

ARM Sites Report

ARM Sites Update

ARM Facility Reconfiguration - Doug Sisterson

MAWS at all ARM Sites - Donna Holdridge

RS41-RS92 comparison at SGP – Donna Holdridge

CFH launches at SGP – Martin Stuefer

Lidar Operations at ARM Sites – Rob Newsom

ARM Climate Research Facility Update

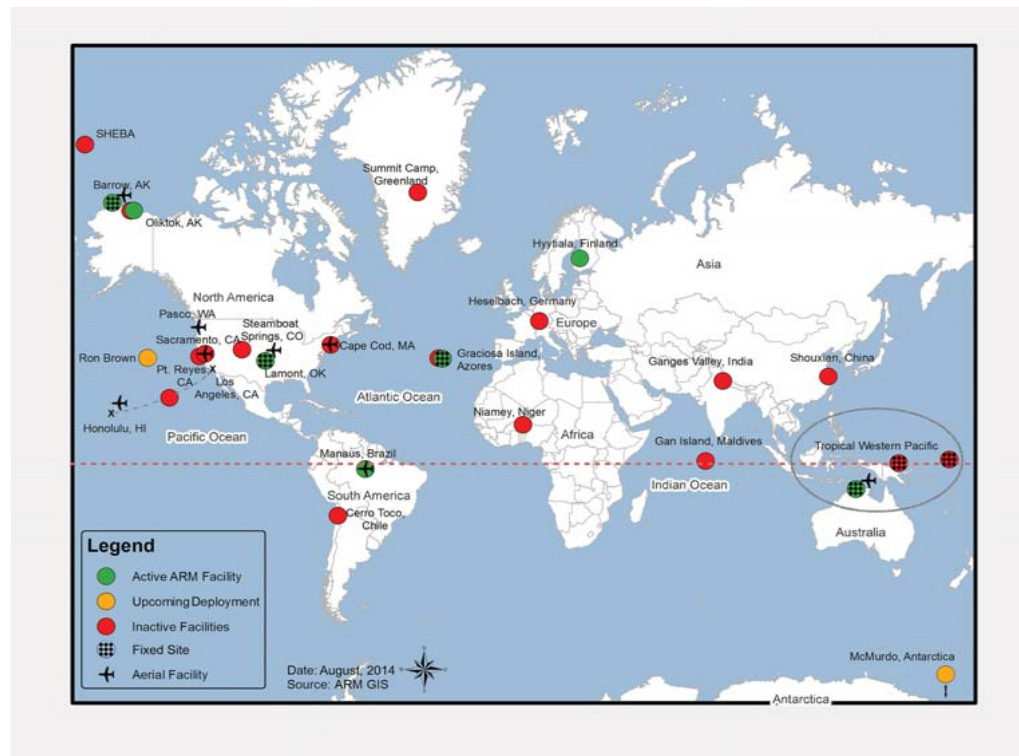
Mission

The ARM Climate Research Facility, a US DOE scientific user facility, provides the climate research community with strategically located in situ and remote sensing observatories designed to improve the understanding and representation, in climate and earth system models, of clouds and aerosols as well as their interactions and coupling with the Earth's surface.

Vision

To provide a detailed and accurate description of the earth atmosphere in diverse climate regimes to resolve the uncertainties in climate and earth system models toward the development of sustainable solutions for the Nation's energy and environmental challenges.

Doug Sisterson (dlsisterson@anl.gov)
ARM Instruments Coordinator
Environmental Science Division
Argonne National Laboratory



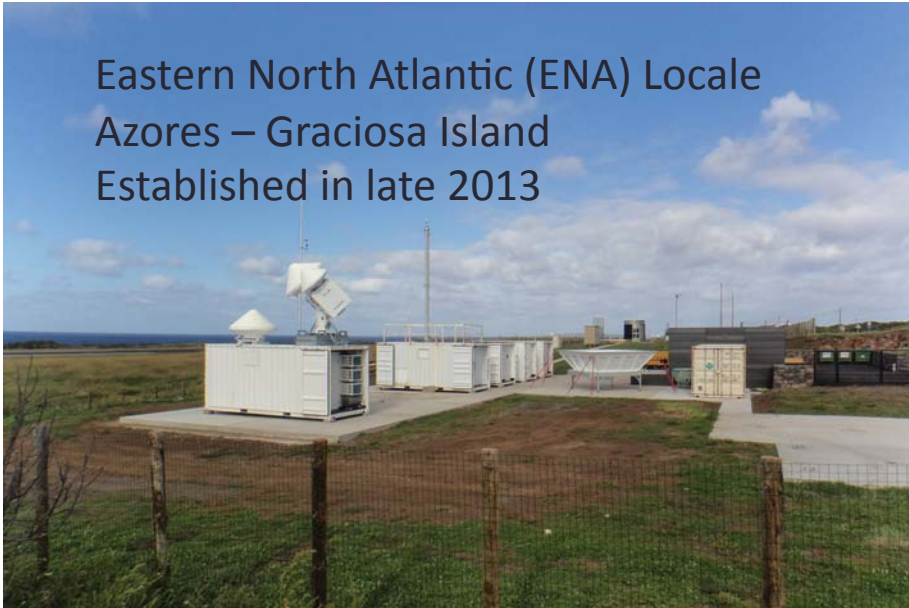
ARM Instrument Mentors

ARM contracts ~50 Instrument Mentors to oversee the operation, documentation, training of local site operations personnel, calibration, and data quality of all the ARM Facility Instruments

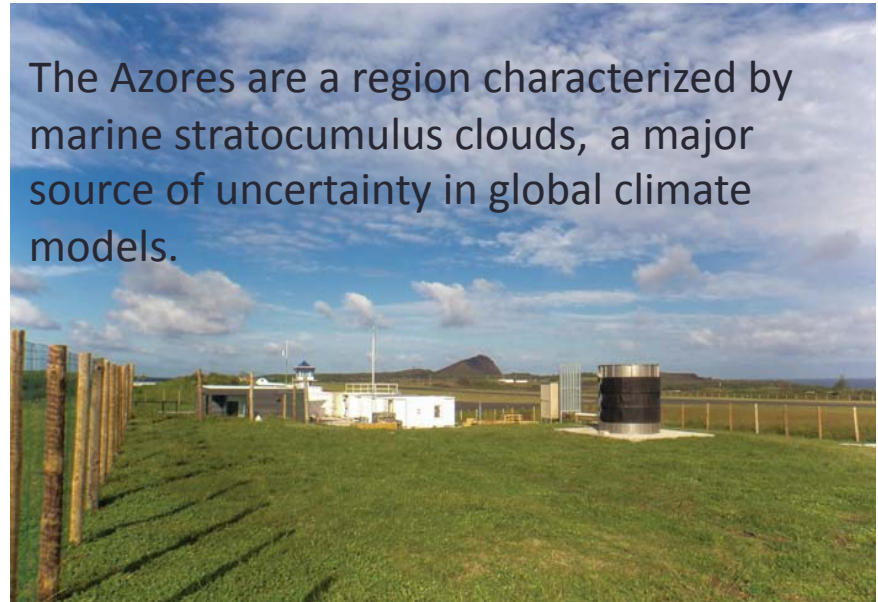
- more than 325 individual instruments
- representing nearly 3,000 total data streams
- representing up to ~1 TB of data per day

ARM Three Fixed Sites - ENA

Eastern North Atlantic (ENA) Locale
Azores – Graciosa Island
Established in late 2013



The Azores are a region characterized by marine stratocumulus clouds, a major source of uncertainty in global climate models.



Aerosol instrumentation: Humidified Tandem Differential Mobility Analyzer, Aerosol Chemical Speciation Mass Spectrometer, Cavity Attenuated Phase Shift Particle Extinction Monitor, CO/N₂O/H₂O gas-phase monitor, CO₂/CH₄/H₂O gas phase monitor, and Ultra-High Sensitivity Aerosol Spectrometer

Atmospheric and boundary state systems: surface meteorological instrumentation, boundary layer cloud system, total sky imager, weighing bucket rain gauge, total precipitation sensor, eddy correlation flux measurement system, and disdrometer

Lidars: micropulse lidar and Doppler lidar

Radars: zenith cloud radar, scanning cloud radar, scanning precipitation radar, and radar wind profiler

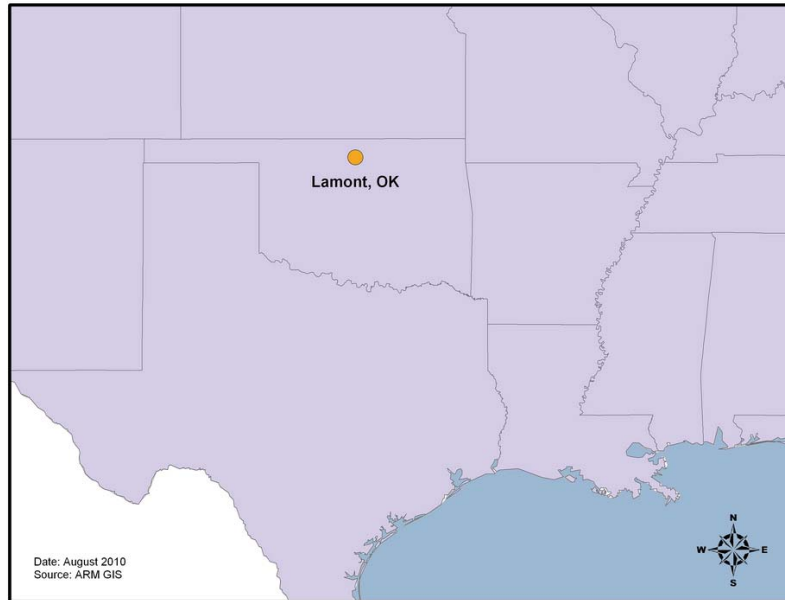
Radiometers: atmospheric emitted radiance interferometer, microwave radiometer, 3-channel microwave radiometer, multifilter rotating shadowband radiometer, pyranometer, pyroheliometer, pyrgeometer, and blackbody calibration system.

ARM Three Fixed Sites - NSA



Instrument systems at NSA include solar and infrared broadband radiometric instruments, a Fourier transform infrared radiometer, cloud lidars and radars, a radar wind profiler, a radiosonde system, a sky imager, and a microwave radiometers. Recent additions include three new dual-frequency scanning cloud radars that provide three- dimensional information about cloud properties, an eddy correlation (ECOR) flux measurement system and complementary surface energy balance system (SEBS); high spectral resolution lidar; and a launching system for automated release of weather balloons.

