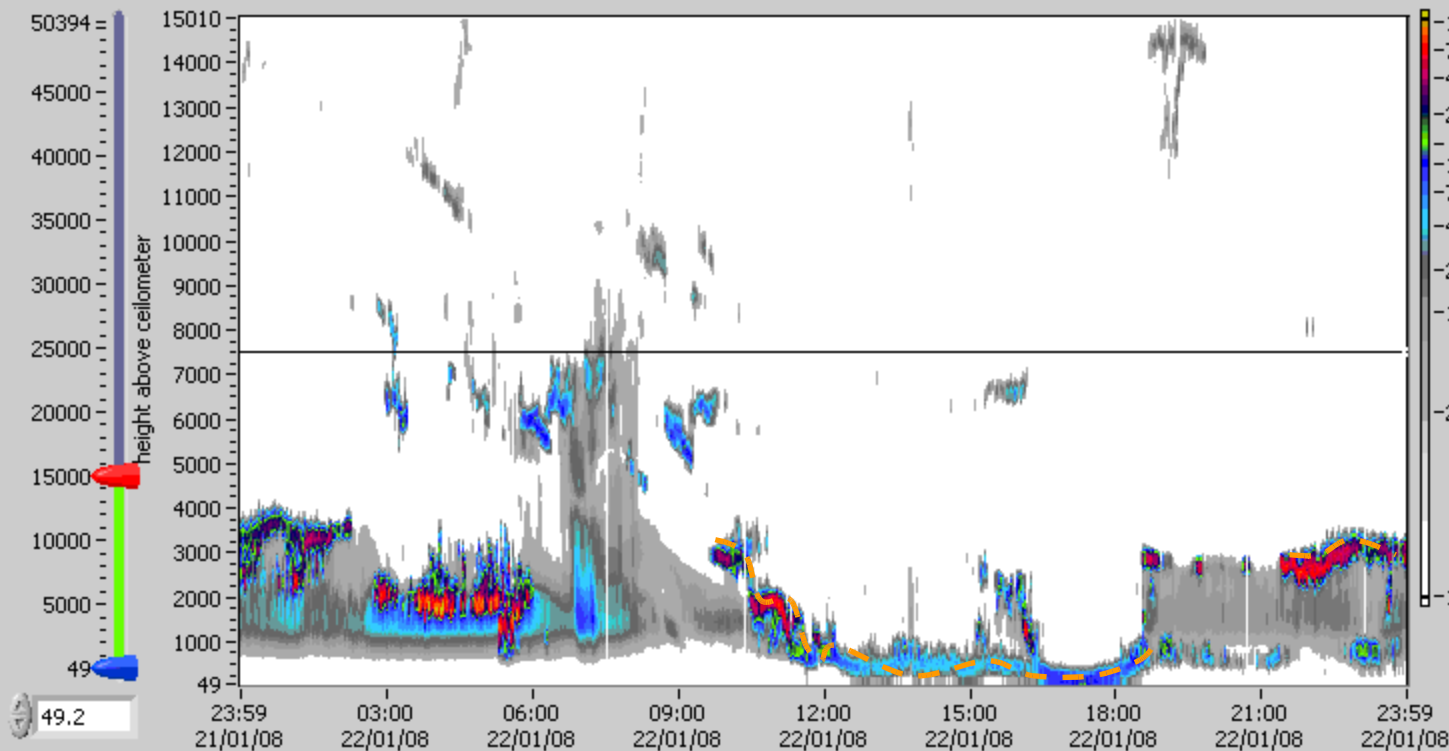
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Serial No.

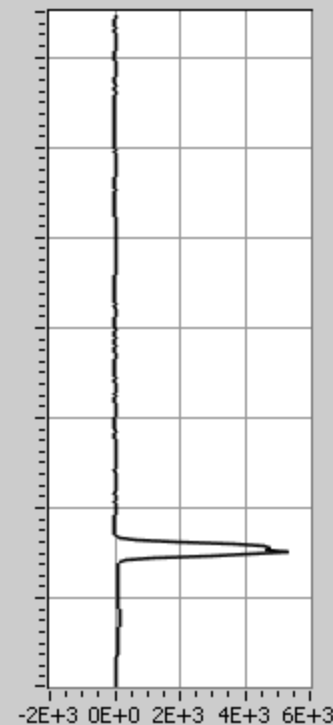
CHM070044



15009.6 ft



49.2



select profile

23:58:32

7529.53

-0.255374

Show Clouds : ☒ off

z-axis representation

P Pr² ln(Pr²)

delete noise

delete x sigma width

☒ 0.30 5

915 MHz wind profiler

Height {km}

6

4

2

5

10

15

20

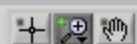
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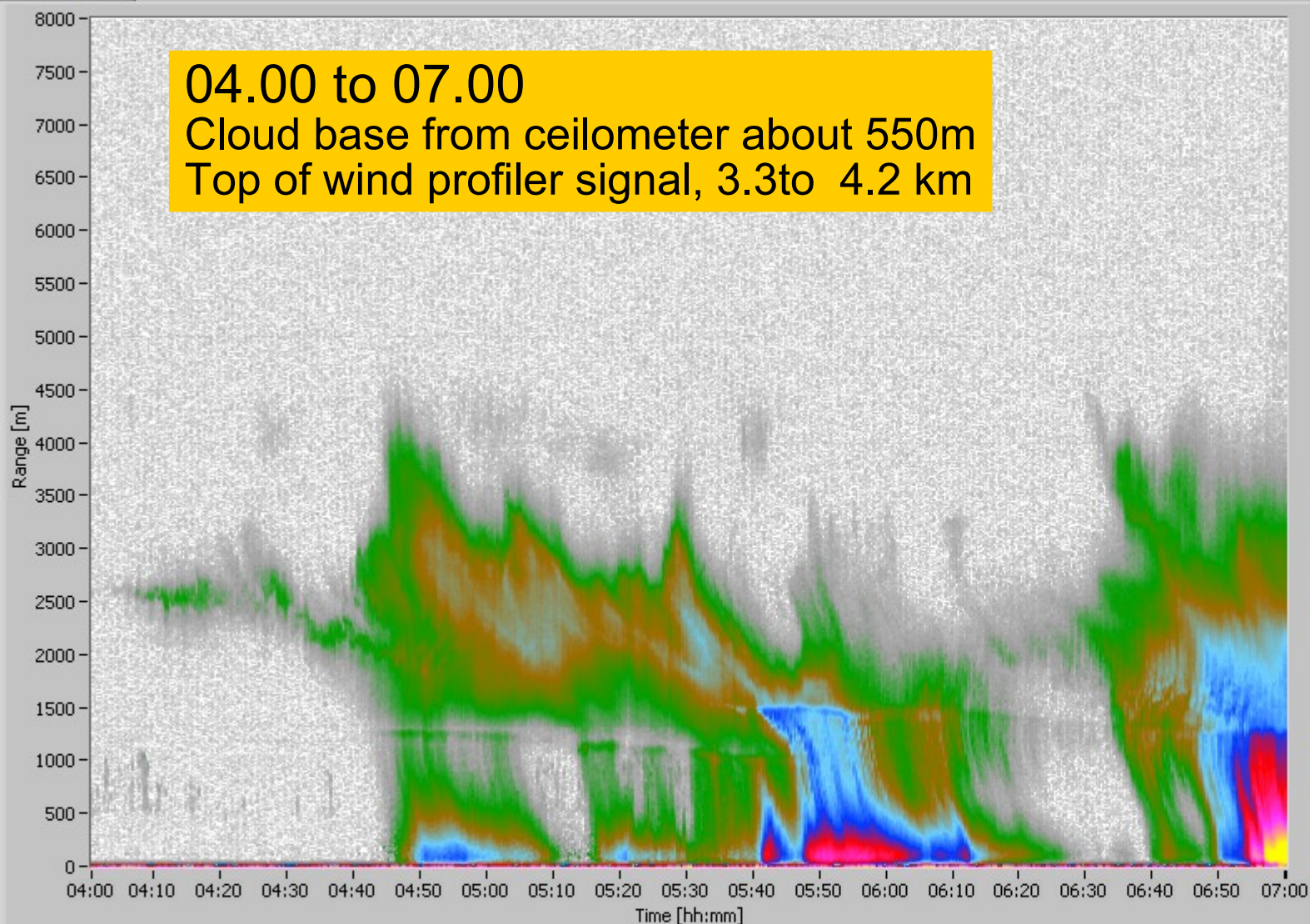
4

2

5



Last Scan



04.00 to 07.00

Cloud base from ceilometer about 550m

Top of wind profiler signal, 3.3to 4.2 km

Intensity [dBZ]

Range [m]

Time [hh:mm]
 Range [m]
 Intensity [dBZ]

Last Scan Time Stamp Peak [dBZ]
 2008/01/22 06:59:34 -35.6855

Data file D:\Camborne\ycr002_20080122_060734_mod.csv

Intensity [dBZ]
 Range [m]

Cursors:

Cursor

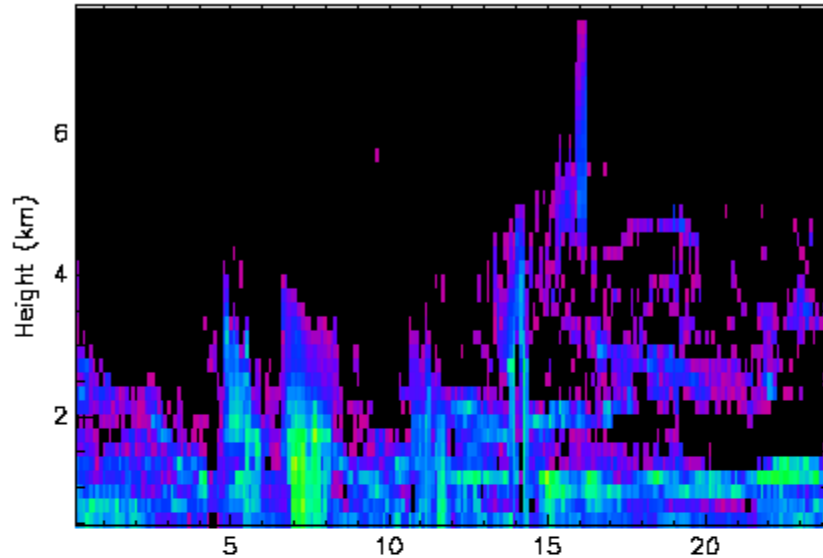


915 MHz wind profiler

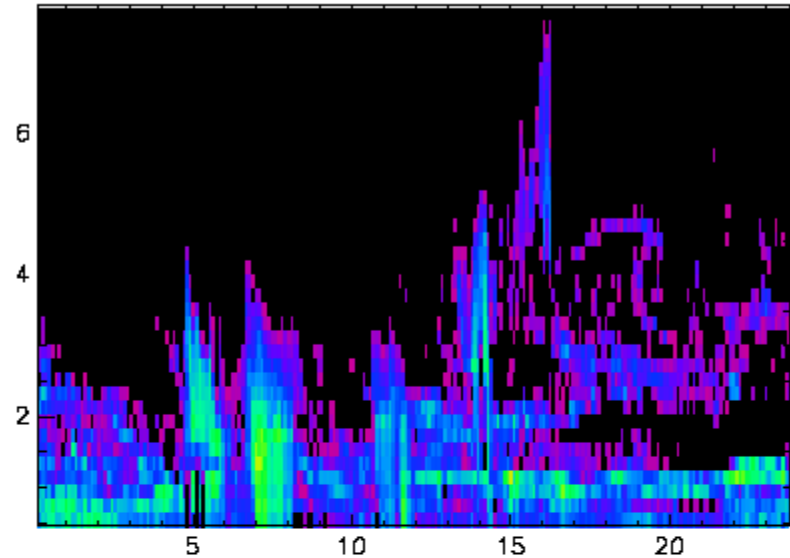
915 MHz wind profiler, quality evaluation tool