ARM Three Fixed Sites –SGP

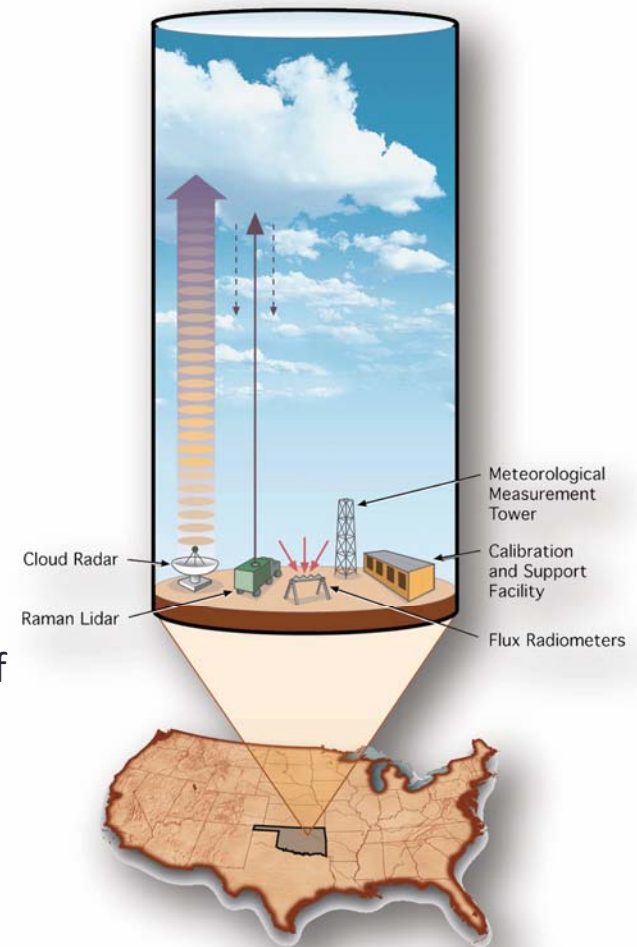


Southern Great Plains (SGP) Locale

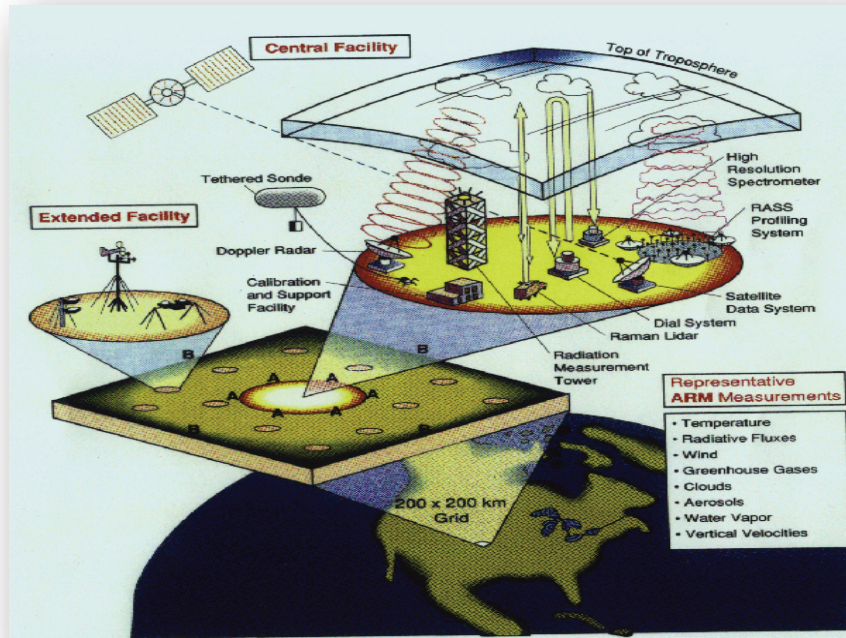
The SGP Site is a study area that consists of ~25-30 in-situ and remote-sensing instrument clusters arrayed across approximately 143,000 square kilometers in north-central Oklahoma.

The SGP: Flagship for ARM

- SGP site: first field measurement site established by DOE's ARM Program (1992-1995)
- Largest site: *in situ* and remote-sensing instrument clusters arrayed across approximately originally 143,000 square kilometers in north-central Oklahoma and south-central Kansas
- Largest of the ARM facility fixed sites
- Heart of the SGP site: most heavily instrumented central facility, on 160 acres southeast of Lamont, Oklahoma
- Subcontracted staff of 30 technicians ensure the operation, calibration, and maintenance of instruments and collection of data from the central facility instruments and from smaller, unstaffed facilities throughout the site



SGP Site History 1992-2010



- Initial layout configured to challenge global climate model (GCM) and other climate models
- Focused on improving radiation transfer under clear skies at the global scale

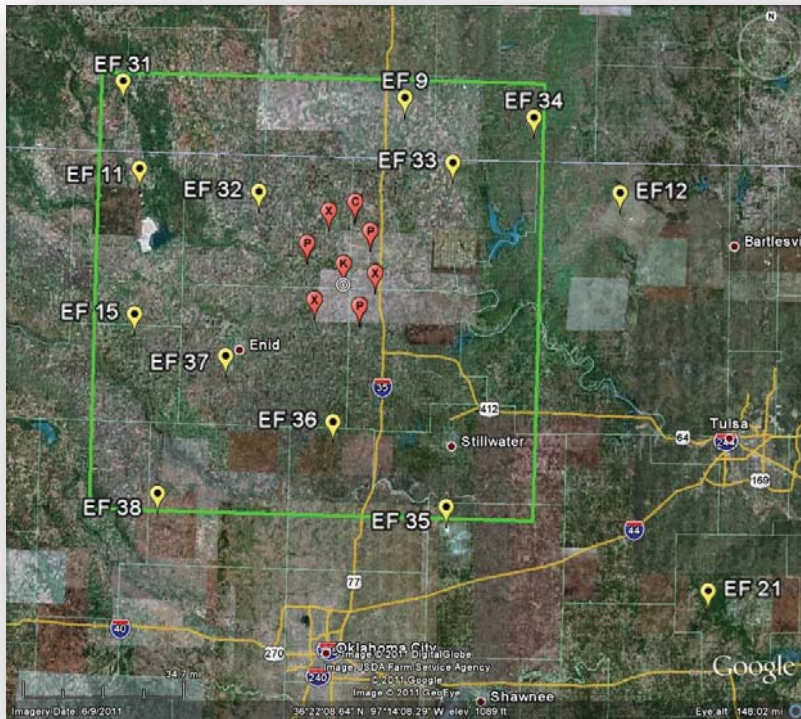
1992–2010: SGP study area established; measured 325 by 275 km



SGP Site Reconfiguration 2010

From Soda Straw to 4D

Improved models were used to reconfigure SGP footprint, combine instrumentation in 3-D spatial arrays to continue to challenge GCM and climate models at finer grid scales; changes focusing on improving cloud and aerosol parameterizations at the regional scale