Camborne 915 High Mode SNR 22/01/2008

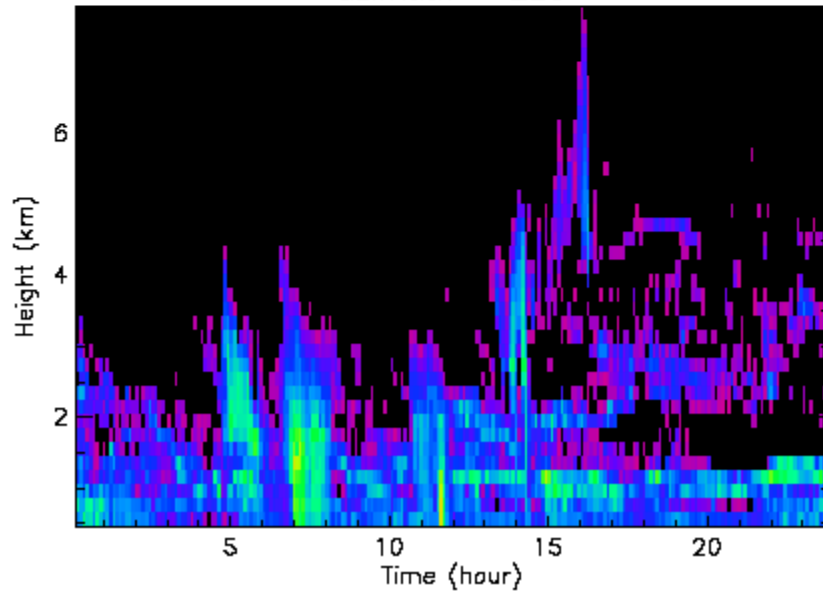
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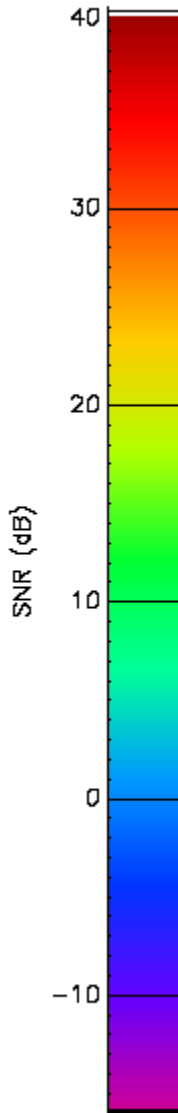
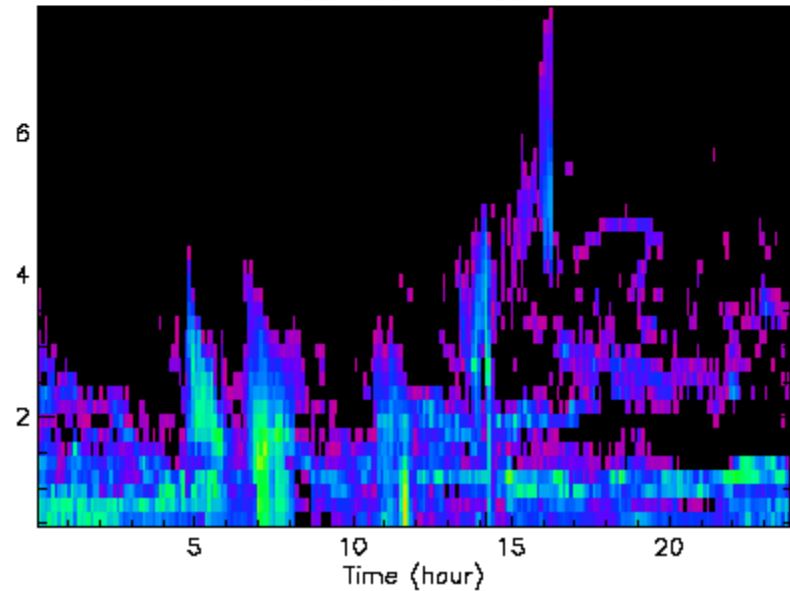
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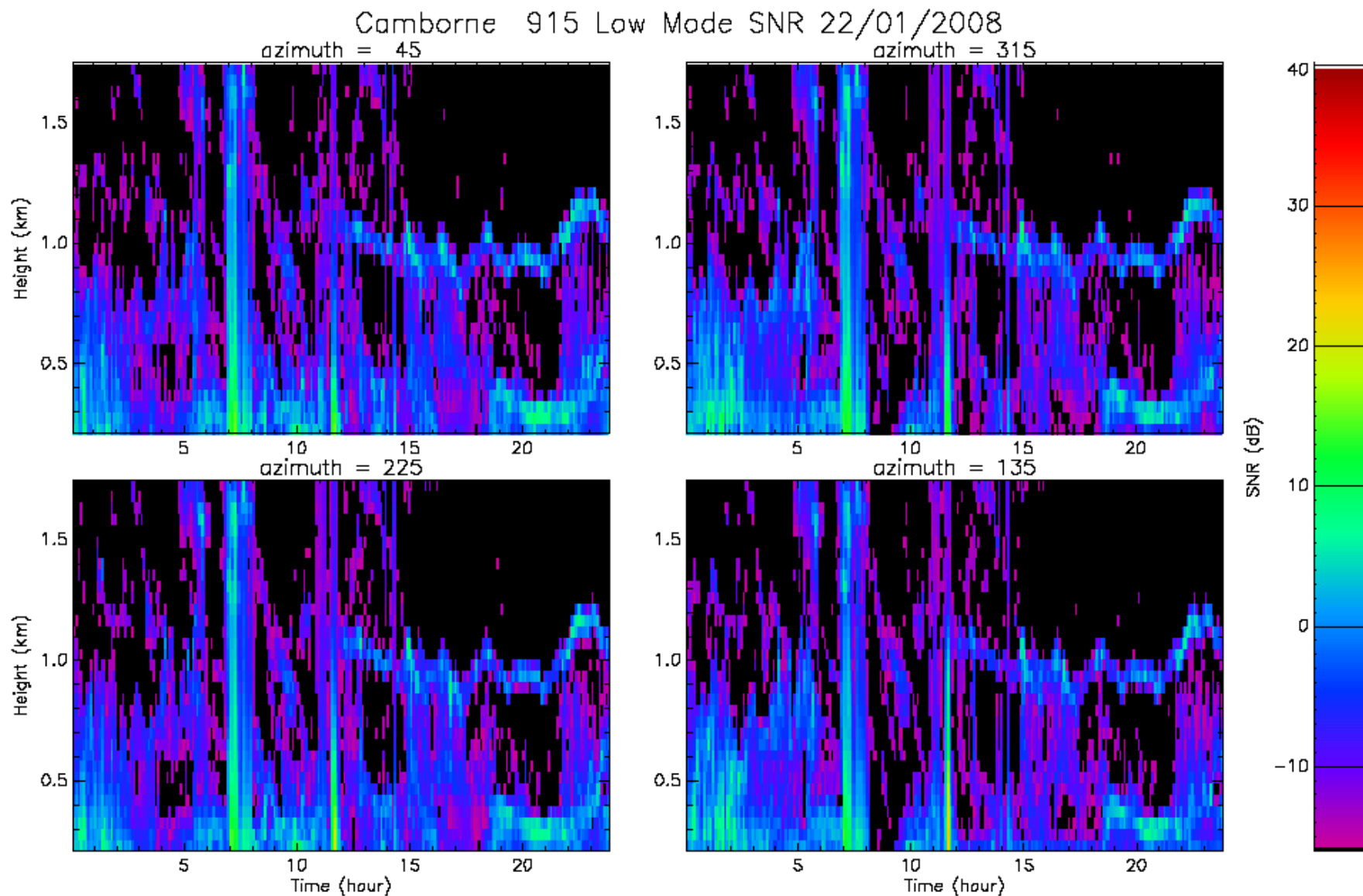
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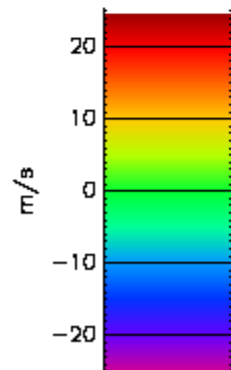
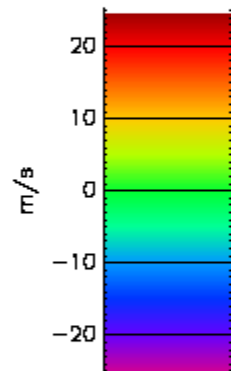
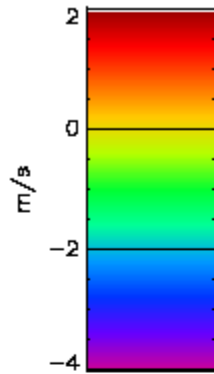
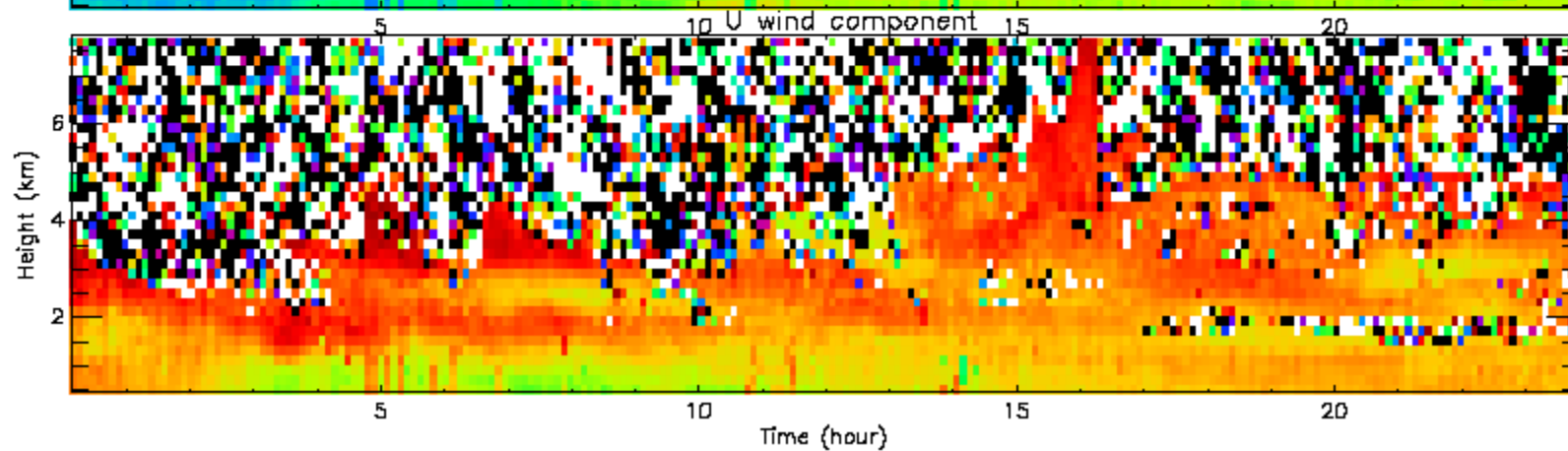
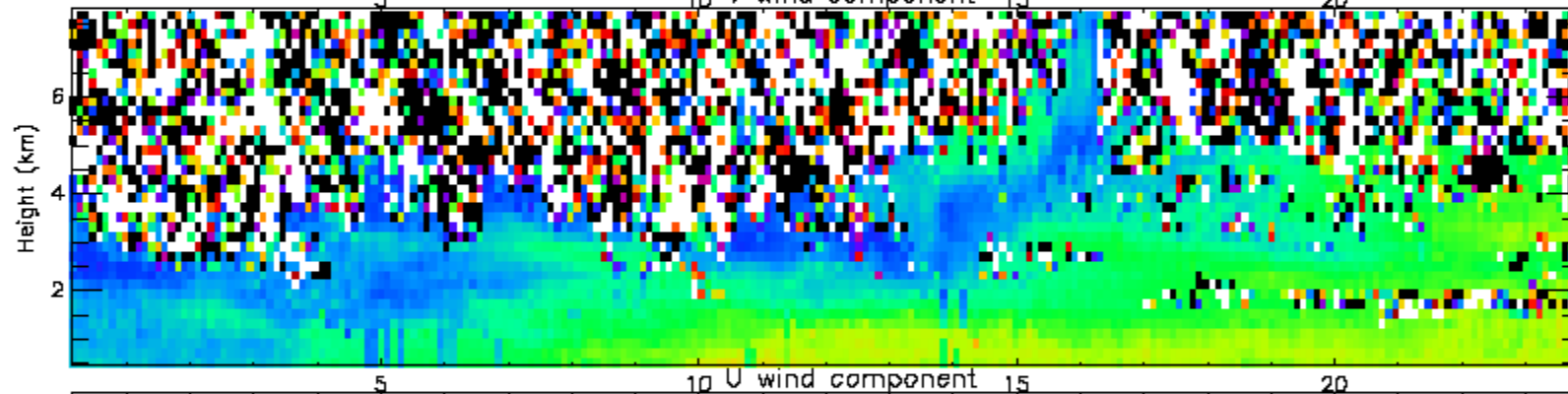
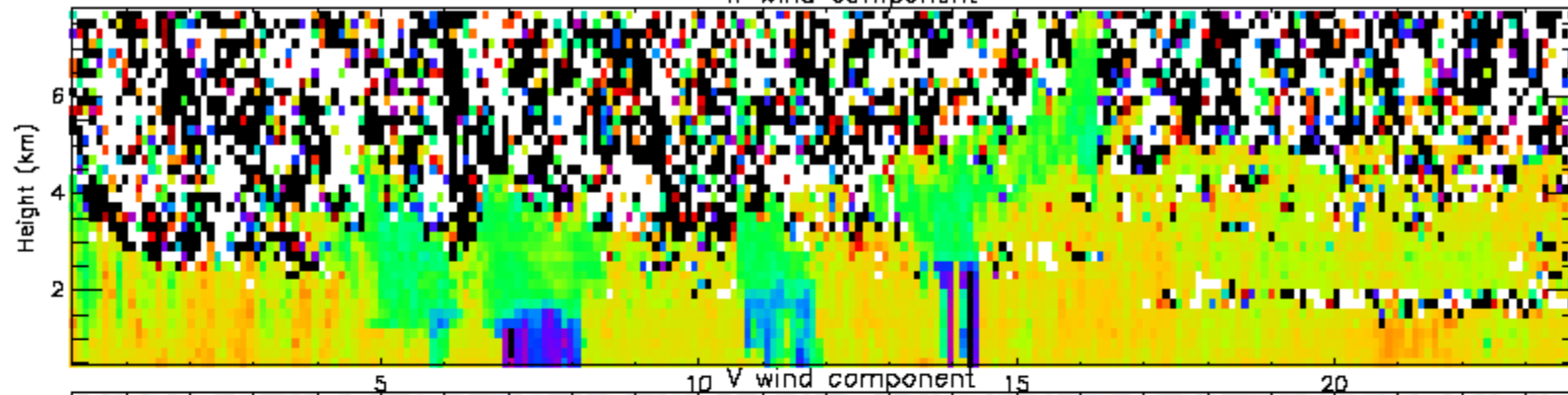
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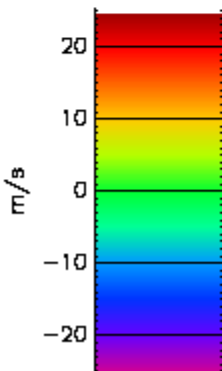
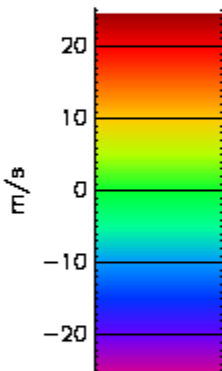
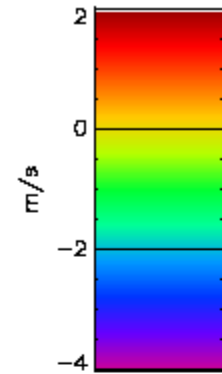
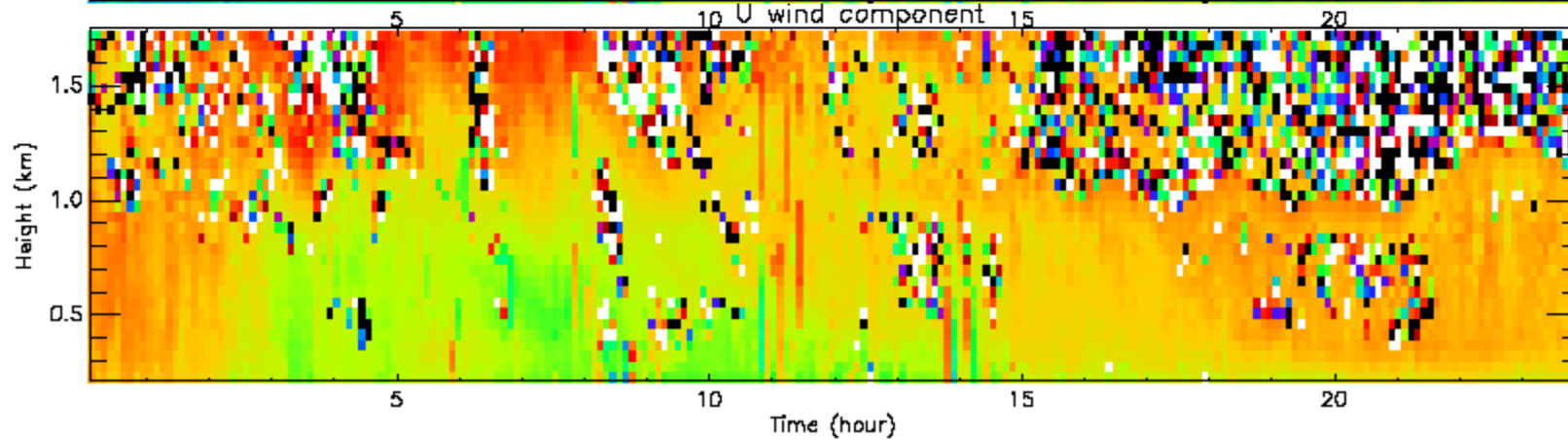
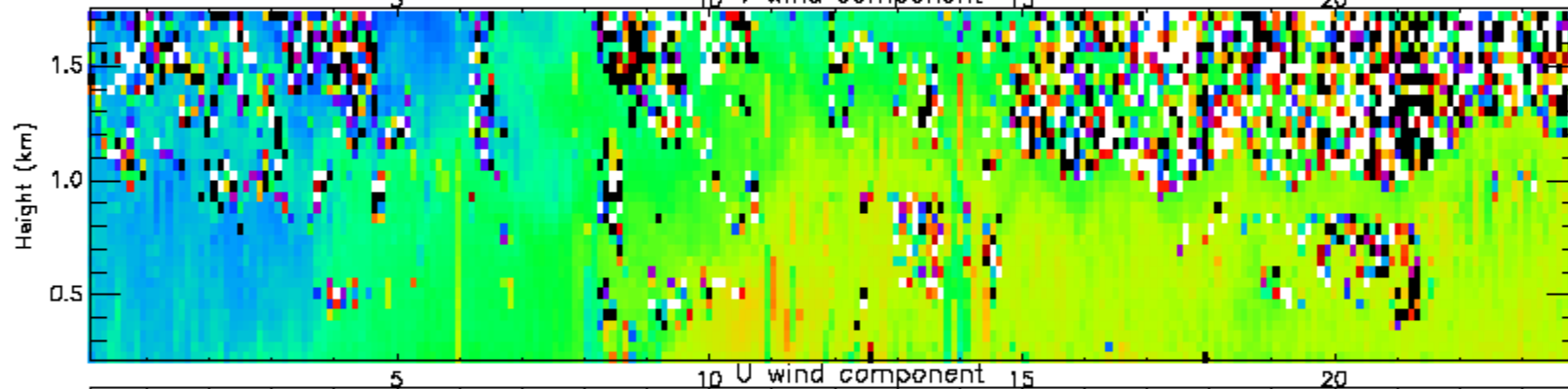
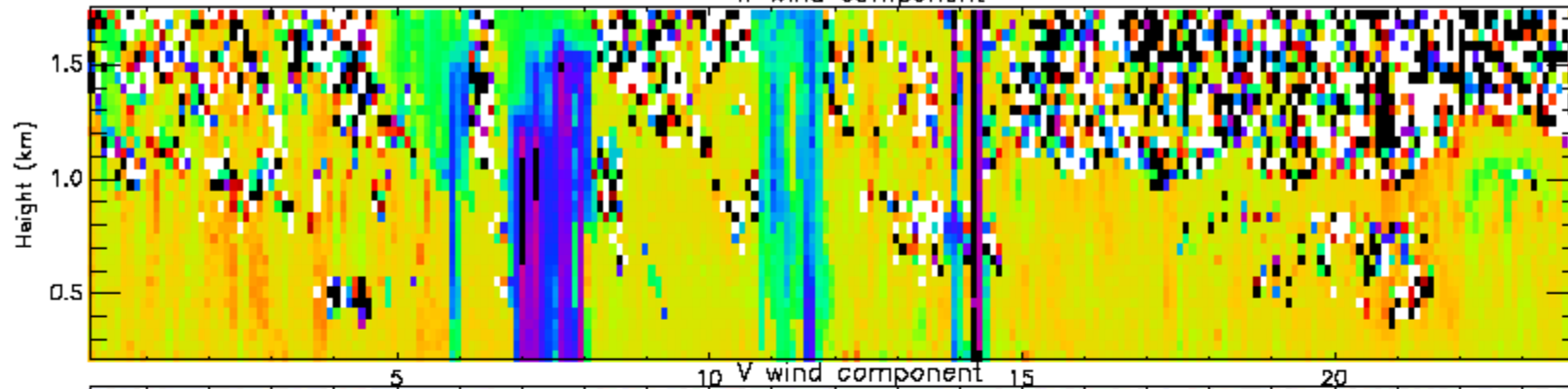
915 MHz wind profiler, quality evaluation tool



Camborne 915 High Mode 22/01/2008
W wind component



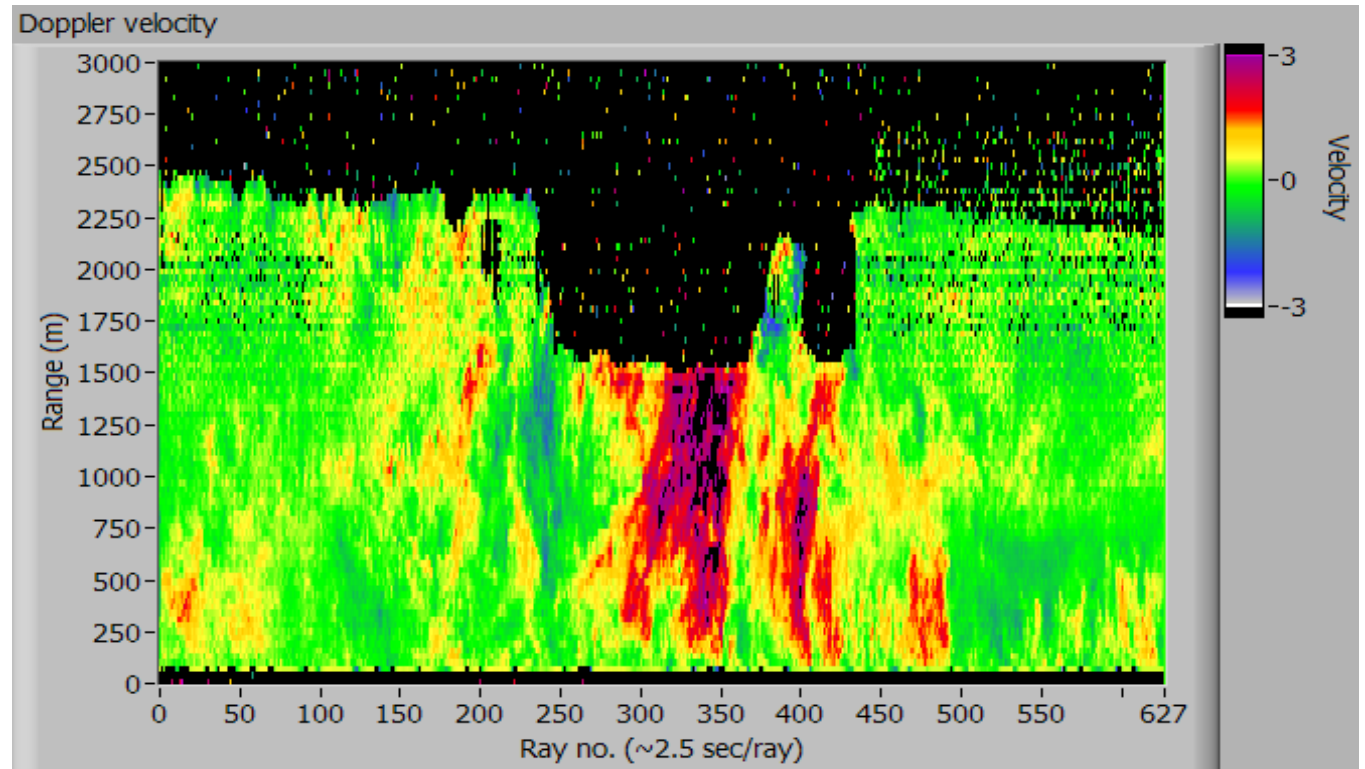
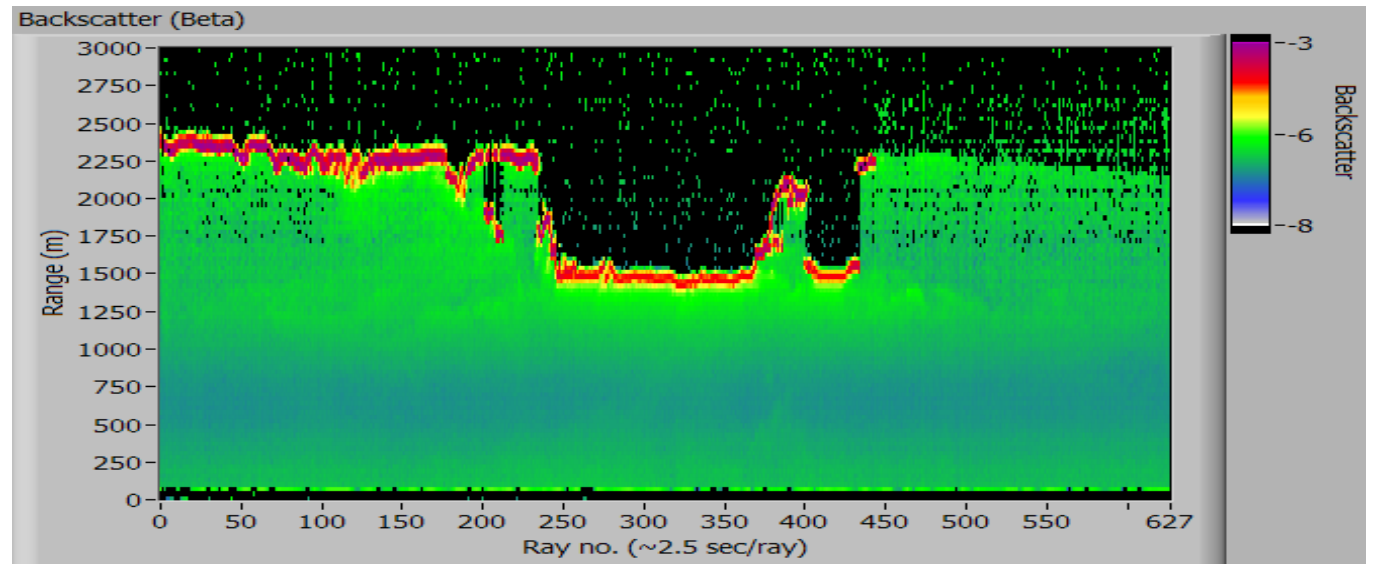
Camborne 915 Low Mode 22/01/2008
W wind component



Optical Doppler
lidar

Halo Photonics
Vertical velocity

Cardington
13.09.07
Starting at 16.00

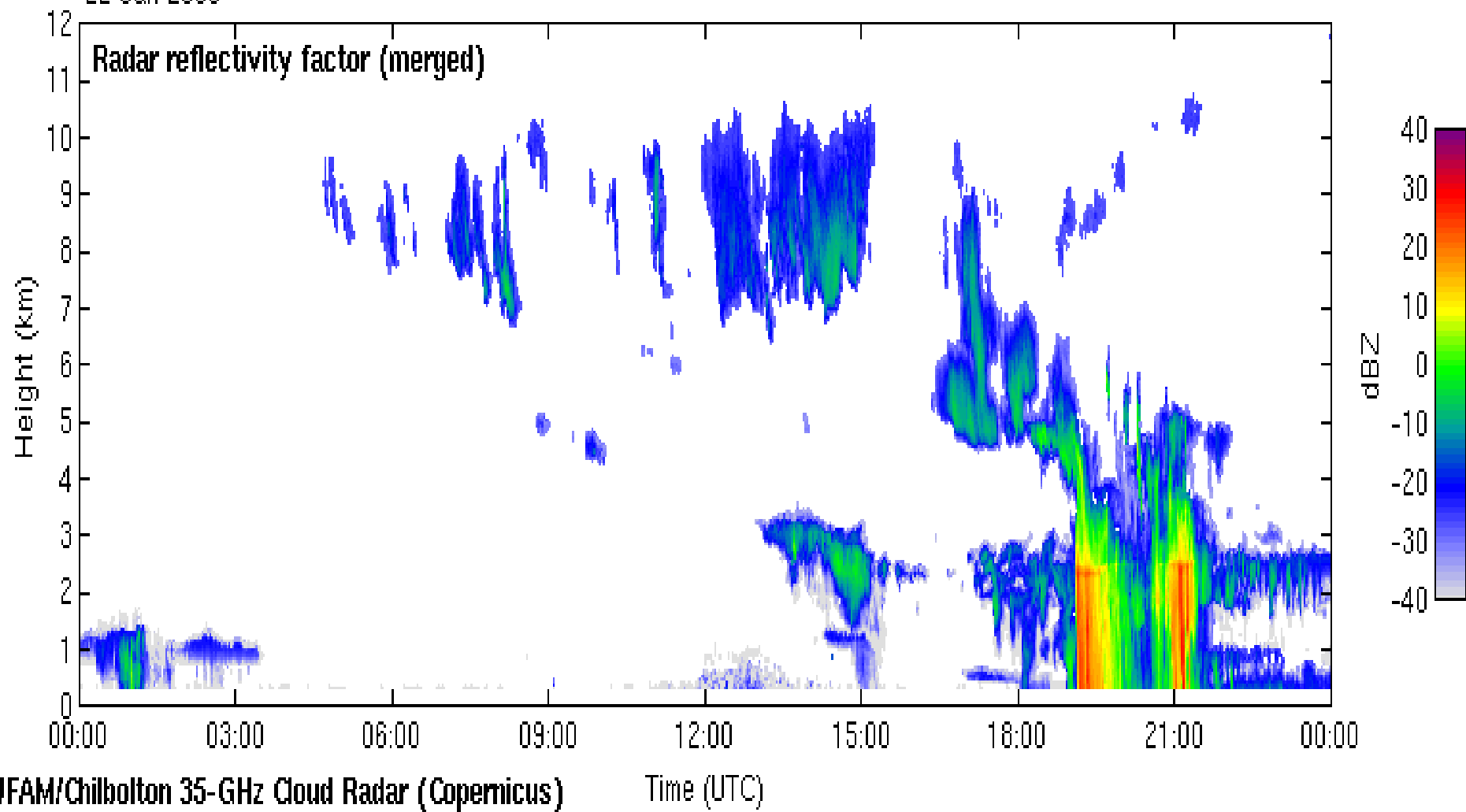


94 GHz and 35 GHz pulsed cloud radars at Chibolton, UK.



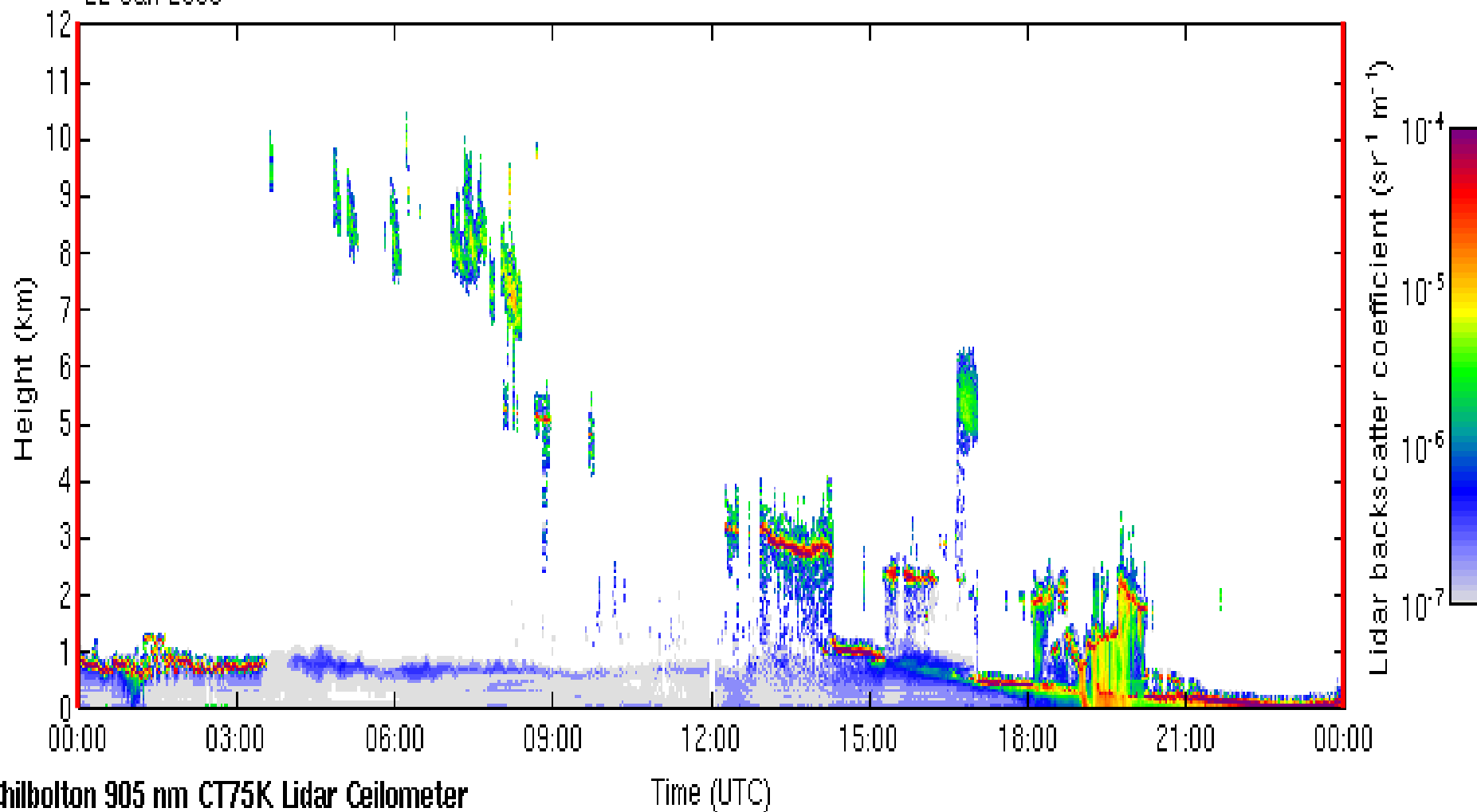


22 Jan 2008



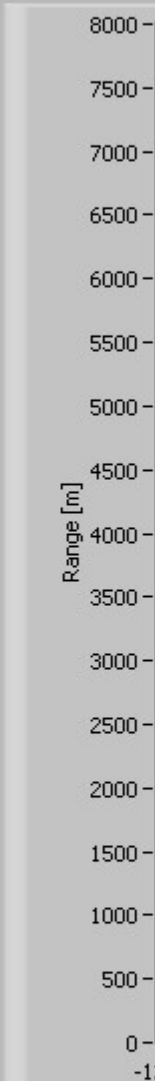
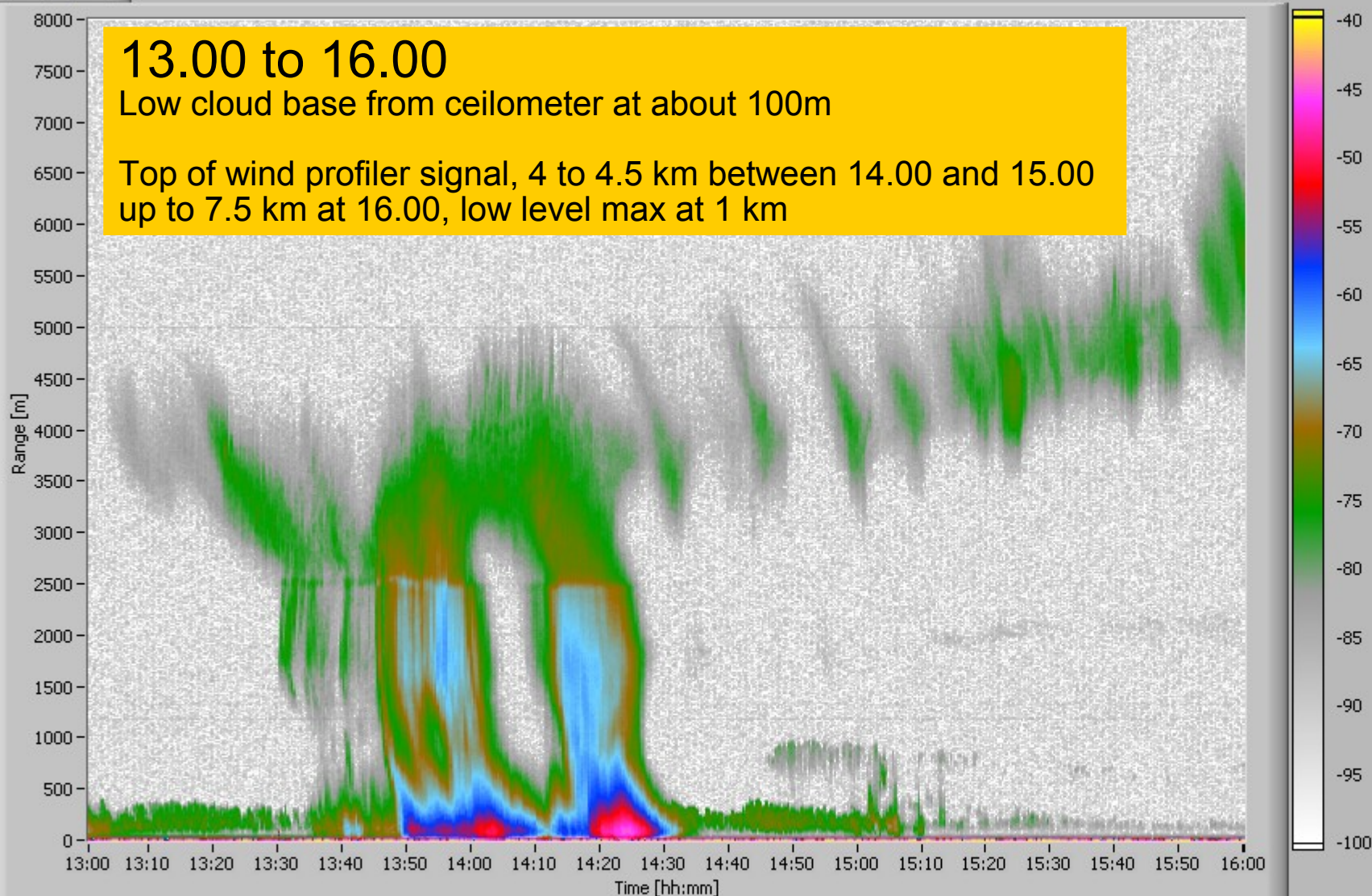
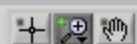


22 Jan 2008





94 GHz fmcw cloud radar



Time [hh:mm] 13.00

Range [m] 0.00

Intensity [dBZ] -100

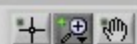
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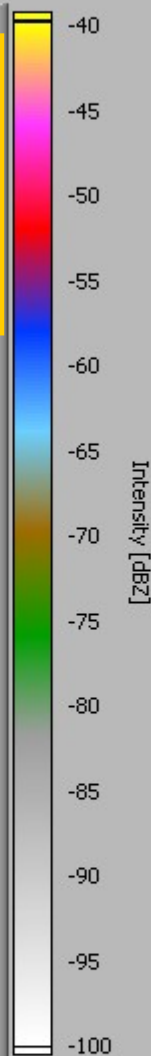
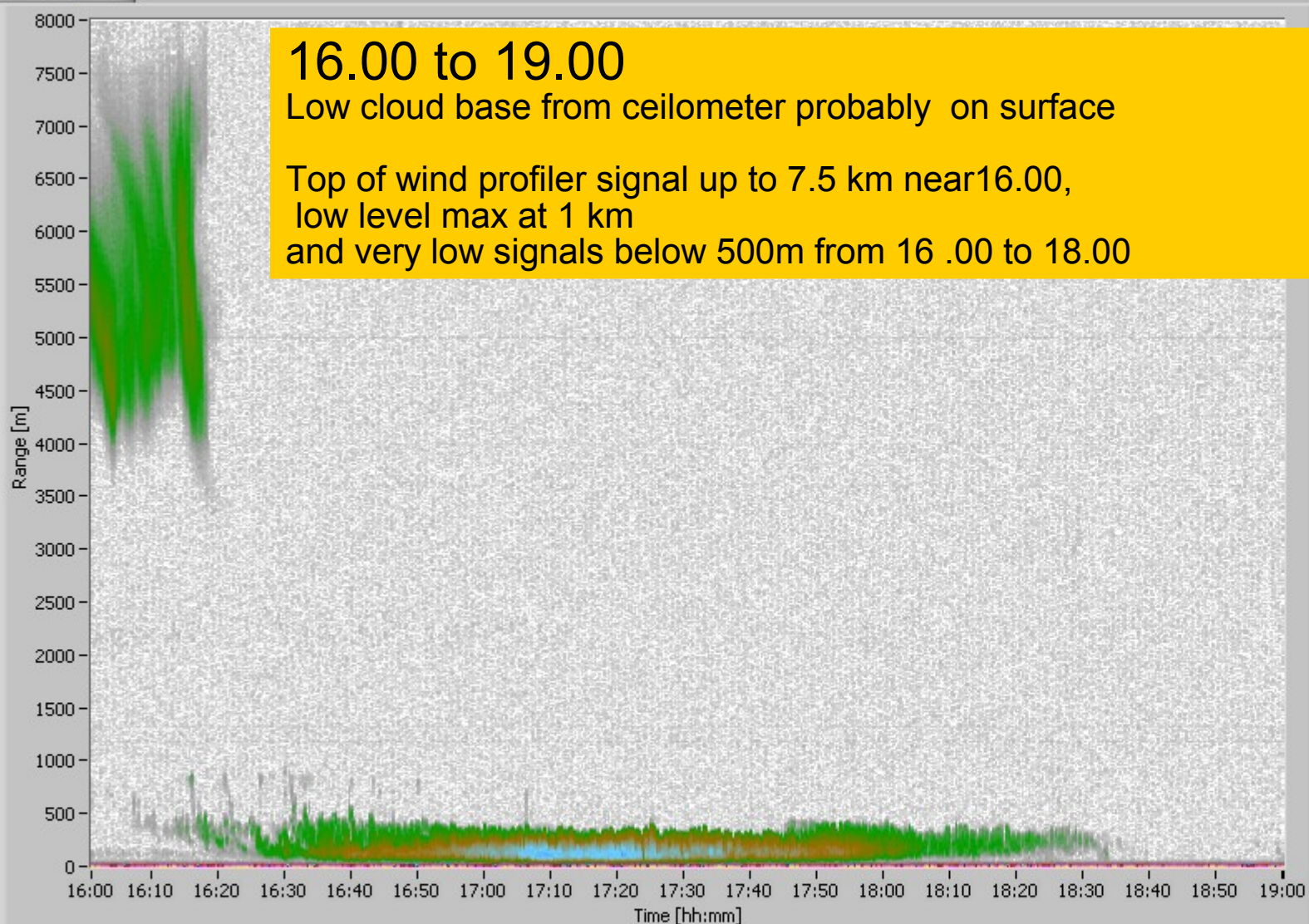
Intensity [dBZ]
 Range [m]

Cursors:

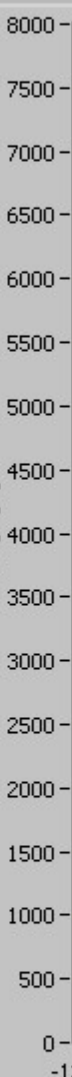
+ ◆ Cursor



Last Scan



Range [m]



Time [hh:mm] 16.00

Range [m] 7500

Intensity [dBZ] -40

Last Scan Time Stamp Peak [dBZ]
 2008/01/22 18:59:34 -42.139E

Data file D:\Camborne\ycr002_20080122_140734_mod.csv

Intensity [dBZ]
 Range [m]

Cursors:

+ ◆ Cursor



Integration Project

- Aims to develop new products from basic measurements of basic instruments,
- E.g. more detailed estimates of clouds
- Identification of top of the convective boundary layer
- Identify significant capping inversions
- Estimates of cloud top
- Estimates of fog depth



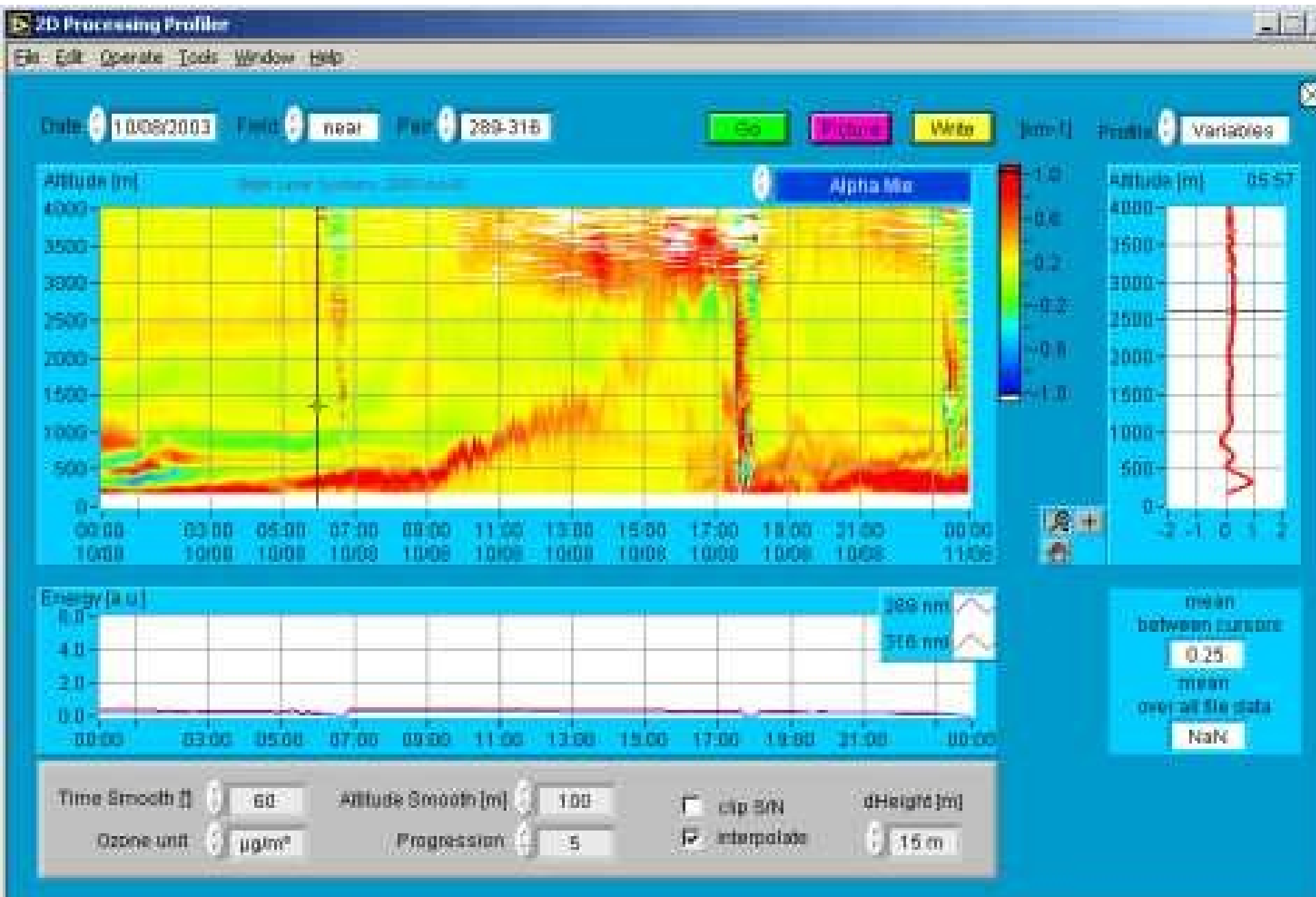
Summary

- Ground based remote sensing is required in future upper air networks
- Design of networks needs to be based on a knowledge of mesoscale structure and the associated atmospheric structures
- Error characteristics of the remote sensing observations must be established for data assimilation techniques
- Improved operational practices need to be developed and are not yet readily available
- It is recommended that testbed experiments be used to develop the necessary knowledge
- CIMO/WMO will sponsor experiments