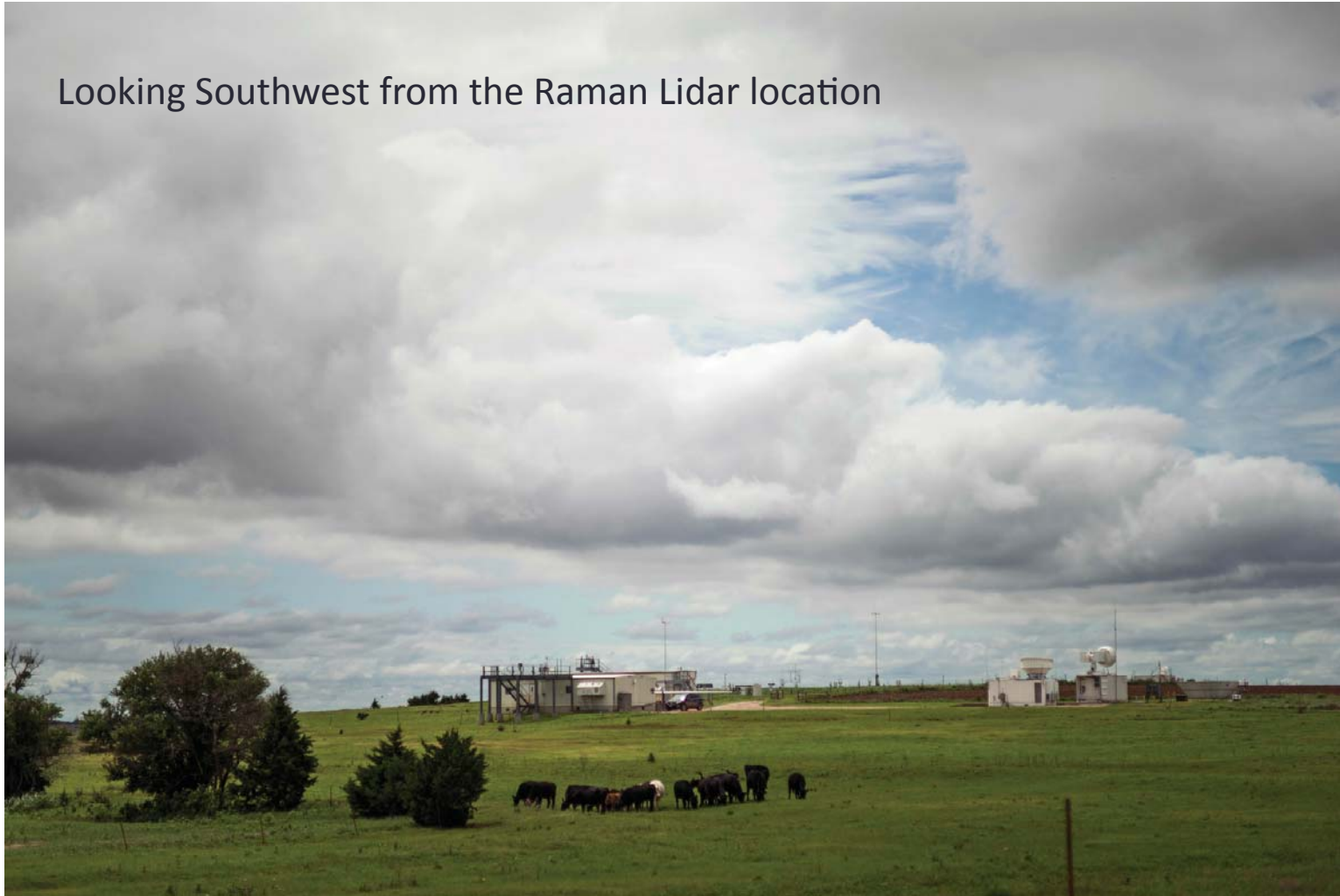


2010–2013 SGP study area was reconfigured to 150 by 150 km



The SGP Central Facility

Looking Southwest from the Raman Lidar location



The SGP Central Facility

Looking WNW from the Optical Trailer



Looking E from the Aerosol Trailer



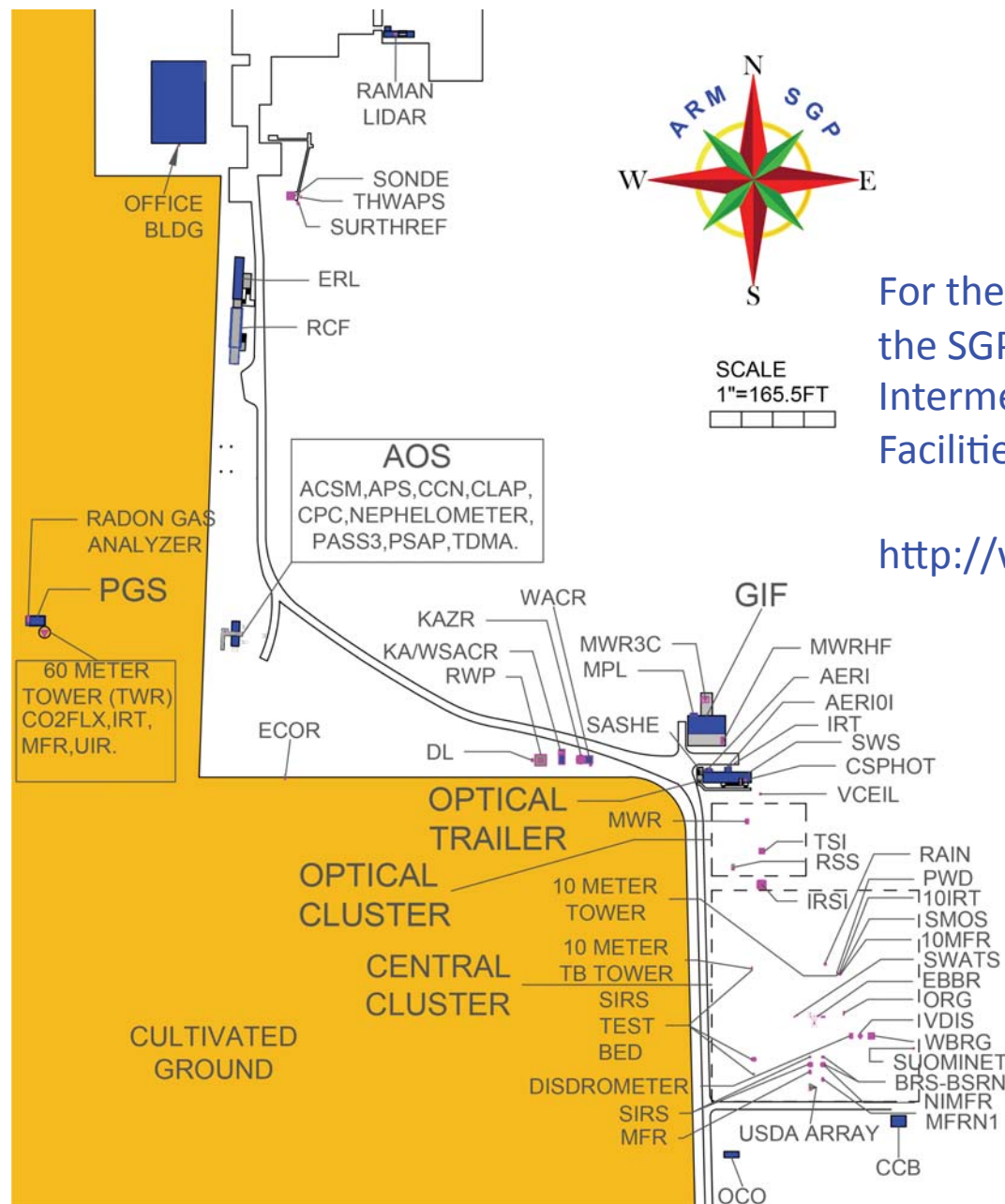
Looking N from the Eddy Correlation location.



Looking S from the Optical Trailer



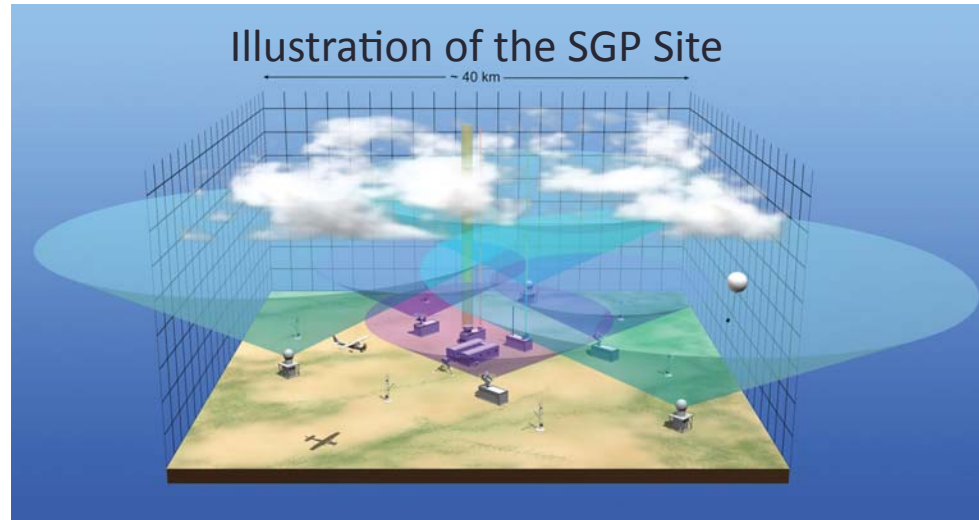
The SGP Central Facility Layout



For the most current list of instruments at the SGP Central Facility, Intermediate Facilities, and Extended Facilities, please go to:

<http://www.arm.gov/sites/sgp/instruments>

The ARM Future - 2015 and Beyond



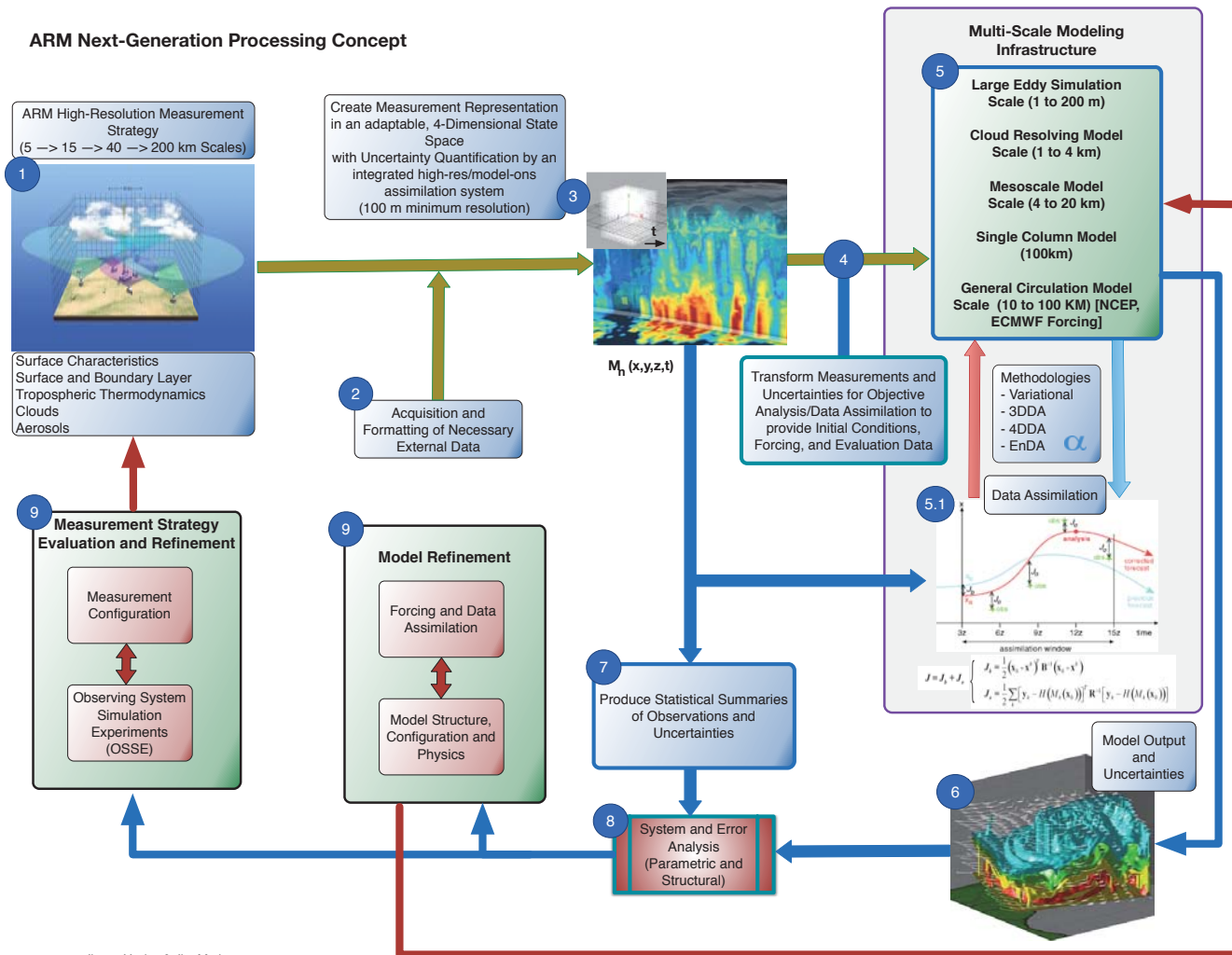
The ARM Facility is now embarking on a reconfiguration strategy for even better observations of atmospheric processes to constrain high-resolution process models. Key elements of the new strategy include the creation of two "super sites" in the United States.

Southern Great Plains – measurements at the SGP Site will be augmented to include additional scanning and profiling remote sensors and more detailed measurements of the land-atmosphere interface that support high resolution climate modeling.

North Slope of Alaska – aerial operations will link the measurements from Barrow and Oliktok, and unmanned aerial systems will provide additional spatial information around Oliktok.