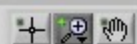
UFAM Ozone and Aerosol Lidar

*Geraint Vaughan, Emily Norton, Dave Wareing,
Hugo Ricketts*

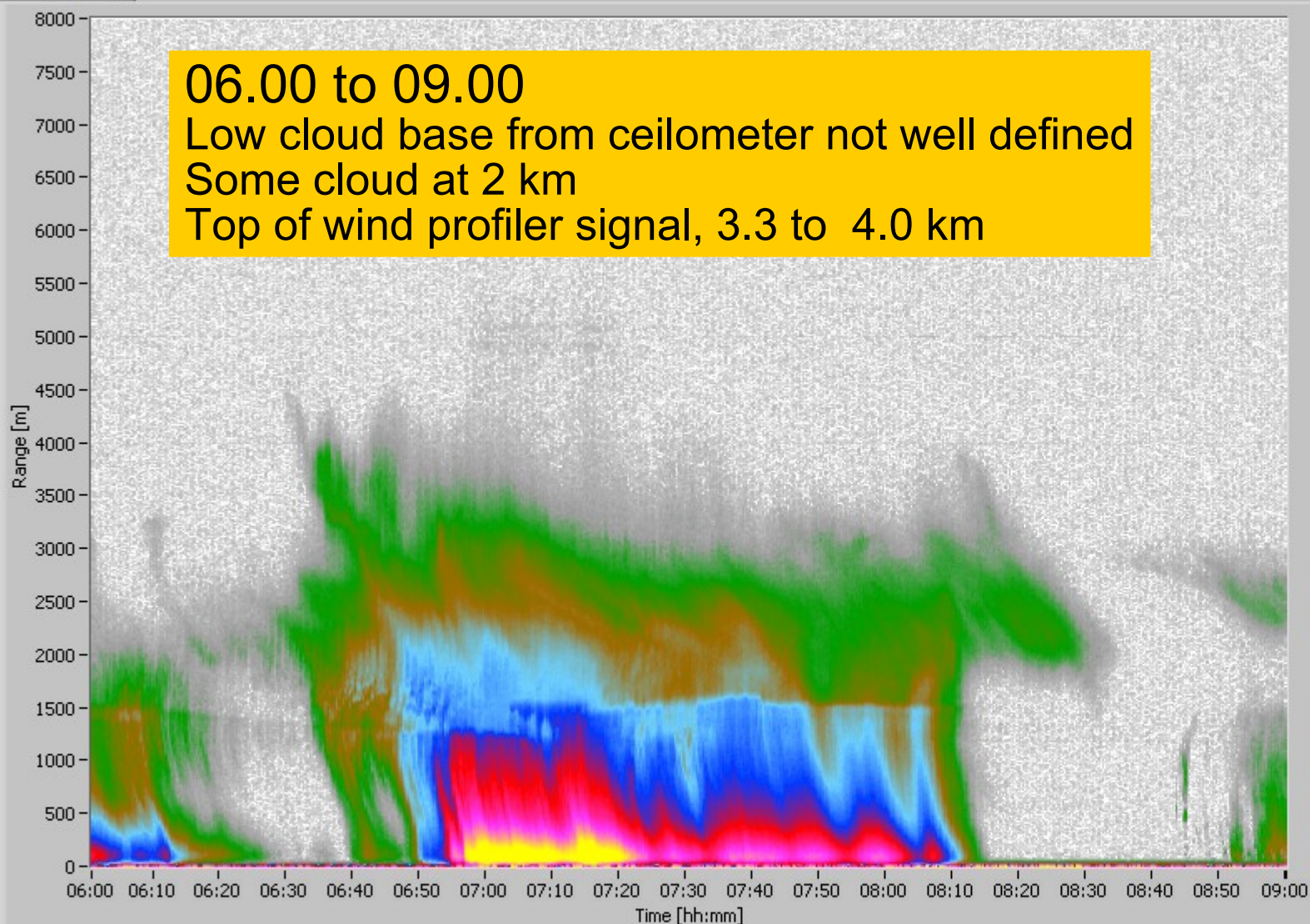
- The five wavelength ozone profiler is a compact stand alone differential absorption lidar (DIAL) system designed by [Elight](#) uses a [Continuum PL8020 Nd:YAG laser](#) in conjunction with a multiplexer to pump Raman shifting cells to produce wavelengths of 266, 289, 299, 316 and 315 nm. The wavelengths 289 nm, 299 nm and 316 nm are generated by stimulated Raman scattering in three respective Raman cells. The 266 nm light beam of the laser pumps the Raman gas cells sequentially by means of a continuously triggering multiplexer. These beams are expanded and emitted into the atmosphere. Backscattered light is collected in a double-coaxial 40 cm diameter telescope allowing measurements in both the near and far field and detected using analogue photo-multiplier tubes.
- The system uses five wavelength beams in the UV region two 'on' and three 'off' the [absorption cross-section of ozone](#) . The attenuation at these wavelengths is measured and used to calculate the vertical distribution of ozone and aerosols up to altitudes of ~5 km.



Questions & answers



Last Scan



06.00 to 09.00

Low cloud base from ceilometer not well defined

Some cloud at 2 km

Top of wind profiler signal, 3.3 to 4.0 km

Time [hh:mm]
 Range [m]
 Intensity [dBZ]

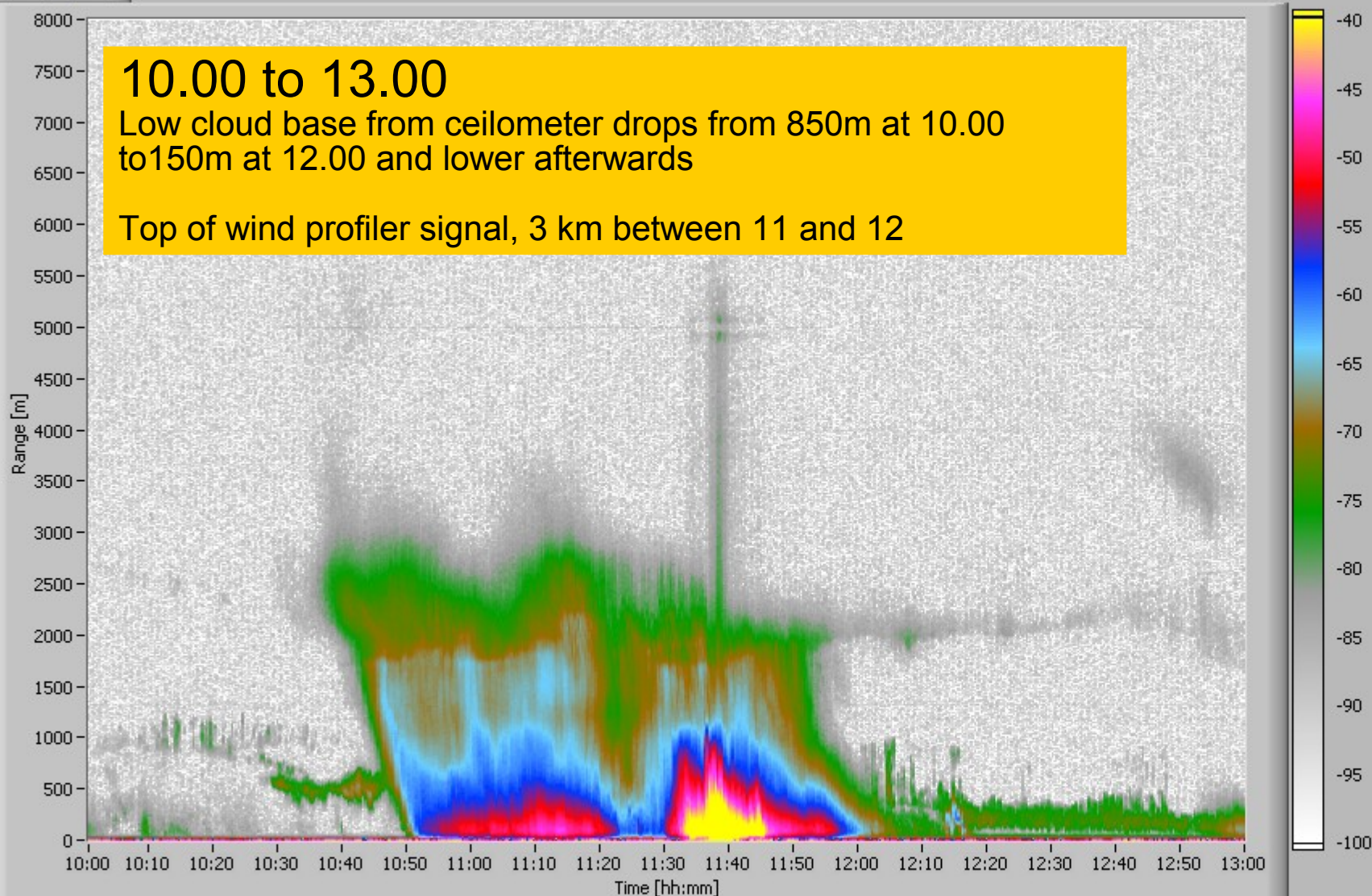
Last Scan Time Stamp Peak [dBZ]
 2008/01/22 08:59:34 -42.9734

Data file D:\Camborne\ycr002_20080122_060734_mod.csv

Intensity [dBZ]
 Range [m]

Cursors:

☐ Cursor



Time [hh:mm] 8.88

Range [m] 9.99

Intensity [dBZ] 2.22

Last Scan Time Stamp Peak [dBZ]
2008/01/22 12:59:34 -52.6026

Data file D:\Camborne\ycr002_20080122_060734_mod.csv

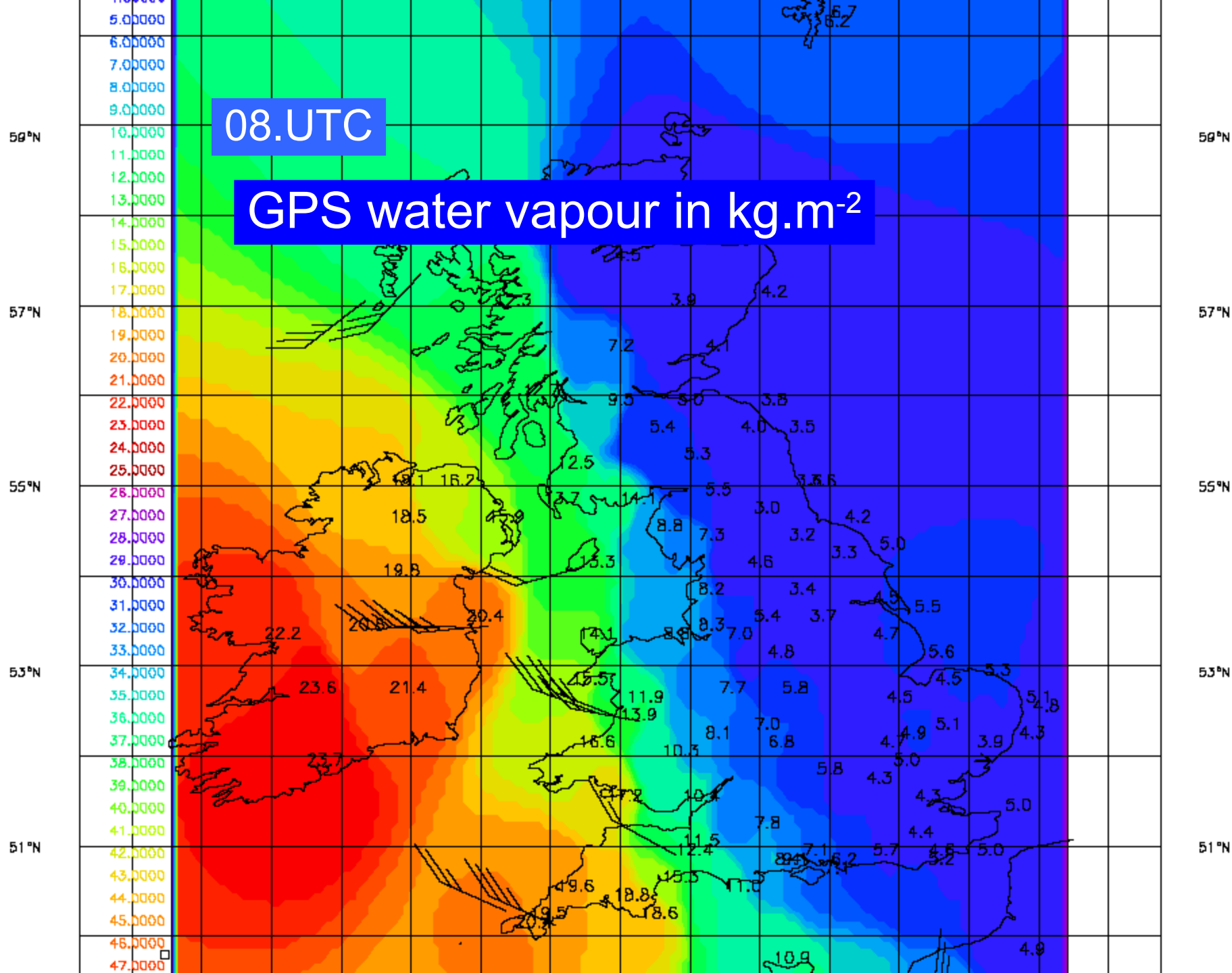
Intensity [dBZ]
Range [m]

Cursors:

+ ◆ Cursor

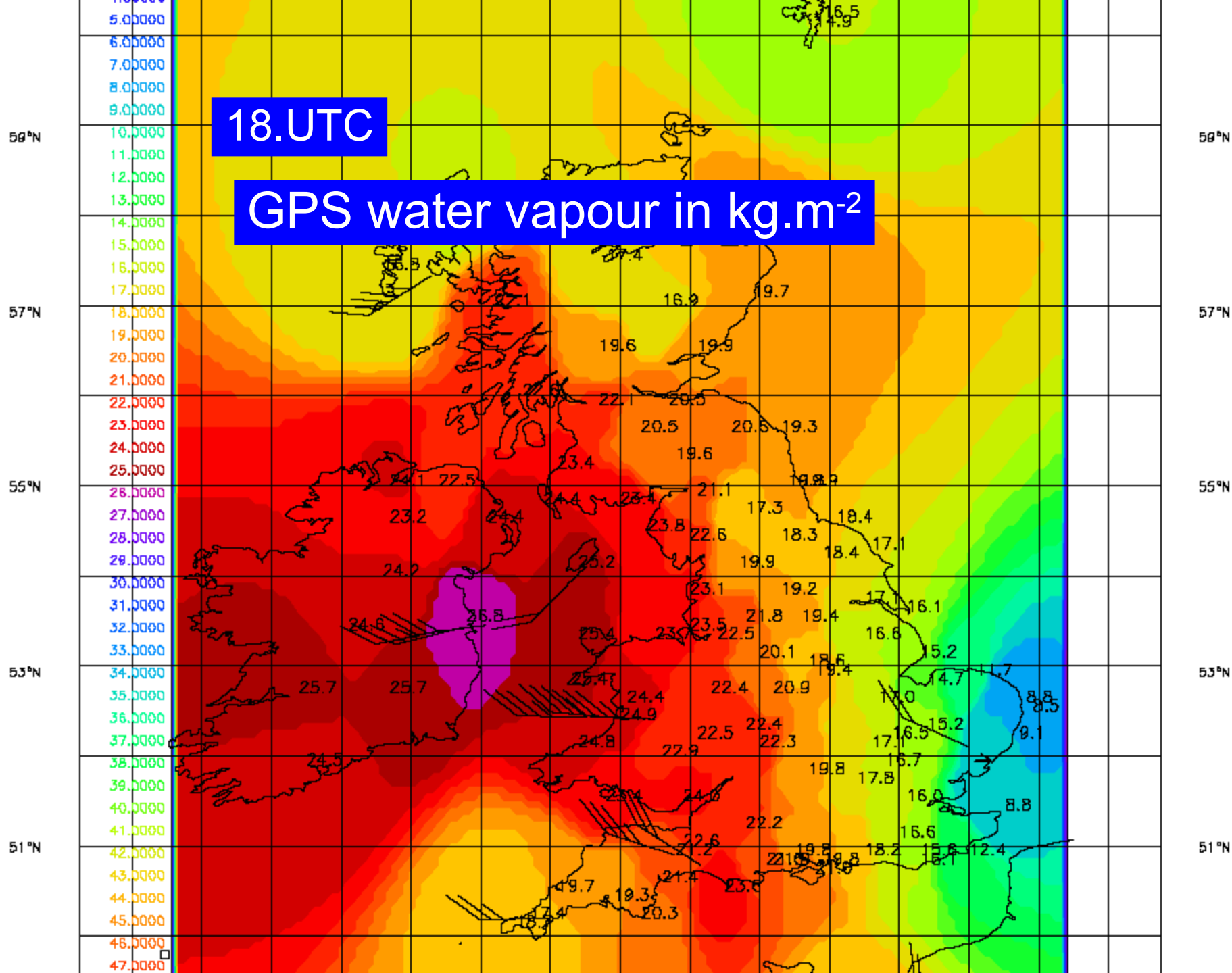
08.UTC

GPS water vapour in kg.m^{-2}



18.UTC


GPS water vapour in kg.m^{-2}



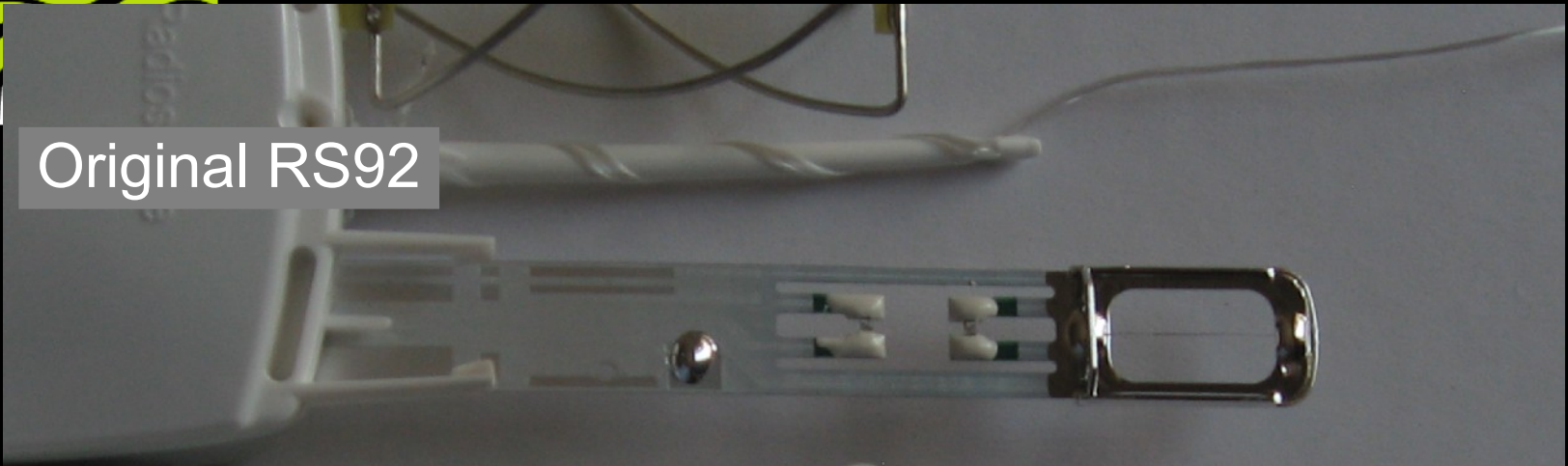


Latest developments in radiosondes

- New Sensors on Vaisala RS92
- New LMS Sippican design
- New Modem sensor designs
- New Internet (SA) GPS radiosonde