From Observations to Models

ARM Next-Generation Processing Concept



Summary

- The TWP fixed sites (Manus Island, PNG; Nauru; and Darwin, AUS) were decommissioned in 2014
- The ENA (Azores, Graciosa Island) fixed site was implemented in 2013
- The NSA (Barrow) is still a fixed site with the addition of the Oliktok mobile facility for long-term deployment with routine manned and unmanned aircraft flights being planned between the two sites
- The SGP will have a dense array of significantly more instrument clusters, but the Central Site in Lamont will not be changed.

MAWS Upgrade to ARM DigiCORA Systems

Donna Holdridge, Argonne National Laboratory
Jenni Kyrouac, Argonne National Laboratory

Presented at
GRUAN-ICM7 Meeting
23-27 Feb 2015
Matera, Italy

Surface Measurement Configuration

ARM Southern Great Plains Site

Site	Deployed	T/RH	Pressure	Winds
SGP	04/1998 - 09/2005 THWAPS	Vaisala Model HMP233 Series Transmitter	Vaisala Model PTB201A Digital Barometer	R.M. Young Model 05103 Wind Monitor
	09/2005 – 09/2014 THWAPS SURTHREF	<u>SURTHREF</u> Average of 6 probes: 3 - Vaisala HMP-45D T/RH probes 3 - Rotronic MP100H T/RH probes	Vaisala Model PTB201A Digital Barometer	R.M. Young Model 05103 Wind Monitor
	09/2014 – present MAWS301	Vaisala Model HMP155 T/RH Probe	Vaisala Model PTB330 Digital Barometer	Vaisala Model WMT700 Ultrasonic Wind Sensor



Surface Measurement Configuration

North Slope of Alaska Barrow Site

Site	Deployed	T/RH	Pressure	Winds
NSA	03/1998 – 09/2008	Vaisala Model HMP45D T/RH Probe	Vaisala Model PTB201A Digital Barometer	Vaisala Model WAA251 Anemometer Vaisala Model WAV151 Wind Vane
	09/2008 - Present	Vaisala Model HMT337 T/RH Probe	Vaisala Model PTB220 Digital Barometer	Vaisala Model WS425 Ultrasonic Wind Sensor
NSA Autosonde	06/2009 - Present MAWS	Vaisala Model HMP155 T/RH Probe	Vaisala Model PTB220 Digital Barometer	Vaisala Model WS425 Ultrasonic Wind Sensor



Surface Measurement Configuration

ARM Tropical Western Pacific Sites (*decommissioned)

ARM Eastern North Atlantic Site

Site	Deployed	T/RH	Pressure	Winds
TWP*	08/1996 – 12/2011	BOM AWS	BOM AWS	BOM AWS
	12/2011 – 06/2014	Vaisala Model HMP45D T/RH Probe	Vaisala Model PTB220 Digital Barometer	R.M. Young Model 05106 Wind Monitor

Site	Deployed	T/RH	Pressure	Winds
ENA	10/2013 - Present	Vaisala Model HMP155 T/RH Probe	Vaisala Model PTB330 Digital Barometer	R.M. Young Model 05106C Wind Monitor



Surface Measurement Configuration

ARM Mobile Facility Sites

Site	Deployed	T/RH	Pressure	Winds
AMF1	02/2005 - Present	Vaisala Model HMP45D T/RH Probe	Vaisala Model PTB220 Digital Barometer	R.M. Young Model 05106 Wind Monitor

Site	Deployed	T/RH	Pressure	Winds
AMF2	10/2010 - Present	Vaisala Model HMP155 T/RH Probe	Vaisala Model PTB330 Digital Barometer	Vaisala Model WS425 Ultrasonic Wind Sensor

Site	Deployed	T/RH	Pressure	Winds
AMF3	09/2013 - Present	Vaisala Model HMP337 T/RH Probe	Vaisala Model PTB330 Digital Barometer	Vaisala Model WS425 Ultrasonic Wind Sensor



Vaisala MAWS301

Automated Weather Station - Summary

- To standardize all sonde surface measurements
- To remove operator error
- Vaisala MAWS301 systems acquired for all ARM sites
- Simple interface with DigiCORA
- Automatically provides surface measurements within GUI
- WMT700, HMP155, PTB330, QML201 Datalogger
- Currently, only SGP has been upgraded
- The rest of the MAWS are planned to be installed this year and next year.



Comparison of Vaisala Radiosondes RS41 and RS92 at the Southern Great Plains Site

Michael Jensen, Brookhaven National Laboratory

Donna Holdridge, Argonne National Laboratory

Petteri Survo, Vaisala, Oyj

Raisa Lehtinen, Vaisala, Oyj

Presented at
GRUAN-ICM7 Meeting
23-27 Feb 2015
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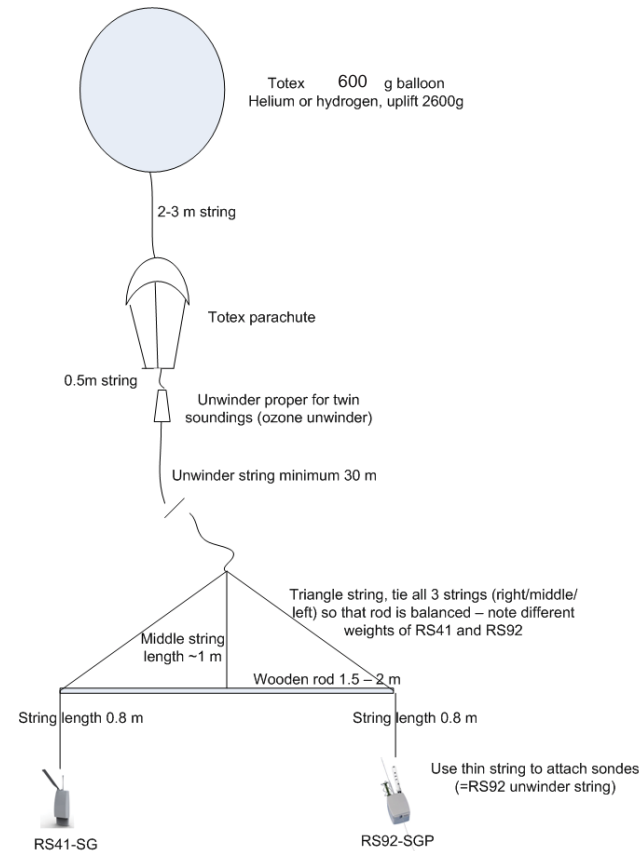
Overview of Launches

- June 3 – 7, 2014
- ARM Southern Great Plains Site Lamont, Oklahoma
- 20 comparison launches; 14 daytime, 6 nighttime



Launch Configuration

- MW31 and MW41 systems
- Shared one antenna set-up
- 600g balloons
- Totex parachutes
- Ozone Unwinder – 30m
- Wooden Rigging
- 20 launches of RS92/RS41 pairs

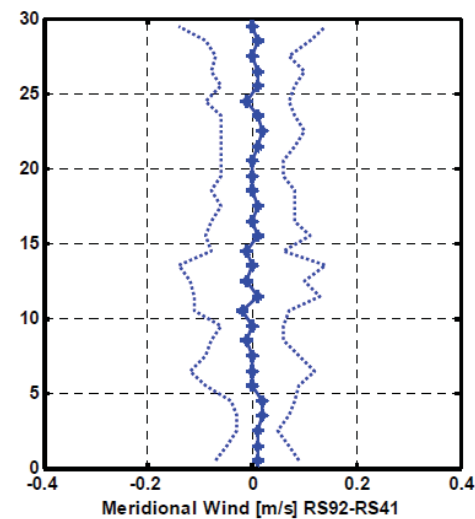
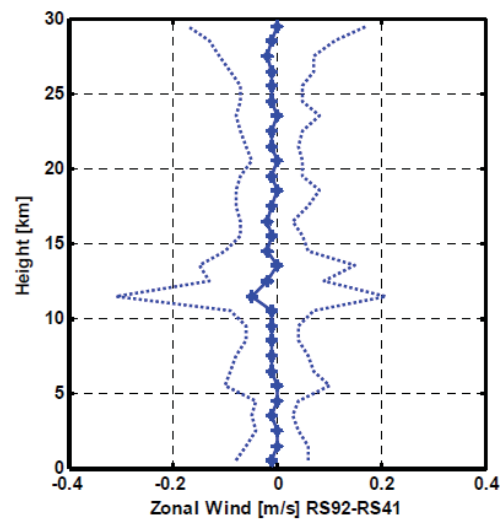
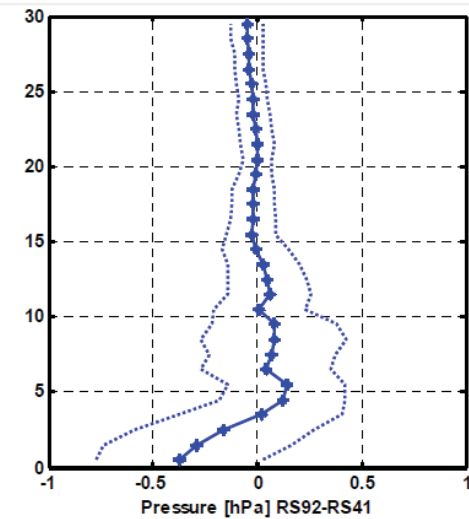
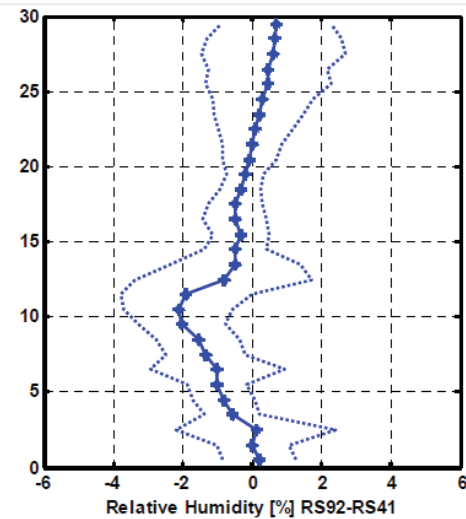
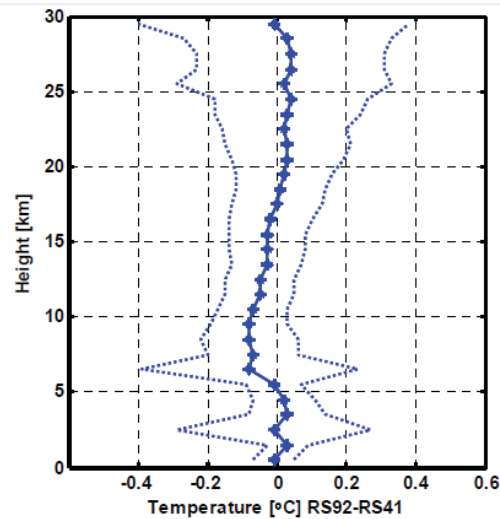


Launch Configuration



Images: Petteri Survo and
Michael Jensen

Preliminary Results



Plots: Raisa Lehtinen

Preliminary Results cont.