Original RS92

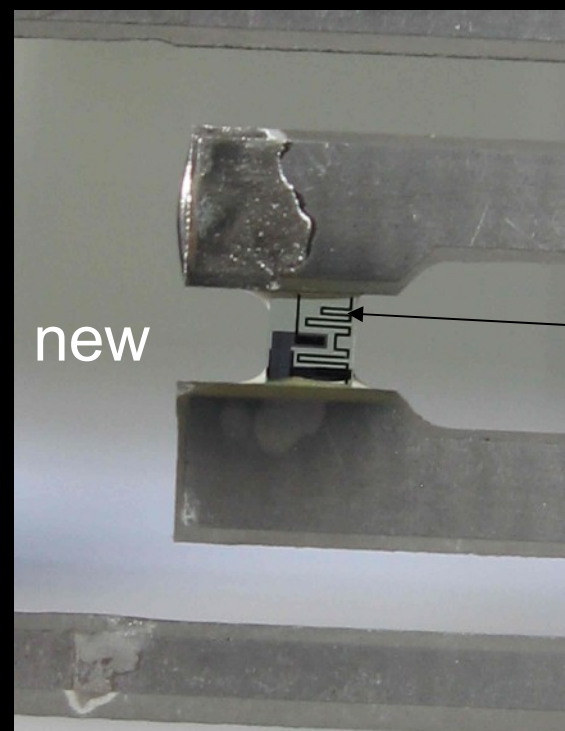
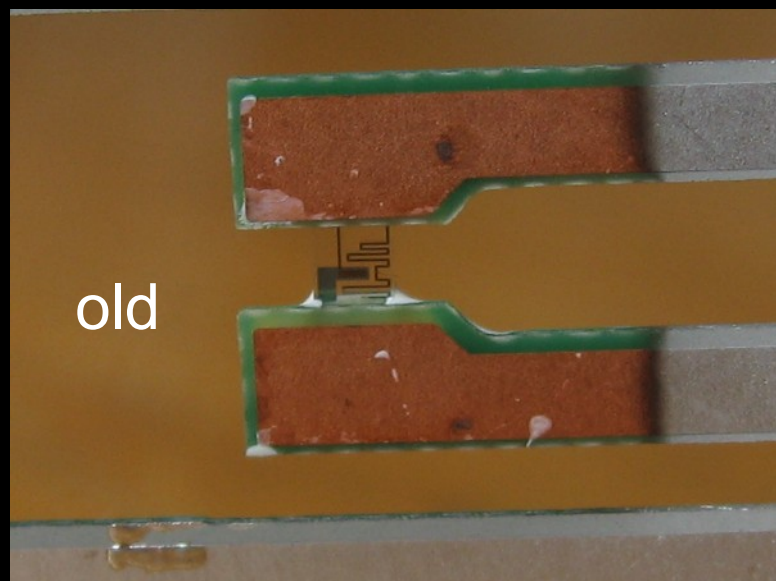
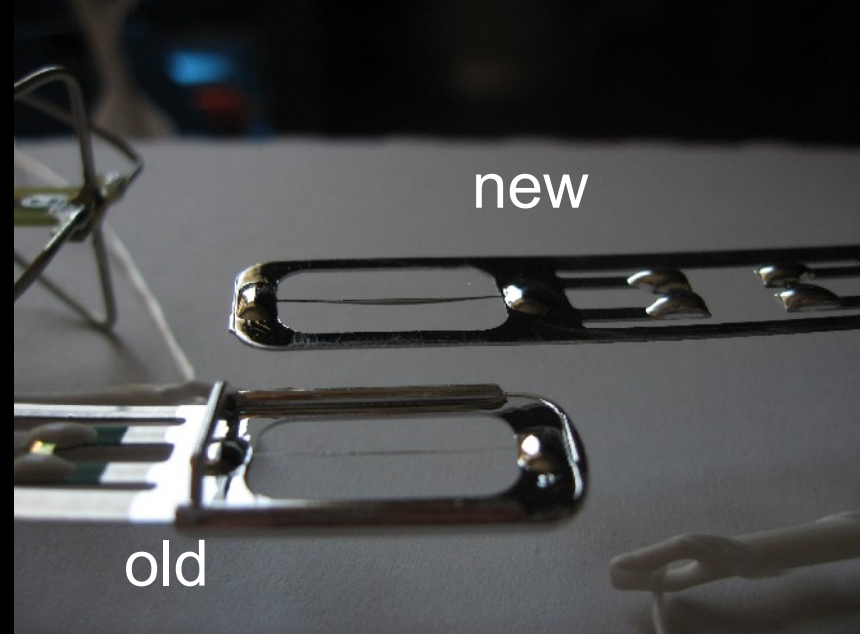


The image shows the original RS92 device, which consists of a white plastic housing on the left and a metal probe assembly on the right. The probe assembly has a silver-colored metal body with a small circular contact point and a larger rectangular contact area. A thin, curved metal wire is attached to the probe assembly.

New RS92



The image shows the new RS92 device, which is similar to the original but features a green printed circuit board (PCB) instead of a metal body. The PCB is mounted on a white plastic housing. A thin, curved metal wire is attached to the PCB. The probe assembly on the right is identical to the original device.



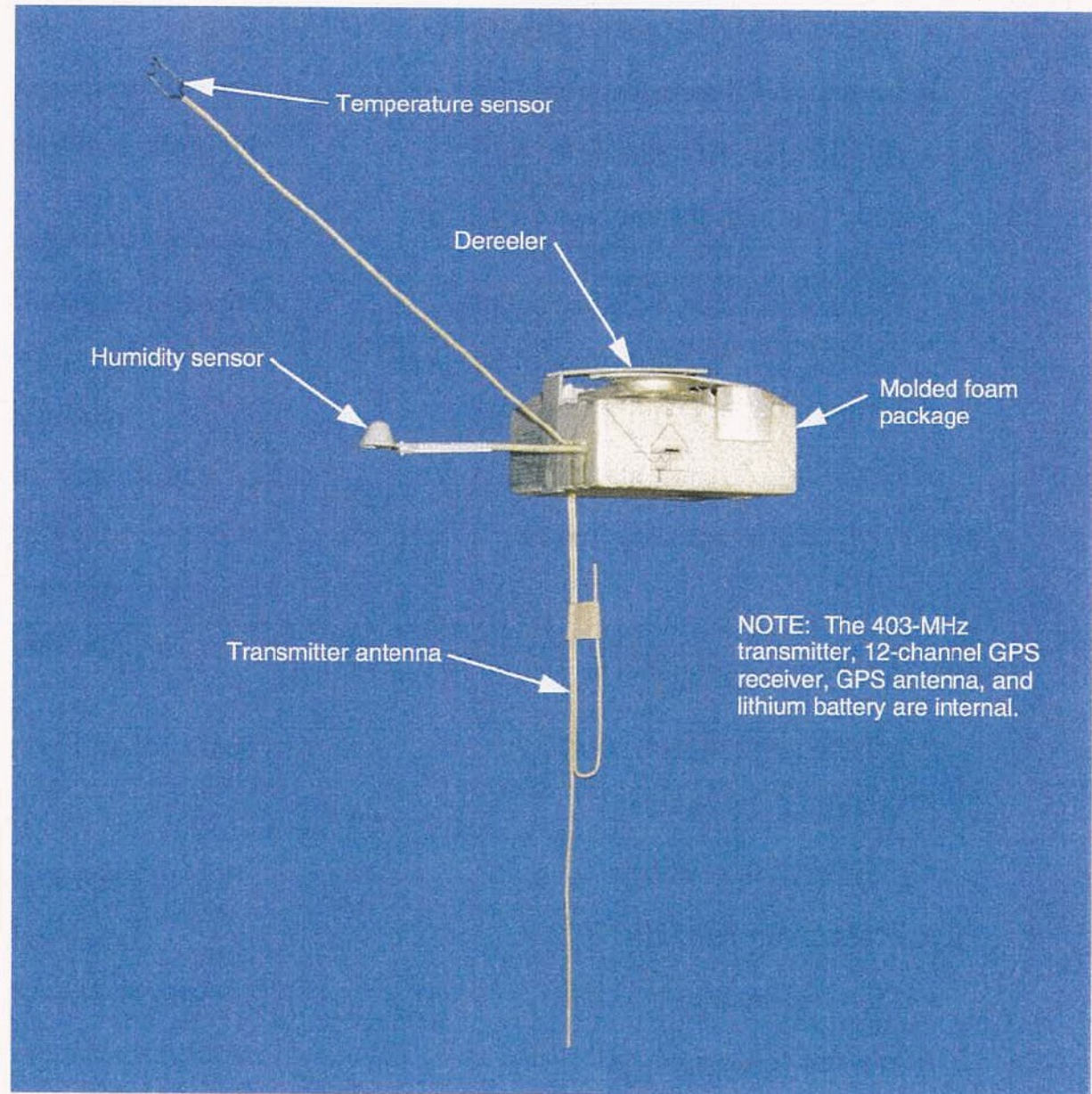
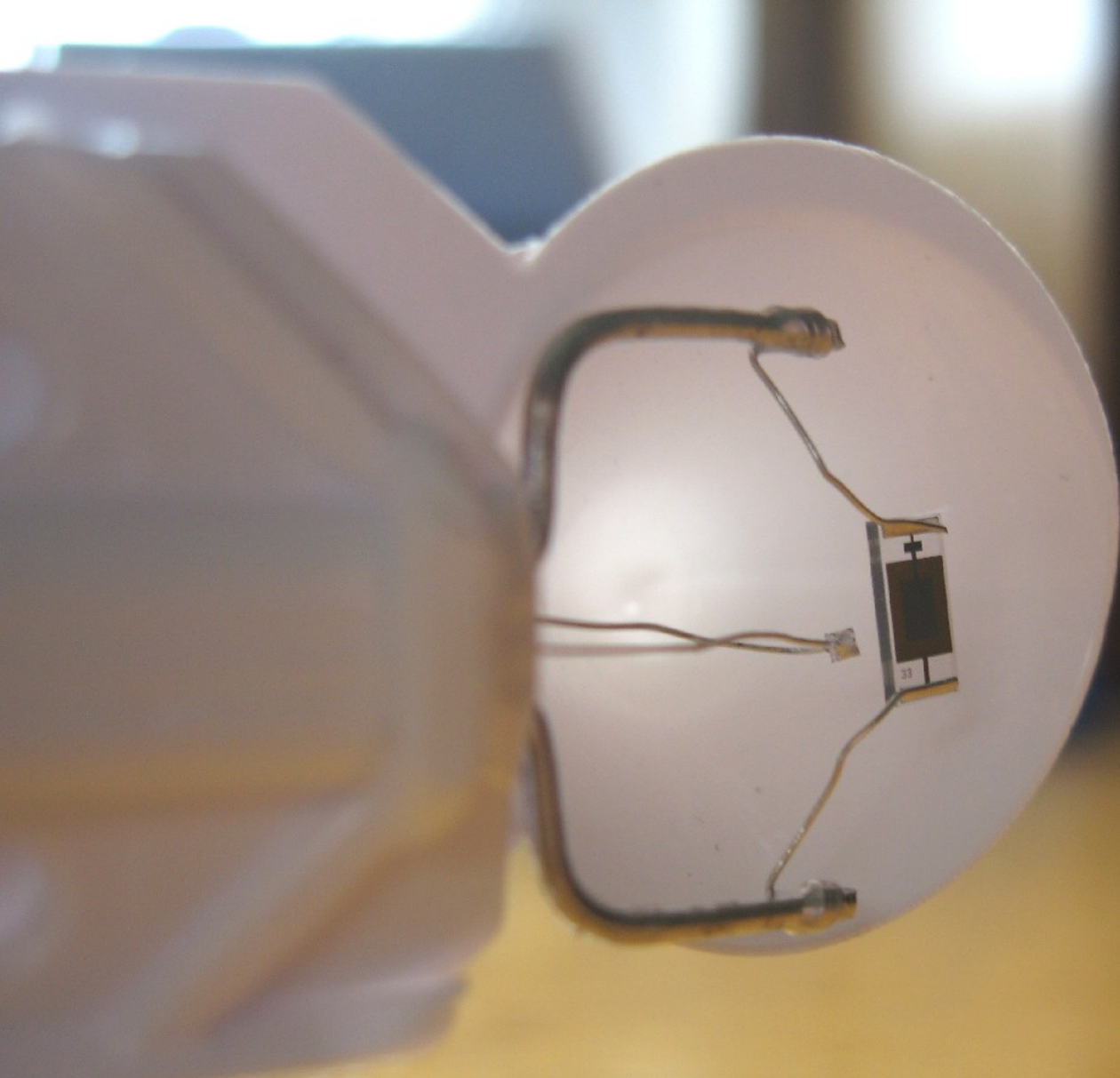


FIGURE 1-1: *The LMS6 Radiosonde*



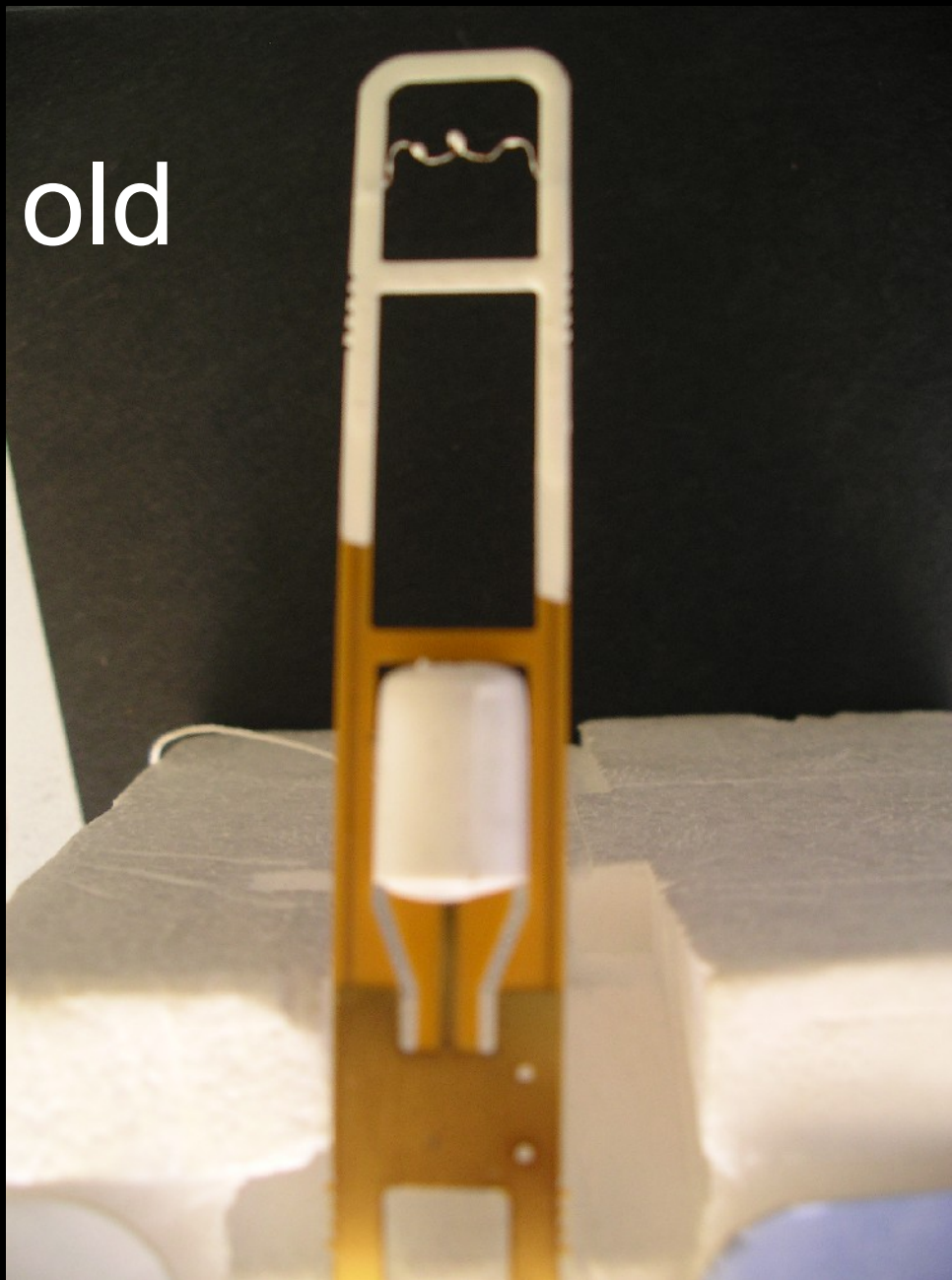
LMS Humidity sensor +T sensor



new



old



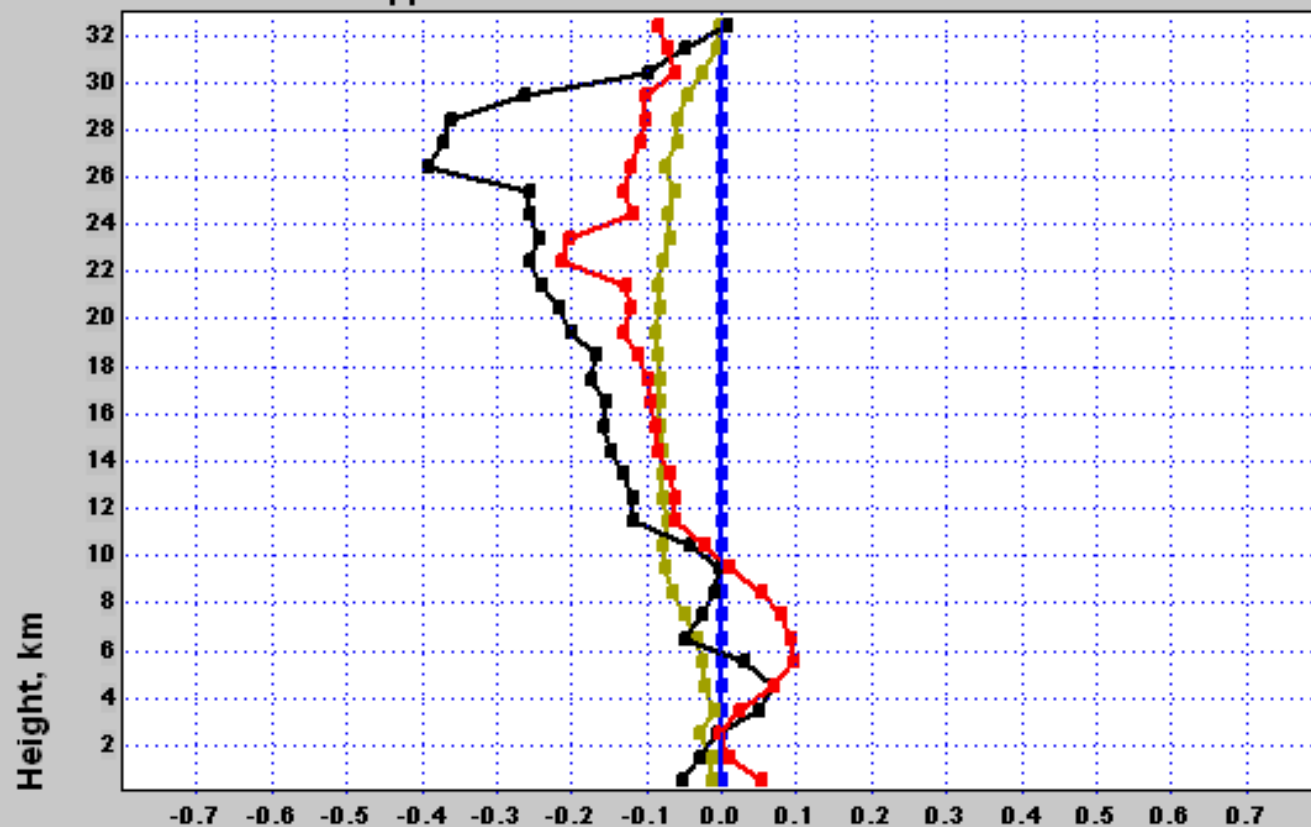


Met Office

Flight-by-flight differences. RS920 RS92N MOD SCAN

Variable: Temperature. Data resolution: Time 1 sec. 11 flights. .