- Mean **temperature** differences were within ± 0.1 °C. There were a few cases with larger differences, typically related to challenging conditions such as the radiosondes emerging from a cloud, or large gradients in the profiles.
- Mean **humidity** profiles agreed to within $\pm 2.1\%$ RH. The largest differences were observed at altitudes of 8 to 12 km, with RS92 measuring 1.6 – 2.1% RH lower humidity levels.
- Mean **pressure** differences were within ± 0.2 hPa in altitudes above 2 km. Near-ground mean difference between RS41 and RS92 was 0.4 hPa.
- Zonal and meridional **wind** components were within ± 0.05 m/s, with standard deviation of differences within 0.26 m/s.



Conclusions

- The RS41 and RS92 radiosondes showed very similar results for all measured quantities.
- The observed differences between RS41 and RS92 are within the measurement uncertainty for all variables, and similar to those reported from previous campaigns arranged by UK MET Office and Czech Hydrometeorological Institute.
- Other ARM instrumentation measurements are being used to interpret results.
- The complete technical report should be completed in the next few months.
- The ARM Program is planning to move forward with acquisition of the MW41 upgrade, but the transition plan from RS41 to RS92 sondes has not yet been developed.



CFH Launches at ARM Southern Great Planes Site at Lamont, Oklahoma

Martin Stuefer, University of Alaska Fairbanks, CFH mentor

Donna Holdridge, ARM – Argonne National Laboratory

Jenni Kyrouac, ARM - Argonne National Laboratory

Doug Sisterson, ARM - Argonne National Laboratory

Howard Diamond, NOAA



ARM CFH Mission / Facts

- **P**rovide long-term quality and well documented CFH measurement data.
- **O**ne CFH sounding per month.
- **H**oward Diamond, through NOAA funds CFH launch hardware.
- **A**RM provides mentorship oversight and ‘manpower’ for the efforts associated with the CFH sonde preparation and launches.
- **I**mprove and evaluate the procedures for CFH launches at the SGP facility.
- **E**valuate CFH launch logistics for use at other ARM launch sites (i.e. Barrow, Alaska) in the future.



Site location and Launch history



- Lamont, OK, 36°36'18.0" N, 97°29'6.0" W, 320 m a.s.l.
- Launch procedures from GRUAN Lead Center
- Three launches so far:
 - Sept. 11, 2014
 - Nov. 24, 2014
 - Feb. 12, 2015
- CFH are checked and adjusted with CFH setup
- Launches will be performed monthly



Launch package

- Cryogenic Frostpoint Hygrometer from Droplet Measurement Technologies (DMT)
- InterMet IMet1 RSB
- Vaisala RS92 radiosonde

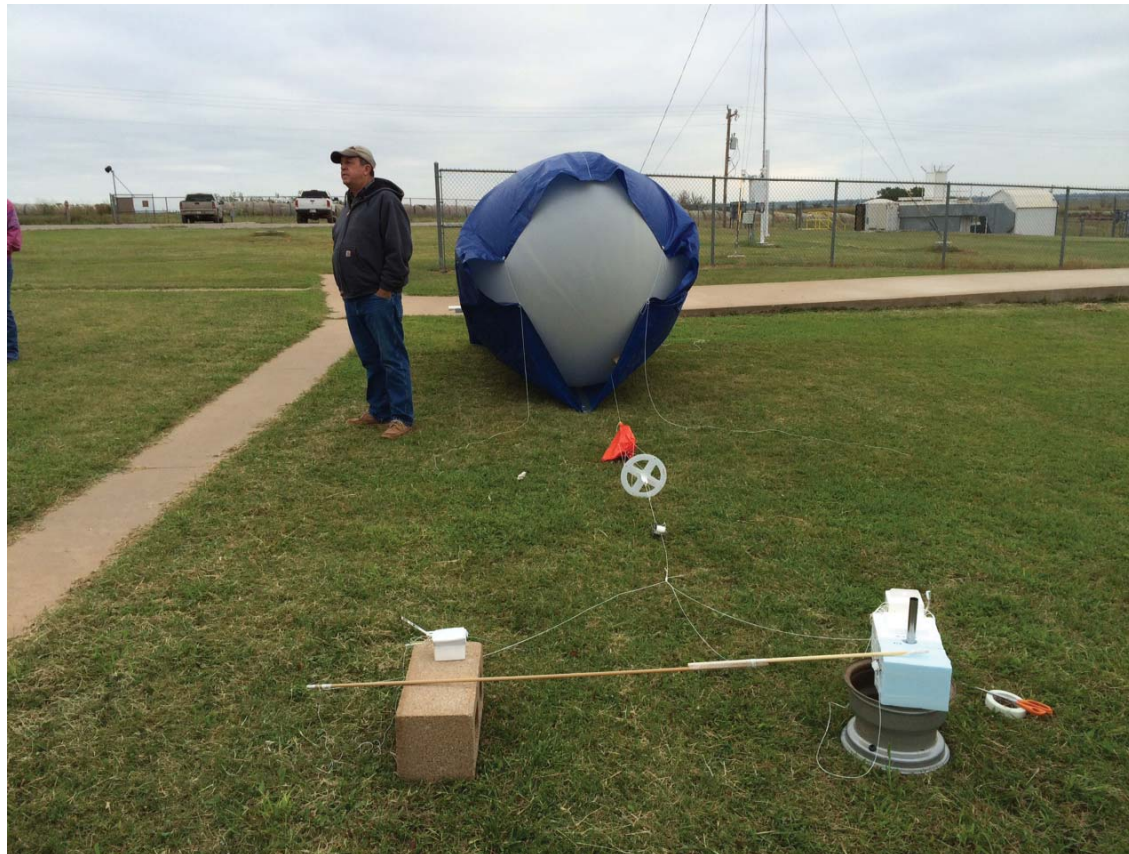


Photo courtesy: Donna Holdridge



RS92 calibration

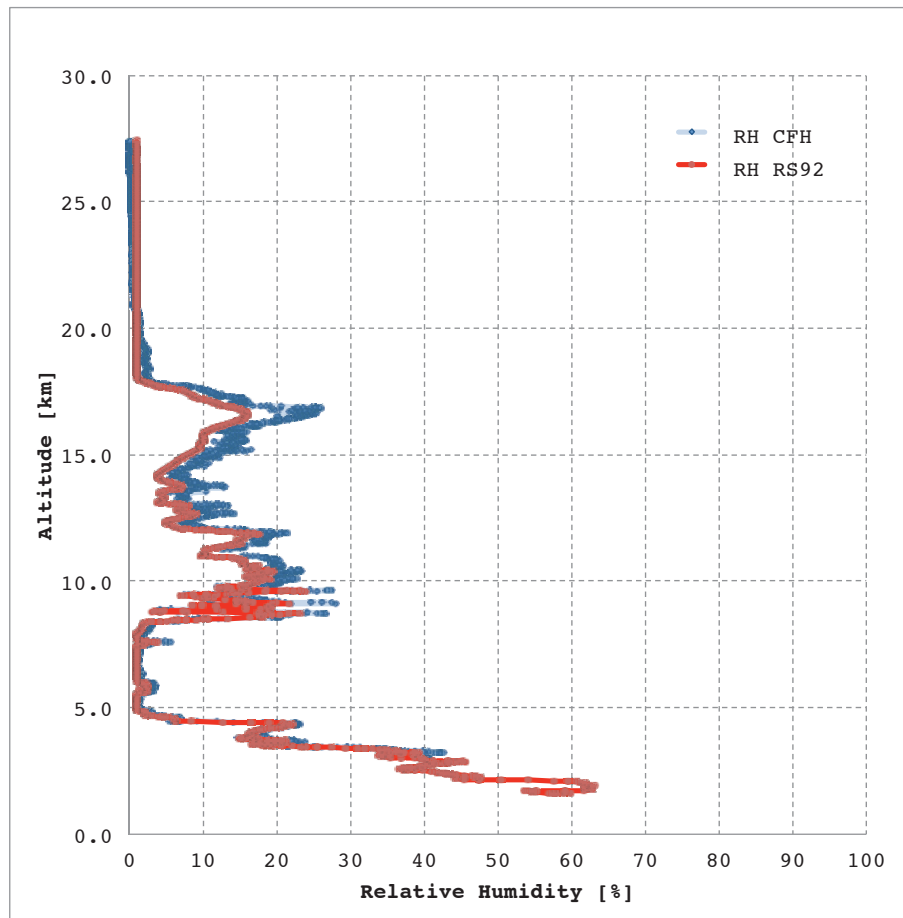
- Factory
- Ground check with Vaisala GC25 prior to each launch