Restriction: Not applied



Night

7	7	2	12
7	7	2	12
7	7	2	12
8	8	2	12
8	8	2	12
8	8	2	12
8	8	2	12
9	9	3	12
10	10	3	3
10	10	3	3
10	10	3	3
10	10	3	3
10	10	3	3
10	10	3	3
10	10	3	3
10	10	3	3
10	10	3	3
10	10	3	3
10	10	3	3
10	10	3	3
10	10	3	3
10	10	3	3
10	10	3	3
10	10	3	3
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10	10	3	3
10	10	4	3
10	10	4	3
10	10	4	3
10	10	4	3

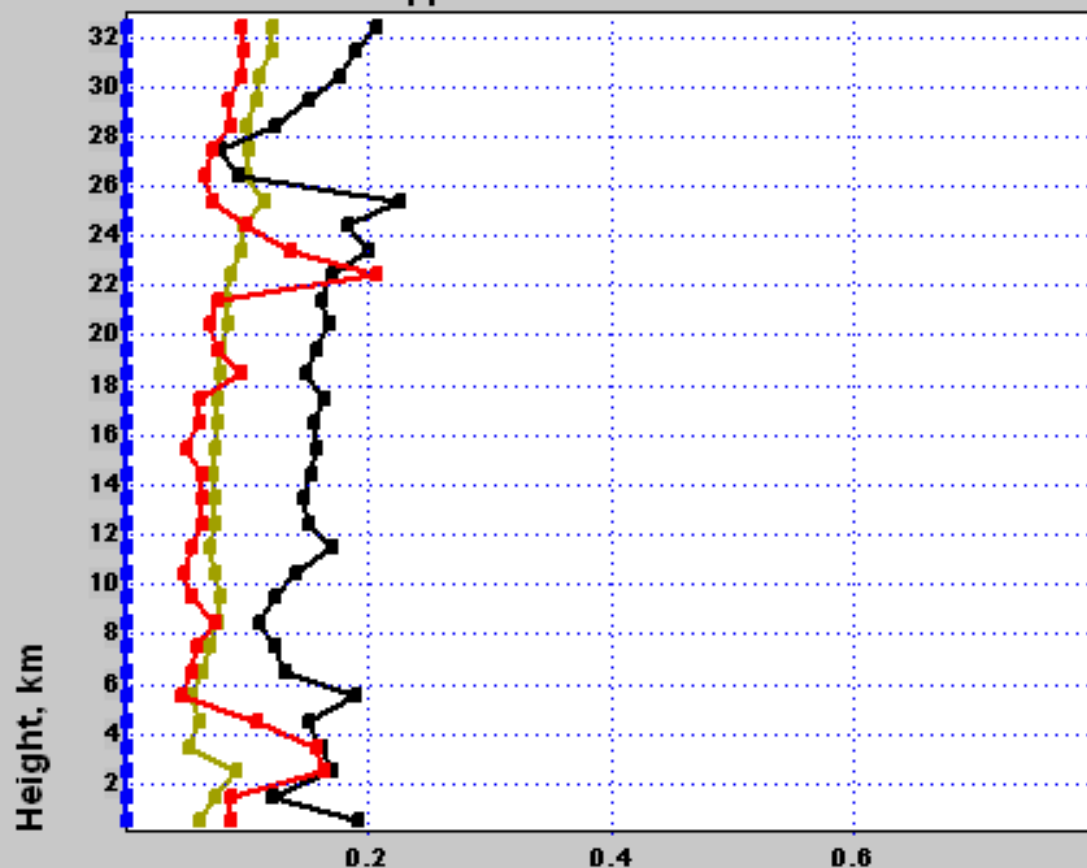


Met Office

Standard Deviations. RS920 RS92N MOD SCAN

Variable: Temperature. Data resolution: Time 1 sec. 11 flights. .

Restriction: Not applied

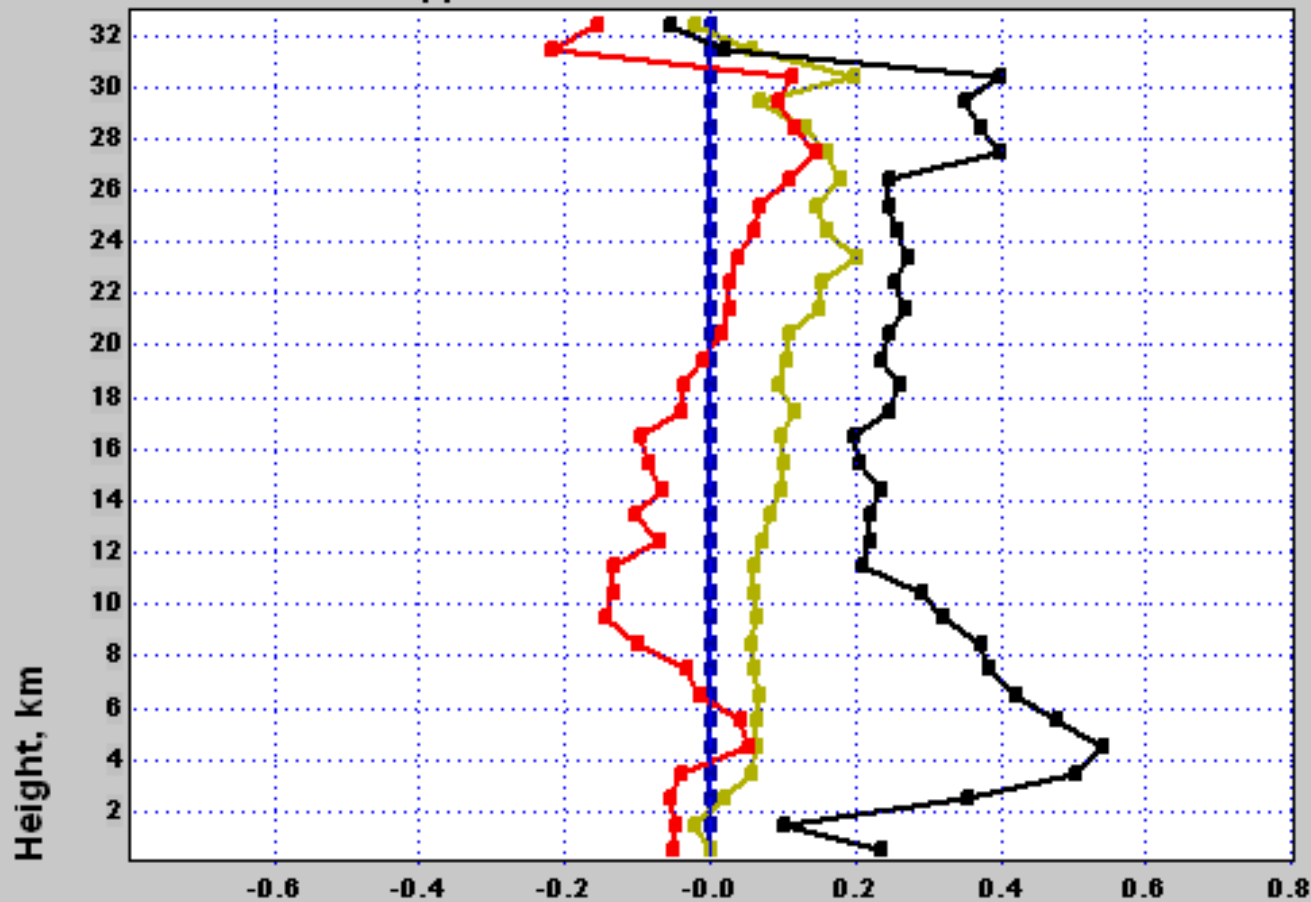


Night

1118	1091	327	337
1097	1097	317	329
1054	1054	312	318
1126	1126	326	318
1247	1247	311	321
1287	1287	331	340
1295	1295	321	343
1442	1442	454	346
1689	1687	512	509
1733	1733	521	545
1775	1775	548	547
1818	1818	556	572
1853	1853	564	587
1857	1857	574	601
1878	1878	562	568
1924	1924	597	587
1993	1993	617	628
1981	1981	606	623
1972	1972	645	613
1999	1999	635	587
1952	1952	620	576
1833	1833	580	545
1823	1823	556	554
1780	1780	542	554
1752	1752	501	532
1722	1722	513	523
1781	1781	526	540
1892	1892	549	583
1853	1853	490	513
1813	1813	508	399
1951	1951	705	488
1951	1951	648	485
1673	1672	642	519



Restriction: Not applied

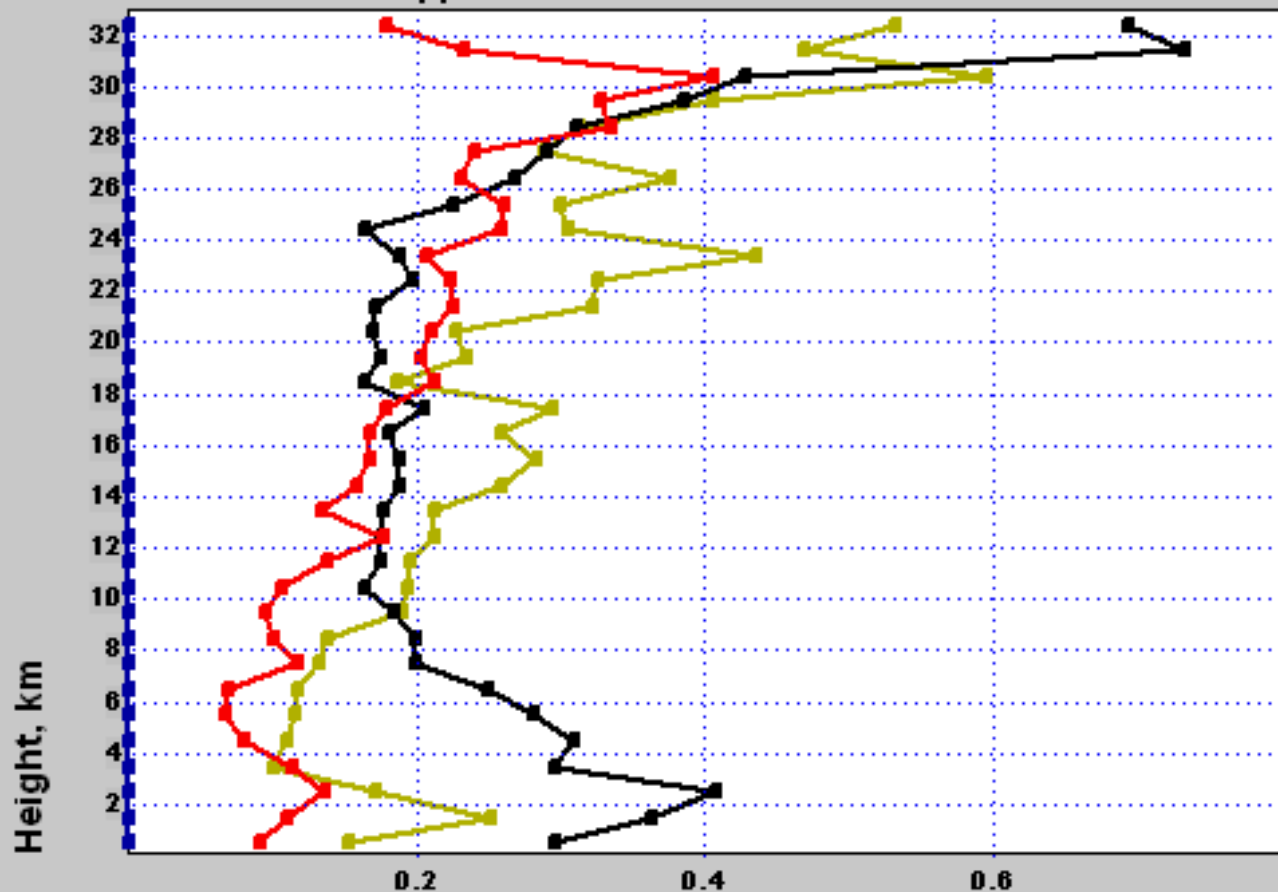
[illegible]



Standard Deviations. RS920 RS92N MOD SCAN

Variable: Temperature. Data resolution: Time 1 sec. 21 flights. .

Restriction: Not applied



Day

1868	1676	337	140
2351	2202	592	142
2647	2498	854	396
2845	2692	906	458
2935	2782	921	484
3067	2918	921	457
3124	2965	933	476
3180	3020	939	478
3236	3075	958	494
3311	3143	984	497
3419	3246	1006	512
3449	3278	1016	507
3552	3370	1046	550
3628	3446	1078	537
3692	3506	1099	563
3734	3543	1121	574
3813	3622	1137	581
3825	3641	1133	599
3885	3713	1162	614
3851	3674	1148	596
3697	3535	1093	583
3499	3328	1034	539
3452	3280	997	556
3392	3215	965	524
3442	3264	1007	517
3454	3275	1005	522
3564	3379	1041	575
3624	3441	1048	569
3590	3392	1029	410
3552	3372	916	387
3777	3590	948	459
3791	3599	877	434
3361	3200	1014	476

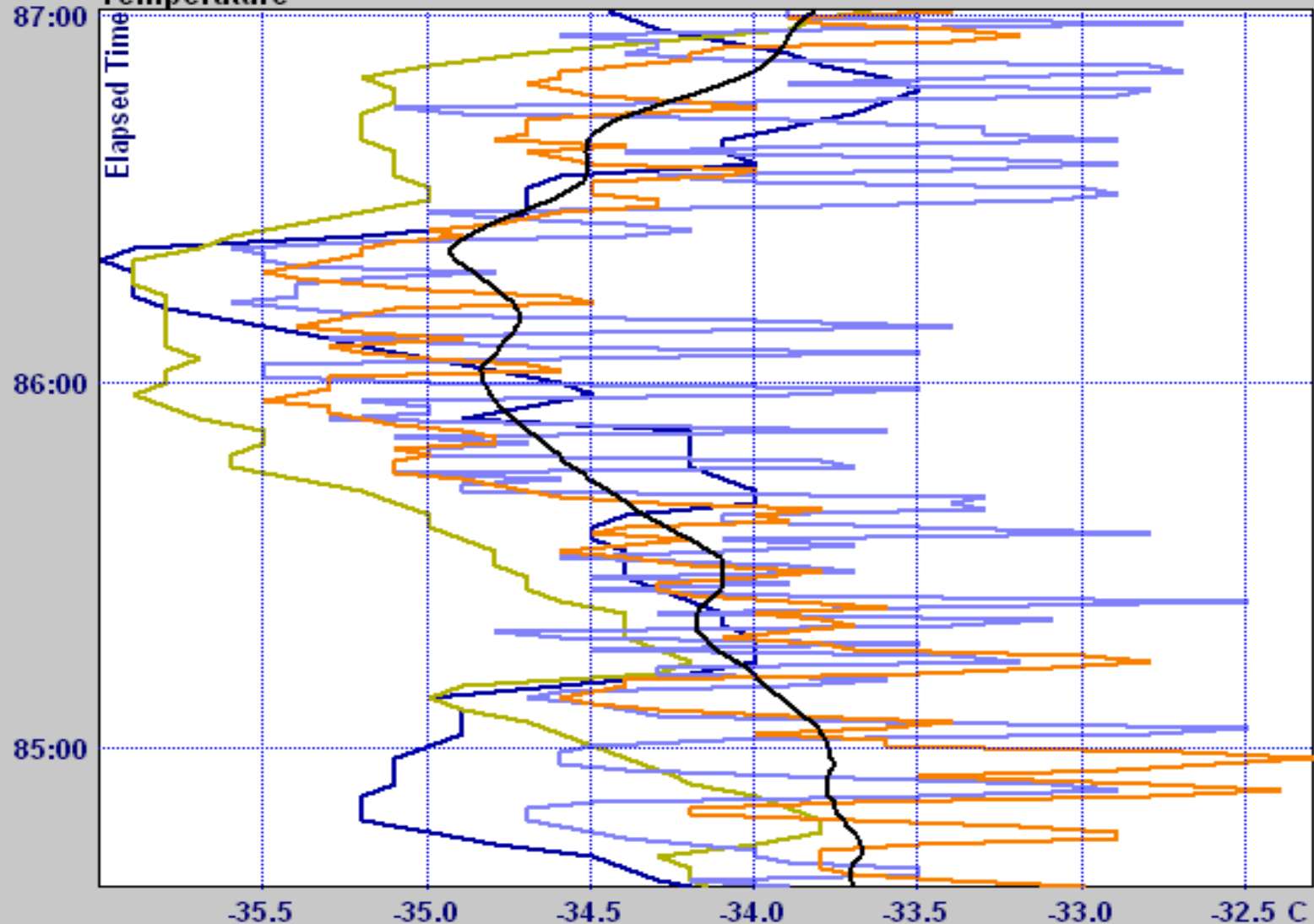


Comparison of raw and processed temperatures at about 15 hPa in day

Met

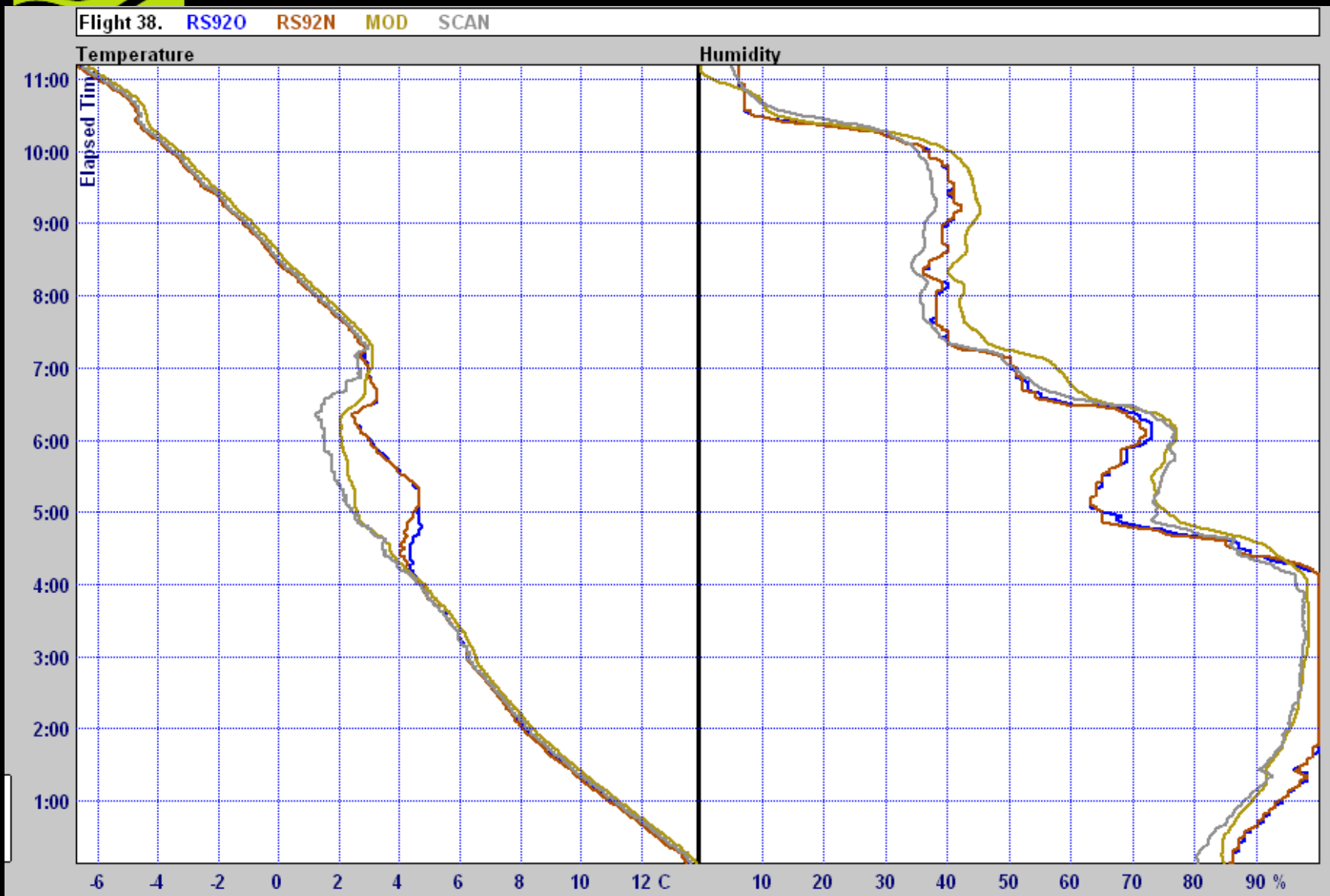
Flight 26. RS920 RS92N RAW0 RAWN MOD

Temperature





Evidence of humidity contamination in emerging from cloud



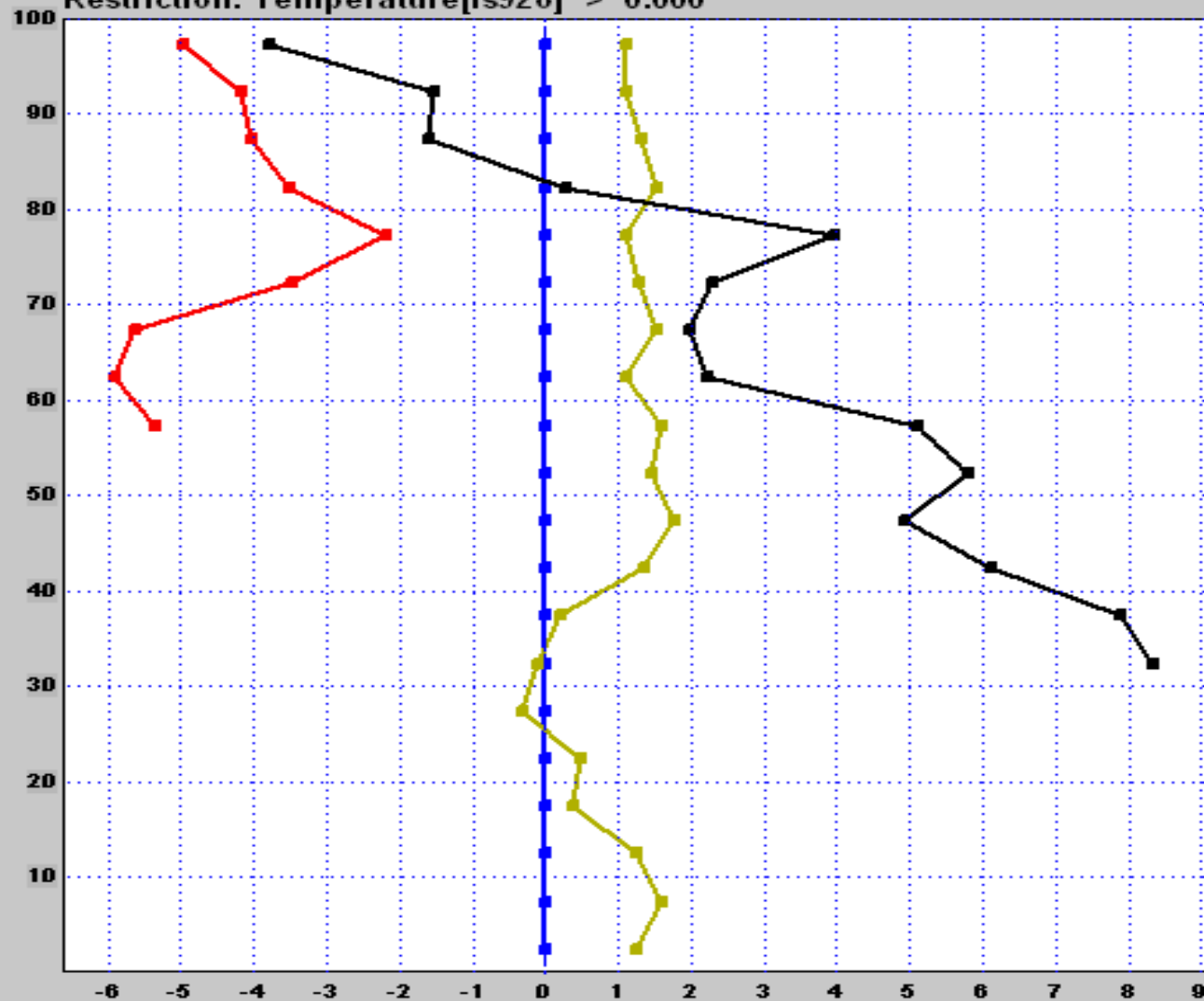


Direct Differences. RS920 RS92N MOD SCAN

Variable: Humidity. Data resolution: Time 1 sec. 26 flights. .

Restriction: Temperature[rs92o] > 0.000

Day



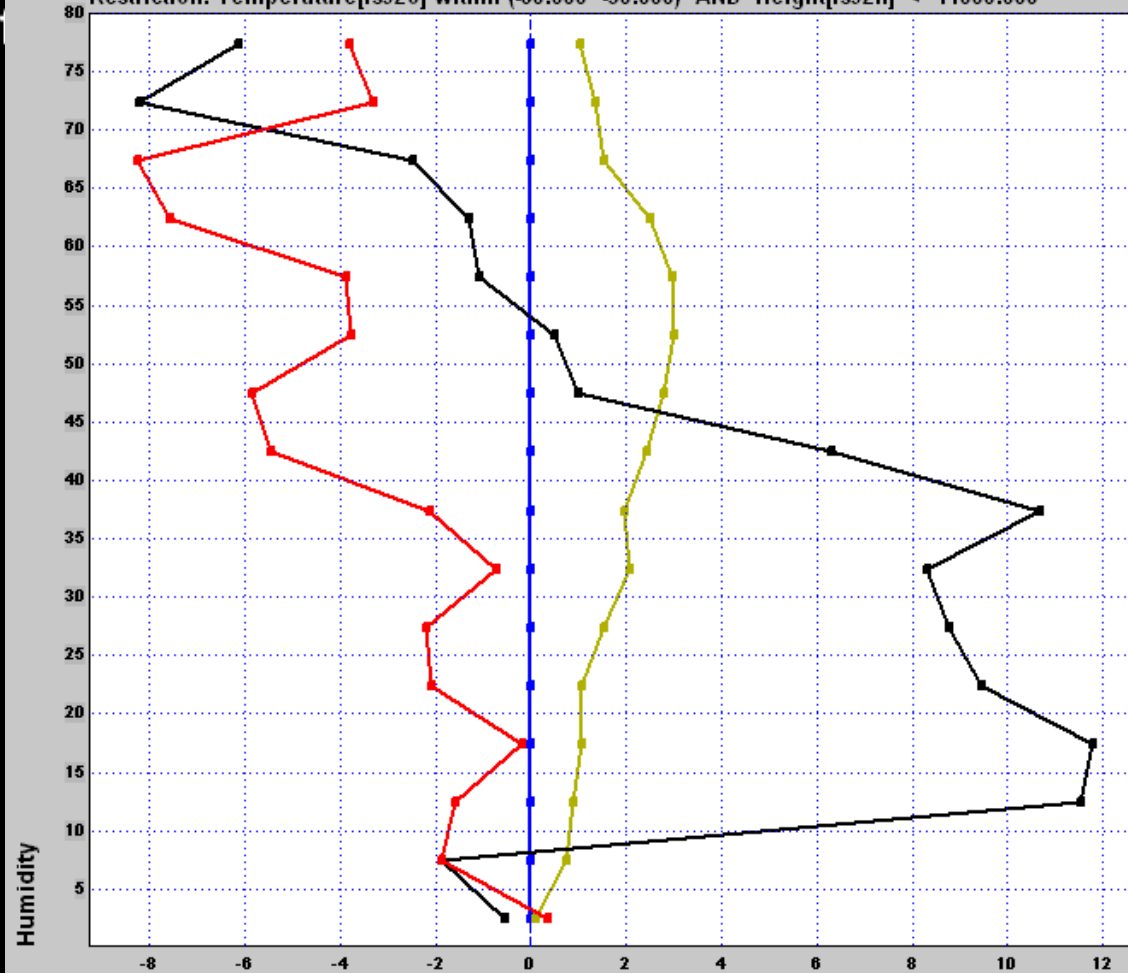
1754	1754	569	85
1845	1759	403	259
1670	1527	404	274
1429	1315	280	174
816	769	237	133
578	496	177	11
446	418	224	14
222	209	150	8
191	190	88	11
134	131	73	
65	65	24	
50	50	16	
48	48	17	
108	108	9	
100	100		
57	57		
56	56		
7	4		
122	106		
86	86		



Direct Differences. RS920 RS92N MOD SCAN

Variable: Humidity. Data resolution: Time 1 sec. 26 flights. .

Restriction: Temperature[rs92o] within (-60.000 -30.000) AND Height[rs92n] < 11000.000



Day

34	34	9	9
213	213	61	36
565	565	89	21
1497	1497	339	11
1365	1365	333	12
1582	1582	402	18
1572	1572	392	27
667	667	141	16
634	634	124	51
539	539	132	18
935	935	136	50
692	692	198	228
372	372	171	108
697	697	191	108
1844	1844	661	572
2361	2361	678	979

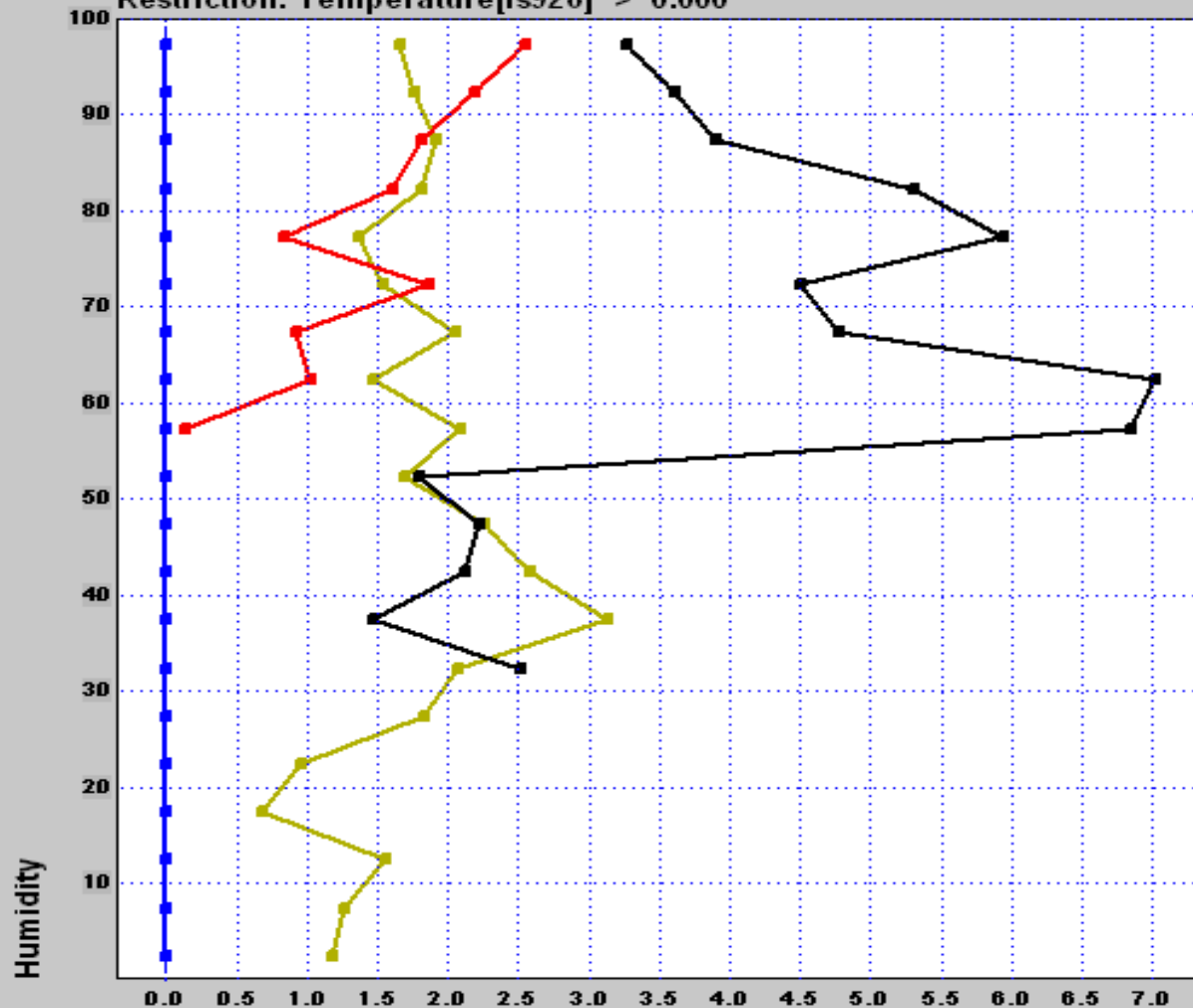


Met

Standard Deviations. RS920 RS92N MOD SCAN

Variable: Humidity. Data resolution: Time 1 sec. 26 flights. .

Restriction: Temperature[rs92o] > 0.000



1754	1754	569	85
1845	1759	403	259
1670	1527	404	274
1429	1315	280	174
816	769	237	133
578	496	177	11
446	418	224	14
222	209	150	8
191	190	88	11
134	131	73	
65	65	24	
50	50	16	
48	48	17	
108	108	9	
100	100		
57	57		
56	56		
7	4		
122	106		
86	86		

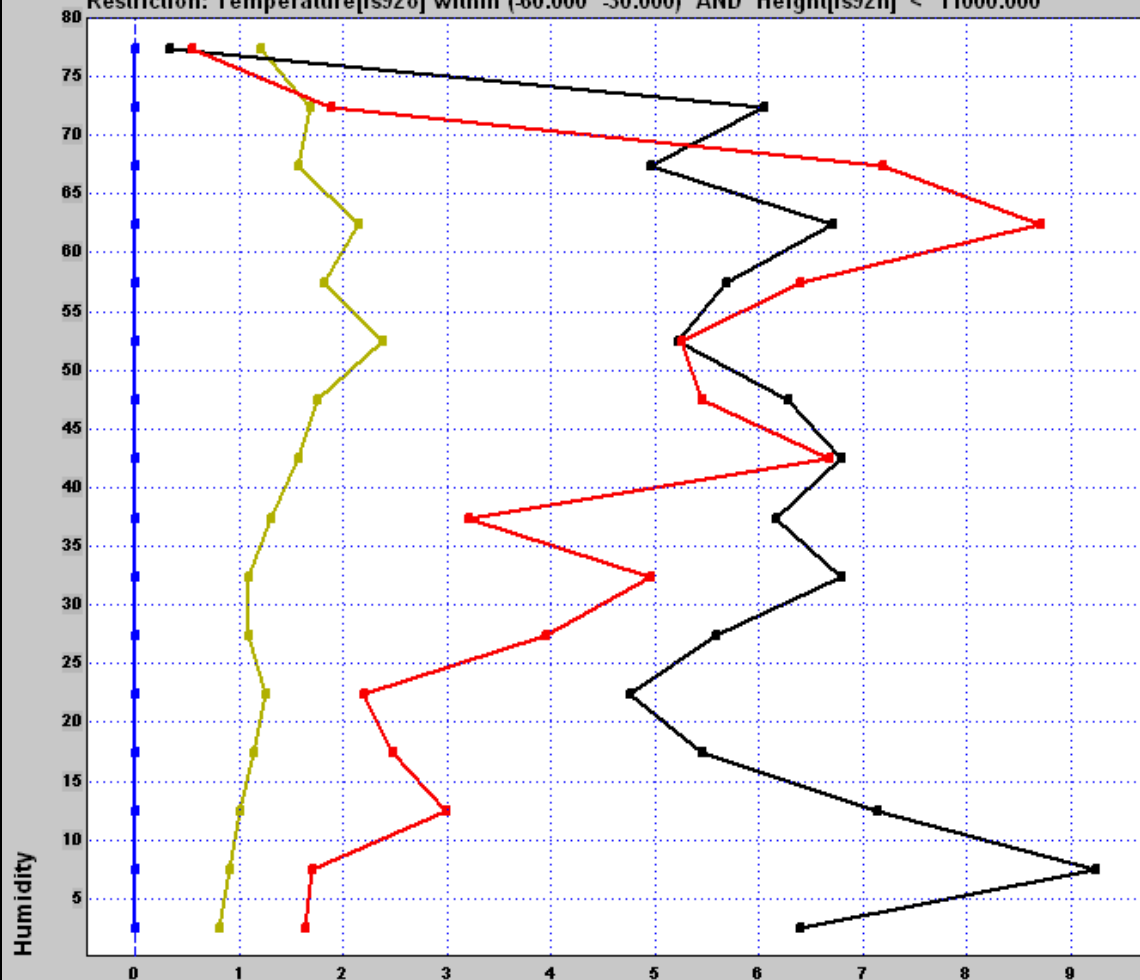


Met Office

Standard Deviations. RS920 RS92N MOD SCAN

Variable: Humidity. Data resolution: Time 1 sec. 26 flights. .