Photo courtesy: Donna Holdridge



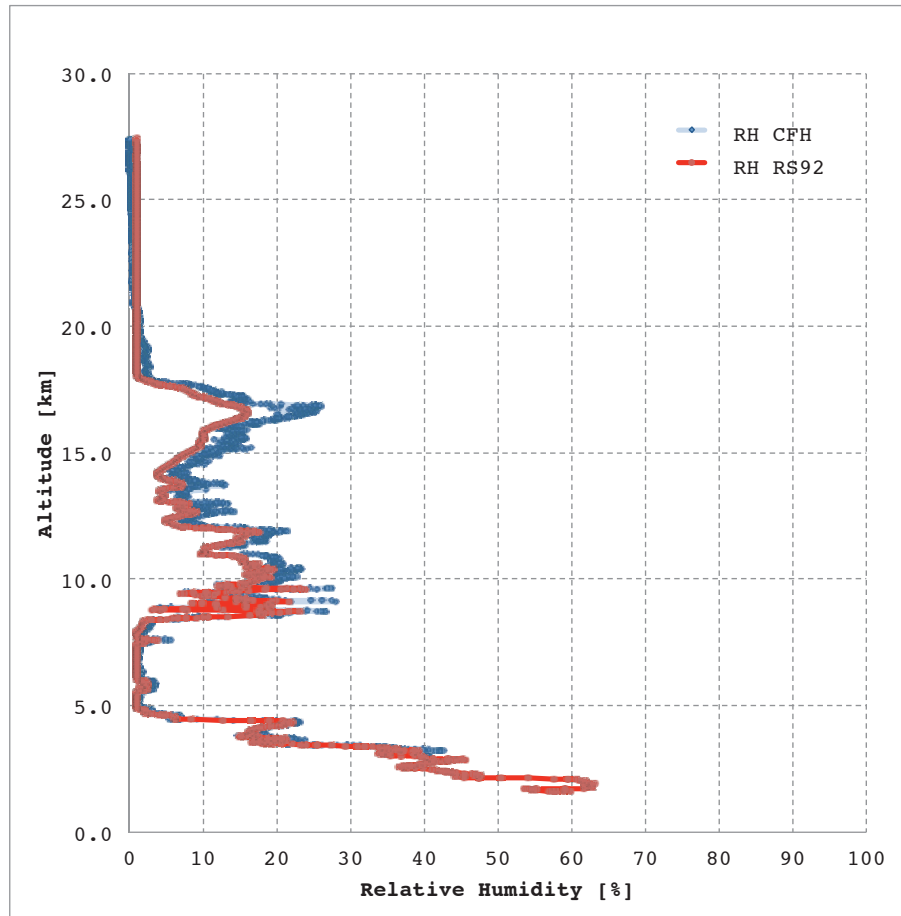
RH Example



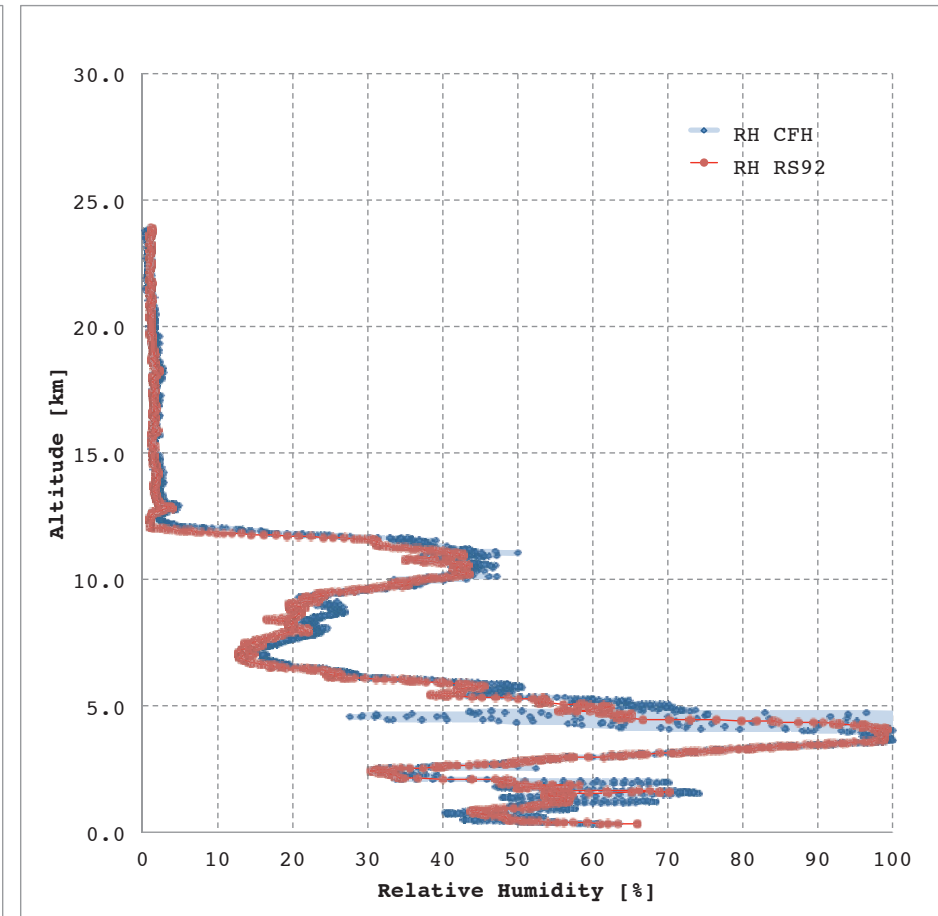
2014-09-11: RH CFH (blue) versus RH (RS92)



RH Example



2014-09-11: RH CFH (blue) versus RH (RS92)



2014-11-26: RH CFH (blue) versus RH (RS92)



To Do

- Refine launch procedures for ARM operators
- CFH Handbook
- Produce baseline CFH humidity measurements
- Define uncertainties
- Work towards GRUAN certification
- Data processing: ARM DMF \Leftrightarrow GRUAN Lead Center
RS launch client



Acknowledgements

- Chris Martin – ARM SGP operations
 - Dave Breedlove – ARM SGP operations
 - John Schatz – ARM SGP operations
 - Matthew Gibson – ARM SGP operations
 - James Martin – ARM SGP operations
 - Nicki Hickmon - ARM SGP operations
 - Mike Ritsche - ARM SGP operations
 - George Sawyer - ARM SGP operations
 - Jody Martin - ARM SGP operations
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- Holger Vömel – NCAR
 - Michael Sommer – GRUAN Lead Center





Lidar Systems at the US Department of Energy's Atmospheric Radiation Measurement Sites

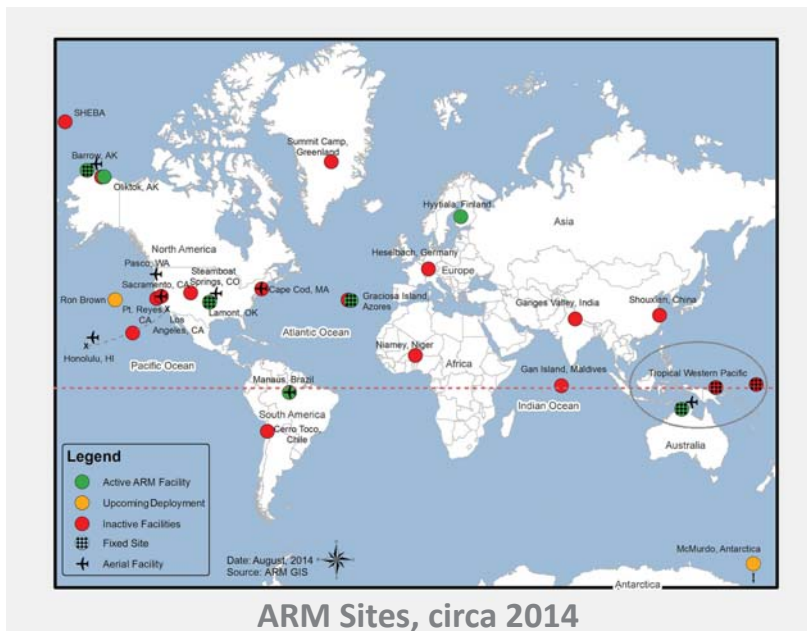
R. K. NEWSOM*

*Pacific Northwest National Laboratory, WA, USA

GRUAN 7th International Coordination Meeting, Matera, Italy, February 23-27, 2015

ARM Lidars

- ▶ ARM operates a number of lidar systems at its fixed and mobile sites around the globe.
- ▶ Systems include:
 - “Standard” systems operated at all sites
 - Micropulse lidars
 - Ceilometers
 - “Advanced” Systems operated at selected sites
 - Doppler Lidars
 - Raman Lidars
 - High Spectral Resolution Lidars (HSRLs)



ARM Doppler Lidar Measurements, and Current Deployment Locations



► Measurements

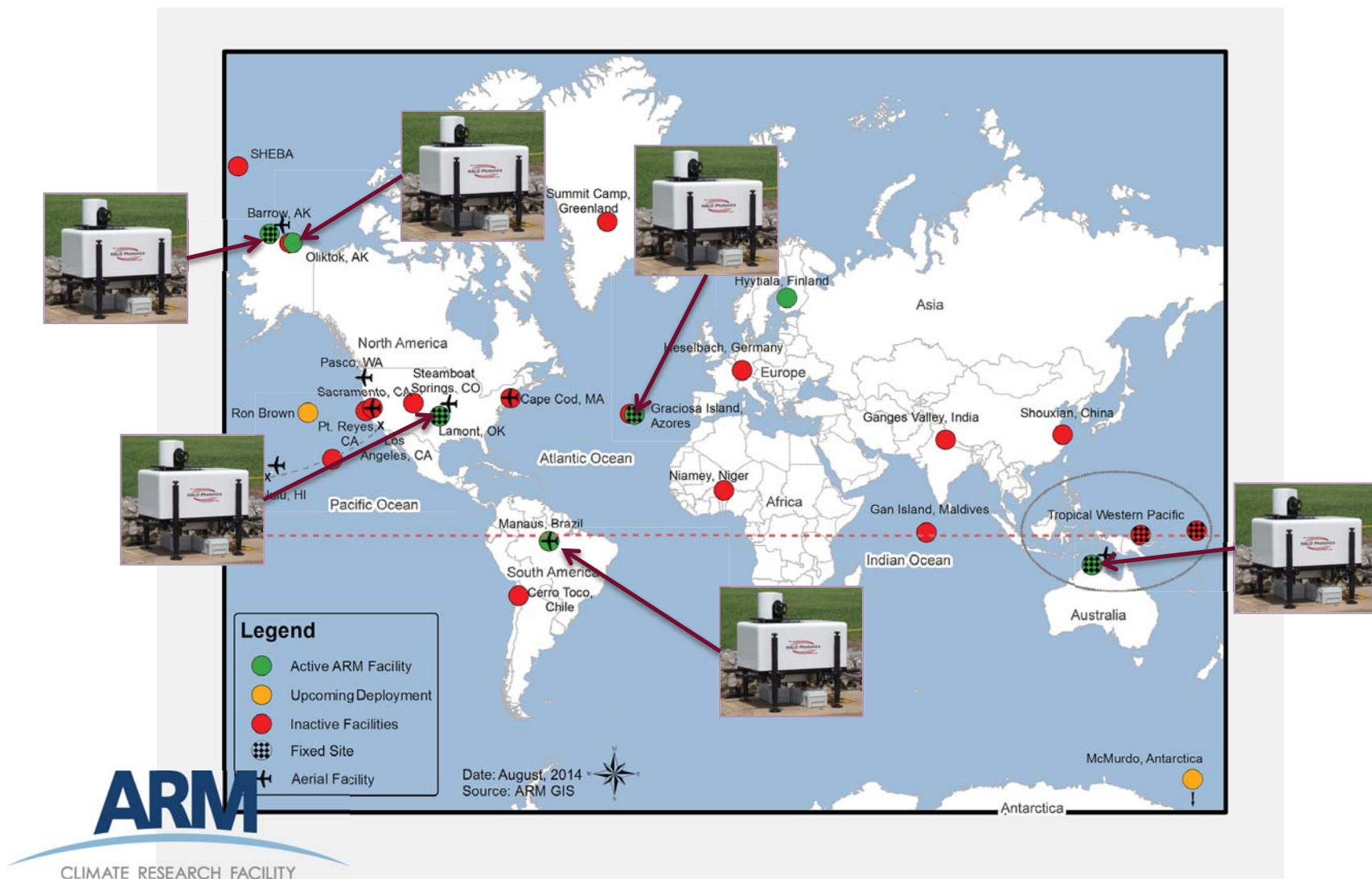
- Clear-air vertical velocity, winds, turbulence, and aerosol backscatter
- Maximum measurement height is 10 km, but mostly limited to atmospheric boundary layer (< 3km).