Restriction: Temperature[rs92o] within (-60.000 -30.000) AND Height[rs92n] < 11000.000



34	34	9	9
213	213	61	36
565	565	89	21
1497	1497	339	11
1365	1365	333	12
1582	1582	402	18
1572	1572	392	27
667	667	141	16
634	634	124	51
539	539	132	18
935	935	136	50
692	692	198	228
372	372	171	108
697	697	191	108
1844	1844	661	572
2361	2361	678	979

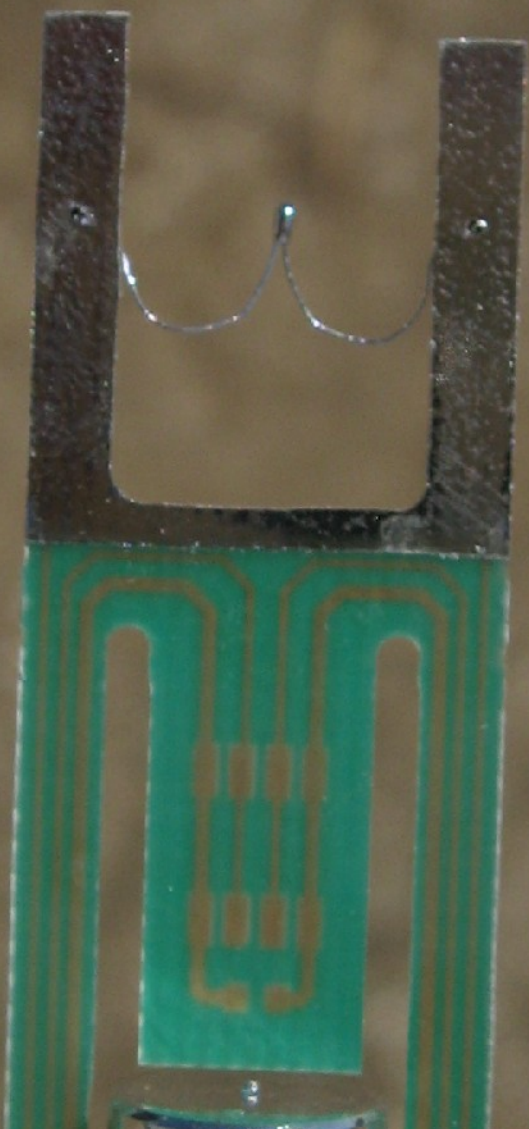


MODEL

BAT-16G 1680MHz

NSN		Mass
P/N	4507000600	220g
S/N	45079663	
Manufactured	10/2007	
Batt. Expiry	2013	

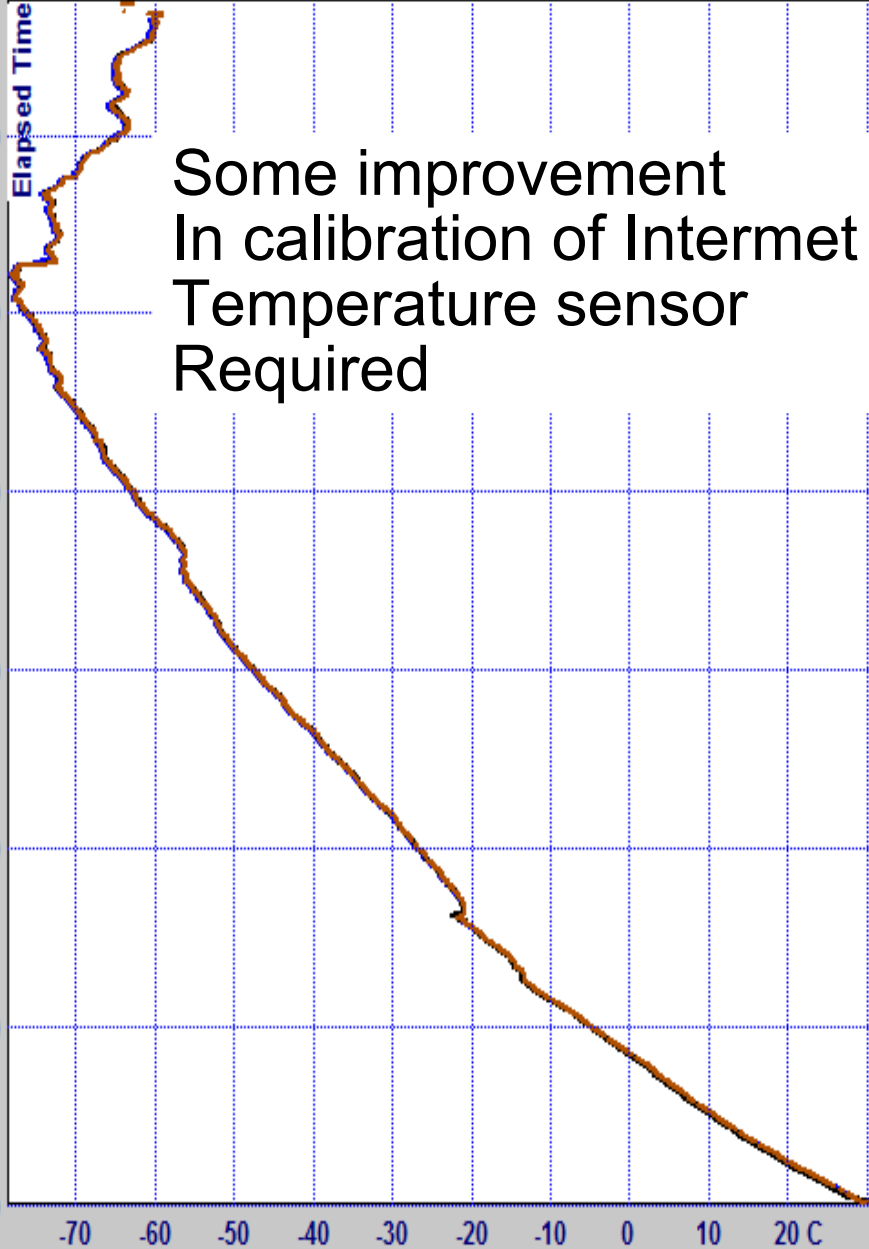
A WEATHER-RESISTANT
METEOROLOGICAL
RADAR
THIS UNIT IS A
MATERIAL



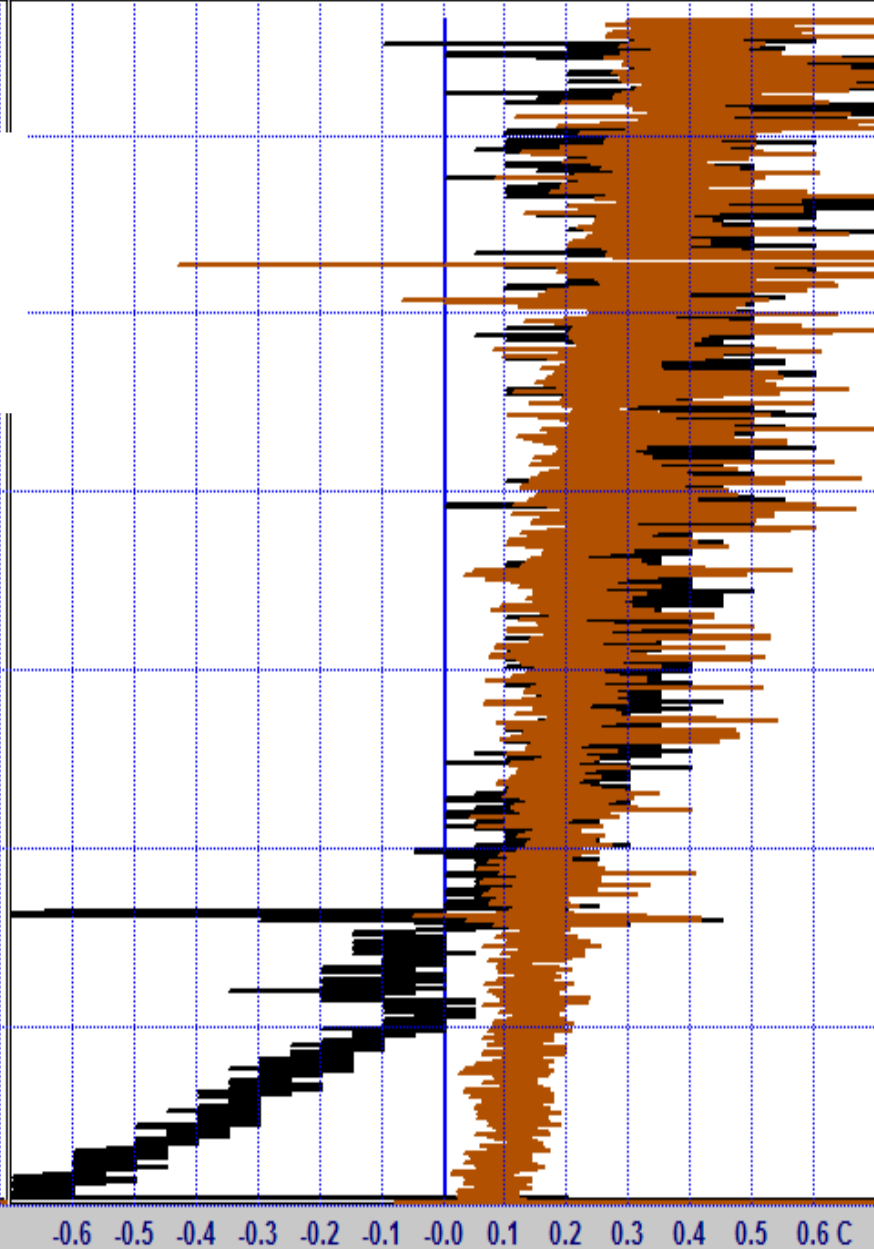




Temperature

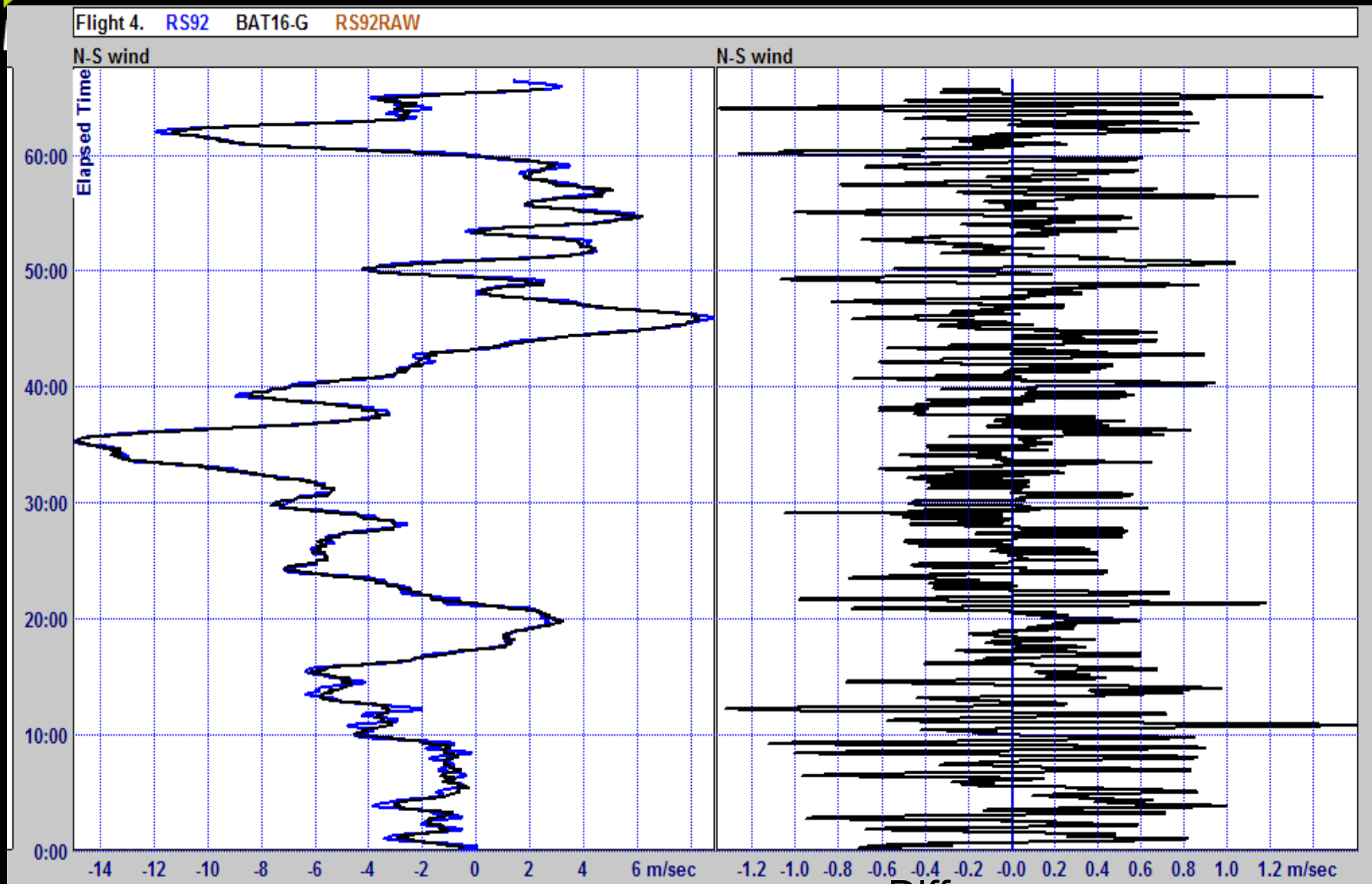


Temperature





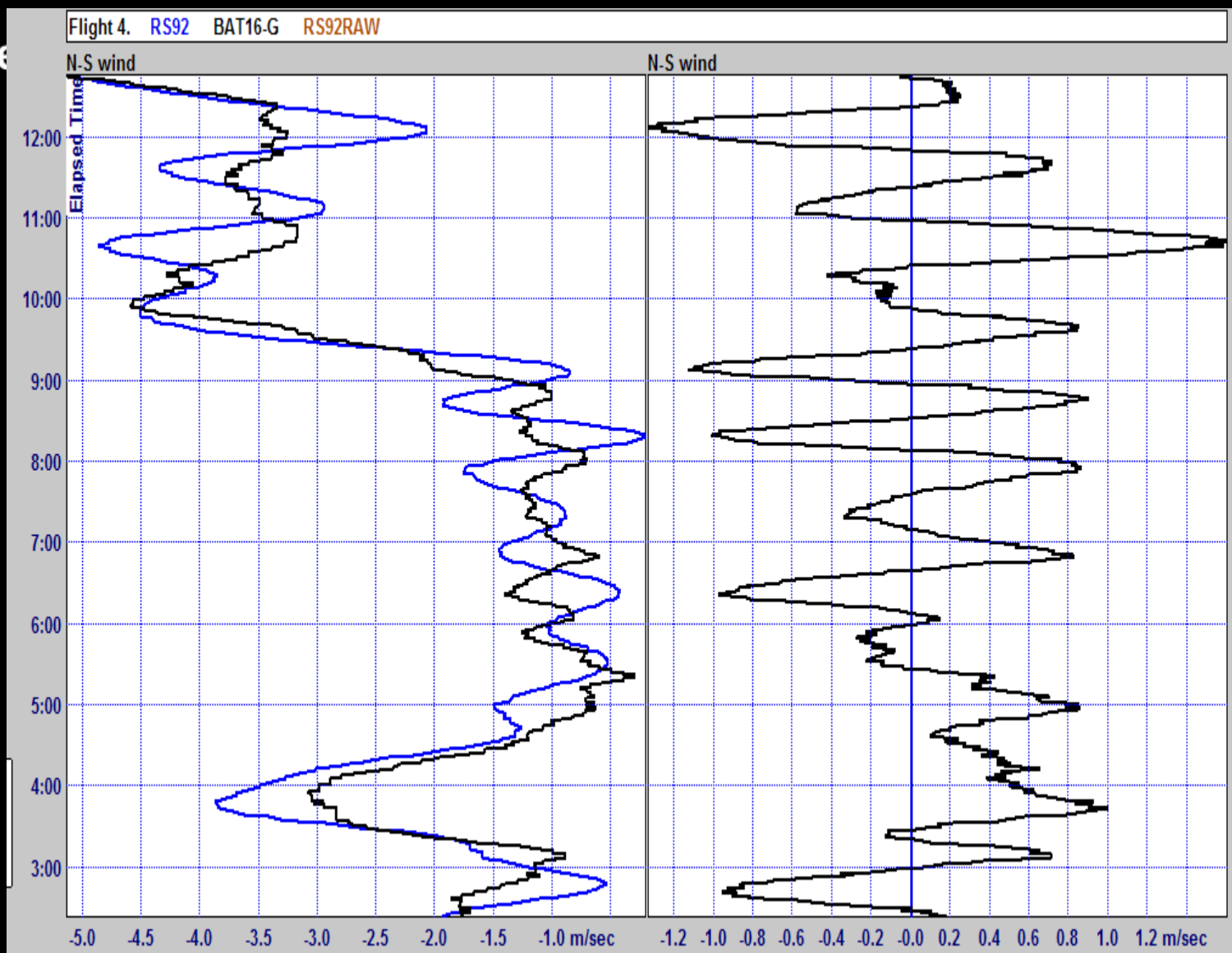
GPS winds usually reliable



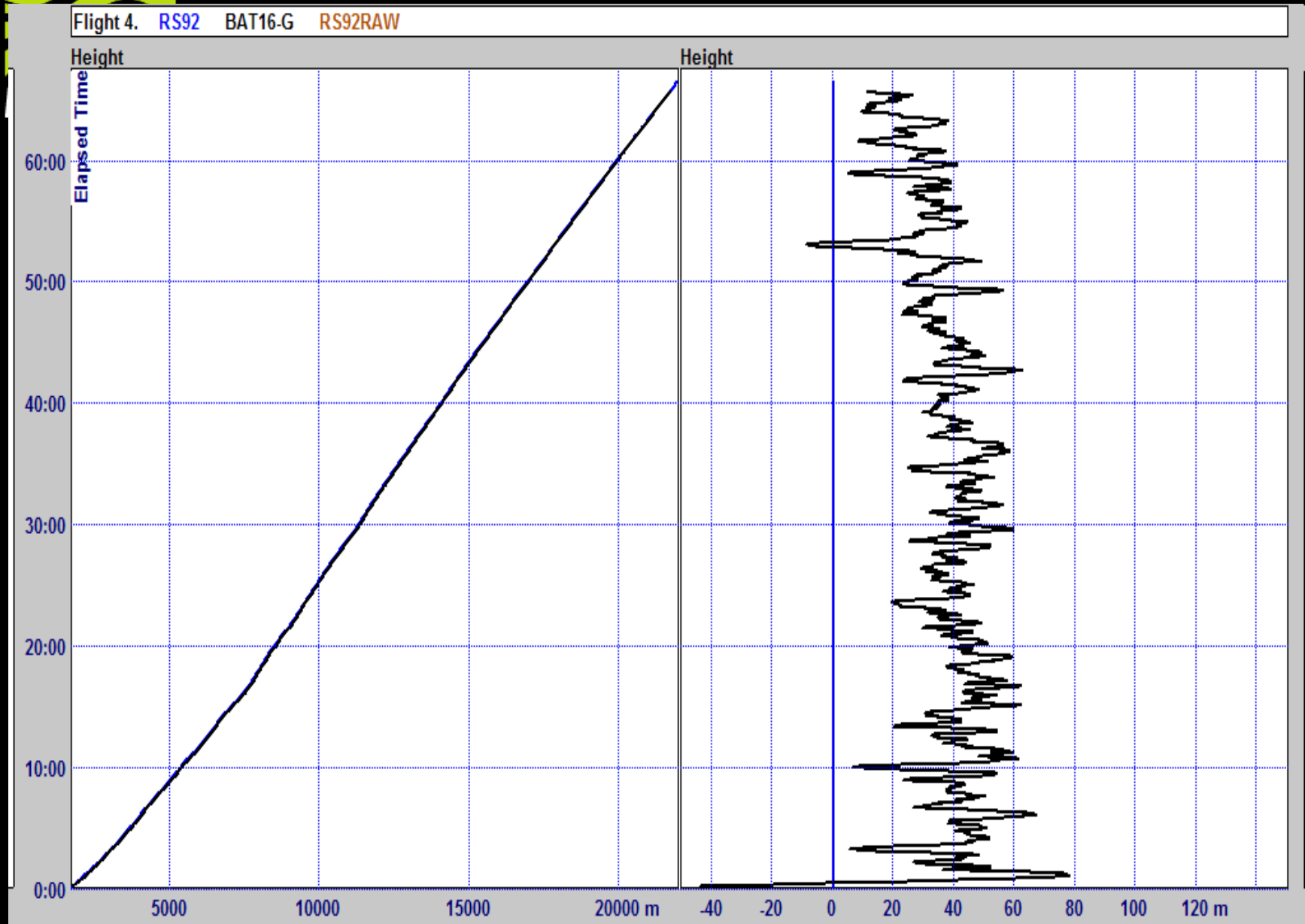


Met Office

Differences in wind often caused by differences in filtering of GPS winds to get rid of pendulum under balloon



GPS heights should be very reproducible, 5 to 10 m





Summary

- Examples of testing newly developed radiosonde systems are shown
- Measurement quality achievable now is much higher than even 5 years ago.
- Can India benefit from bilateral or regional collaboration in developing new radiosondes?