► ARM currently operates 6 Doppler systems at the following sites:

- Southern Great Plains (SGP), Oklahoma, USA, 2011 to present
- Tropical Western Pacific (TWP), Darwin, AU, 2010 through 2014
 - Moved to SGP in 2015
- 1st ARM Mobile Facility (AMF1)
 - Nainital, India, June 2011 to March 2012
 - Cape Cod, MA, USA, July 2012 to July 2013
 - Manacapuru, Brazil, January 2014 to present
- North Slope of Alaska (NSA), Barrow, Alaska, USA, 2014 to present
- 3rd ARM Mobile Facility (AMF3)
 - North Slope of Alaska (NSA), Oliktok Point, Alaska, USA, 2014 to present
- Eastern North Atlantic (ENA), Graciosa Island, Azores, 2014 to present



ARM Doppler Lidar Deployment Locations

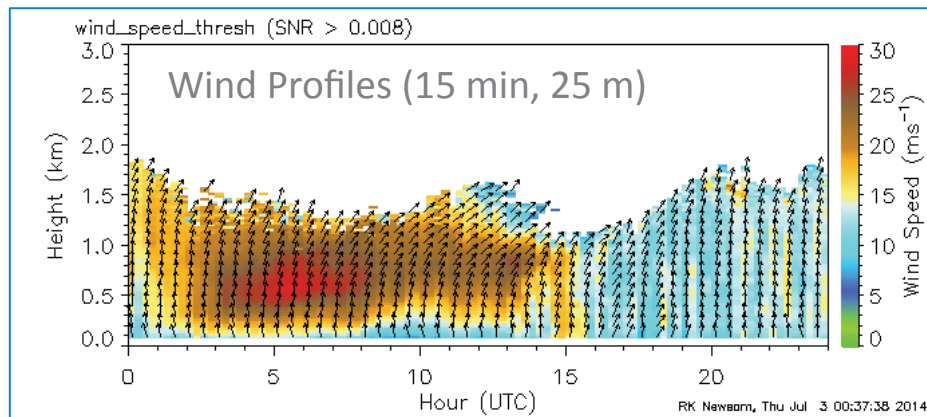
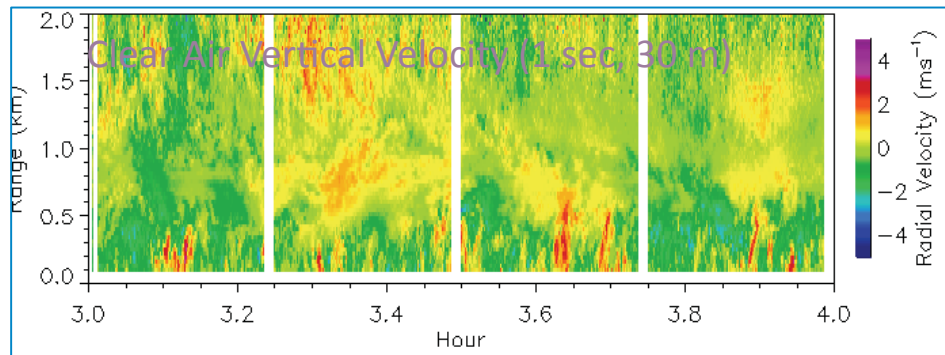


ARM Doppler Lidar Specs

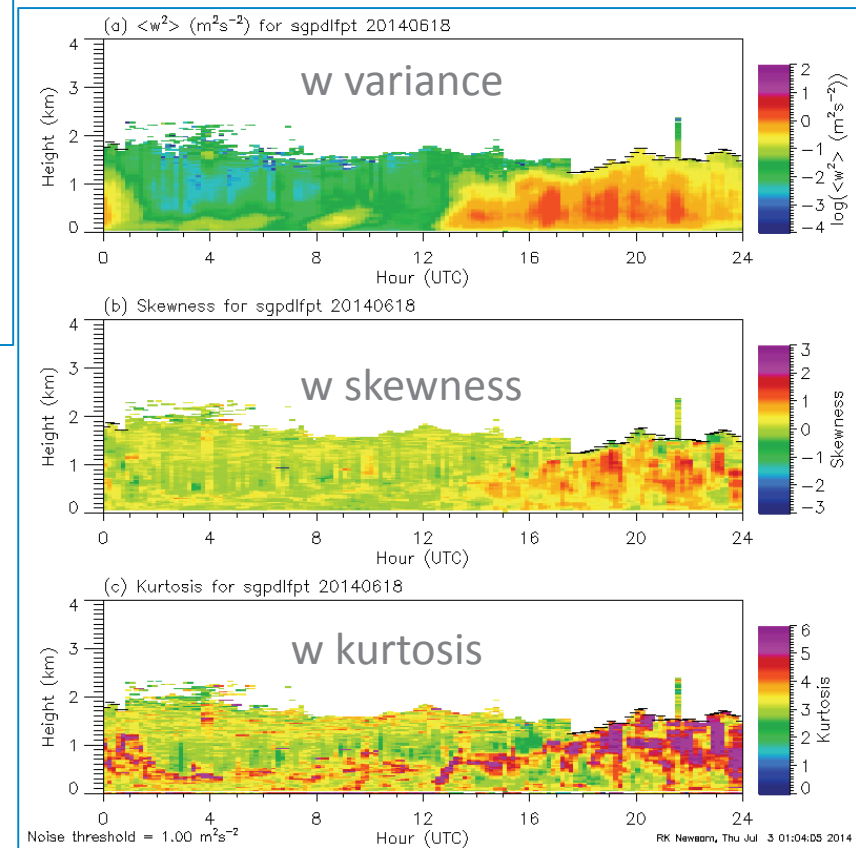
- ▶ Manufacturer: Halo Photonics (UK)
- ▶ Specs
 - Wavelength: 1.5 μm
 - Pulse width: 150ns (22.5m)
 - Pulse Energy: $\sim 100 \mu\text{J}$
 - Pulse repetition Frequency: 15 kHz
 - Max Measurement Range: 10 km
 - Typical range: $\sim 2\text{-}4 \text{ km}$
 - Velocity precision: $\sim 10 \text{ cm s}^{-1}$
 - Full upper hemispheric scanning capability
 - Sensitive to aerosol backscatter
- ▶ Measurements and Operation modes
 - Vertical staring and PPI scans once every 15 min
 - Typical resolution: 1 sec, 30 m
 - Direct Measurements
 - Radial Velocity
 - SNR
 - Derived Measurements
 - Attenuated aerosol backscatter
 - Winds
 - Vertical velocity statistics



ARM Doppler Lidar Data Products



Vertical Velocity Variance, Skewness and Kurtosis



ARM Raman Lidar

► Built by John Goldsmith at Sandia Labs, Livermore, CA, USA

► Specs

■ Transmitter

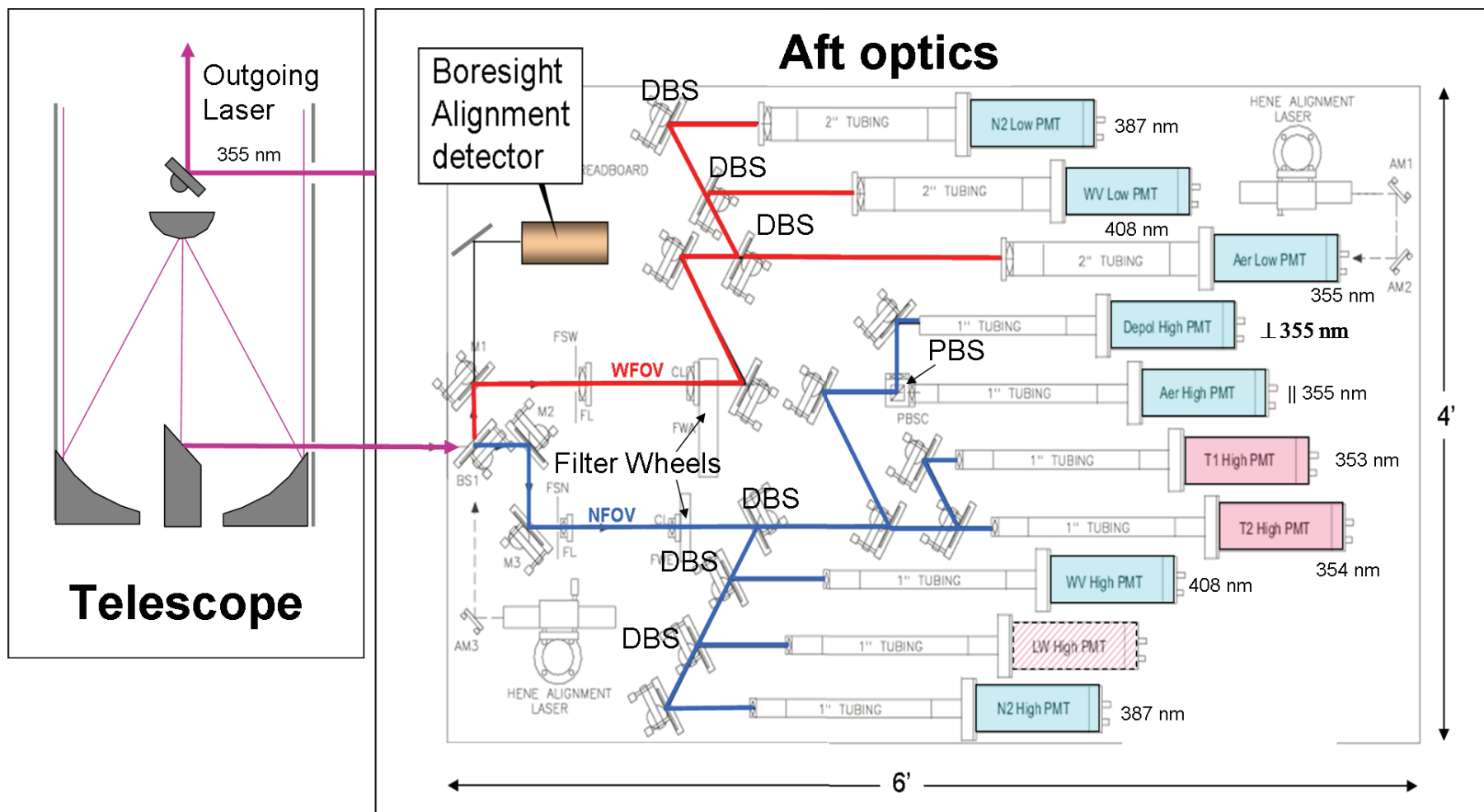
- Tripled Nd:YAG (Manufacturer: Continuum)
- Wavelength: 355 nm
- Pulse Energy ~300 mJ
- PRF 30 Hz
- Pulse width ~5 ns
- Beam Diameter 13 cm
- Beam Divergence 0.1 mrad

■ Receiver

- Primary Telescope diameter 61 cm, f/9.3
- Field of view: 2 mrad for Wide (WFOV) and 0.3 for narrow (NFOV)
- PMTs: Electron Tubes 9954B
- Detection Electronics: Licel Transient Data Recorders
- 9 Detection channels
 - ◆ WFOV unpolarized elastic @ 354.71nm (bandwidth = 0.3 nm)
 - ◆ NFOV co-polarization elastic @ 354.71nm (bandwidth = 0.3 nm)
 - ◆ NFOV depolarization elastic @ 354.71nm (bandwidth = 0.4 nm)
 - ◆ WFOV H₂O @ 407.45nm (bandwidth = 0.3 nm)
 - ◆ NFOV H₂O @ 407.45 nm (bandwidth = 0.3 nm)
 - ◆ WFOV N₂ @ 386.69 nm (bandwidth = 0.3 nm)
 - ◆ WFOV N₂ @ 386.69 nm (bandwidth = 0.3 nm)
 - ◆ WFOV Rotational Raman 1 @ 353.27nm (bandwidth = 0.2 nm)
 - ◆ WFOV Rotational Raman 2 @ 354.27nm (bandwidth = 0.2 nm)



ARM Raman Lidar Specs



ARM Raman Lidar Measurements and Current Deployment Locations

► Raman Lidars

■ Measurements

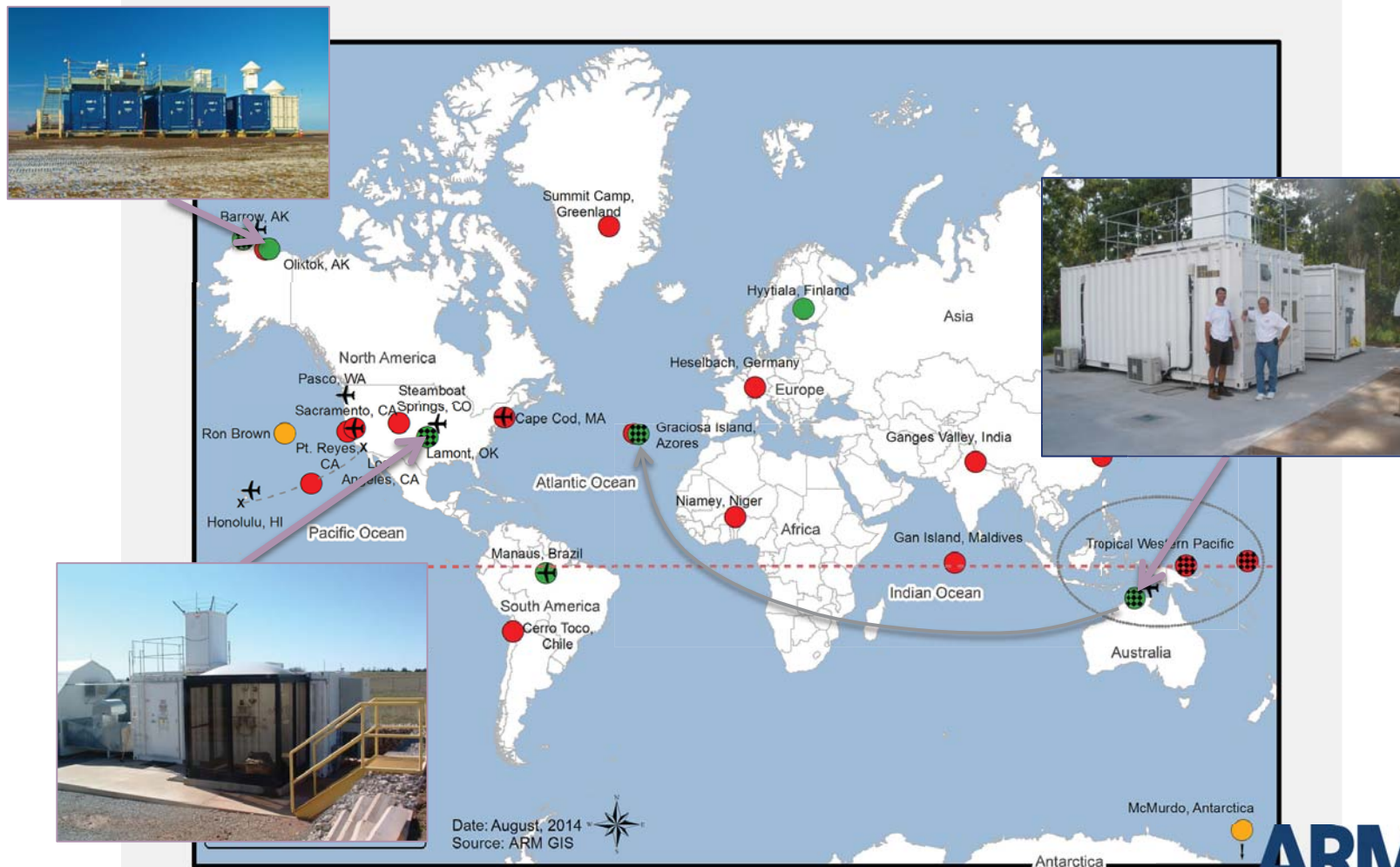
- Water vapor mixing ratio, temperature, aerosol backscatter, aerosol extinction, linear depolarization ratio.
- Maximum measurement height is ~30 km
- In complete overlap limits the measurement accuracy below ~1 km.

■ ARM currently operates 3 Raman systems at the following sites:

- Southern Great Plains (SGP), Oklahoma, USA, 1996 to present
- Tropical Western Pacific (TWP), Darwin, AU, 2010 through 2014
 - ◆ Moved to ENA in 2015
- 3rd ARM Mobile Facility (AMF3)
 - ◆ North Slope of Alaska (NSA), Oliktok Point, Alaska, USA, 2014 to present



ARM Raman Lidar Deployment Locations



ARM Raman Lidar Data Products

▶ Raw Data

- Resolution: 7.5 m, 10 sec
- PMT Analog voltage
- Photon Counts
- Photon counting rates from merging analog and photon counts

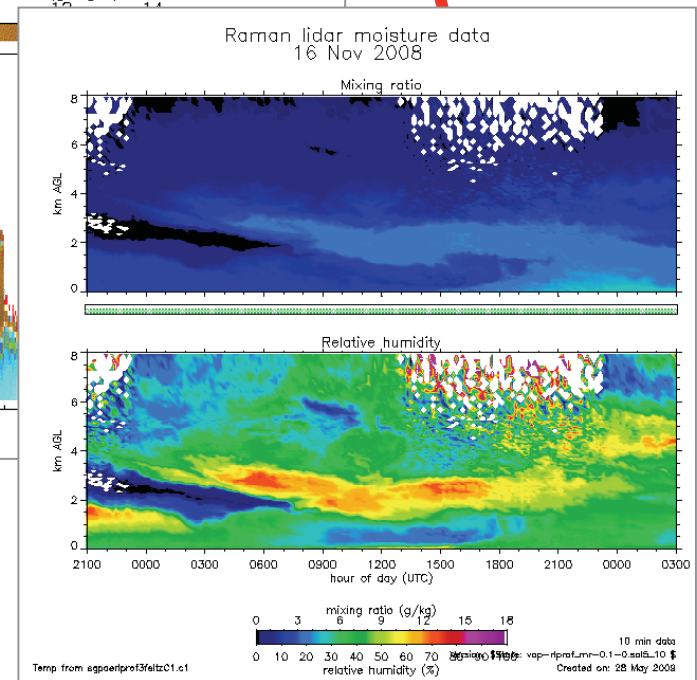
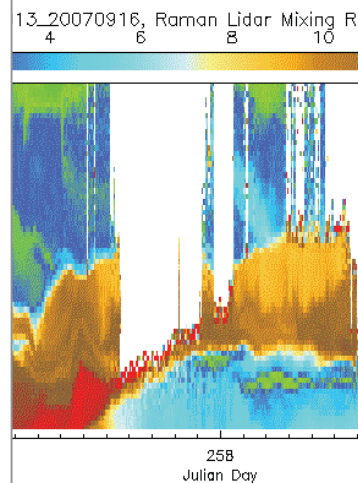
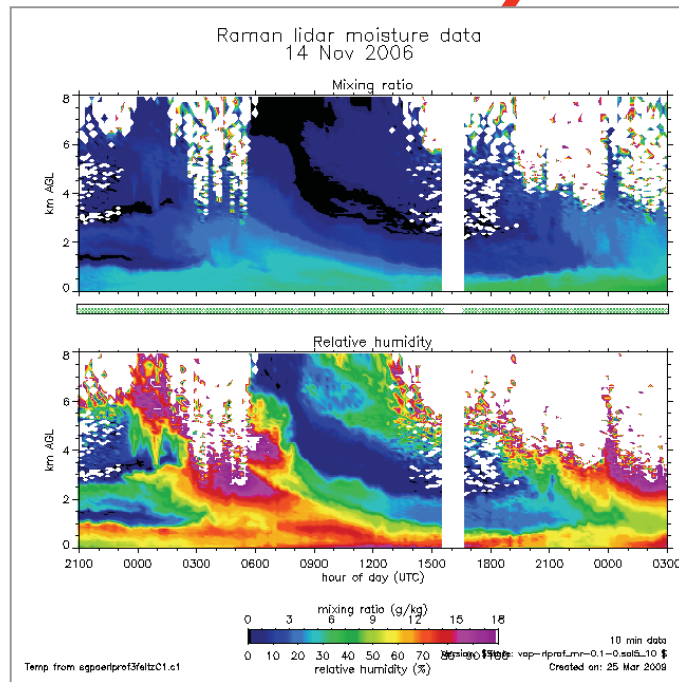
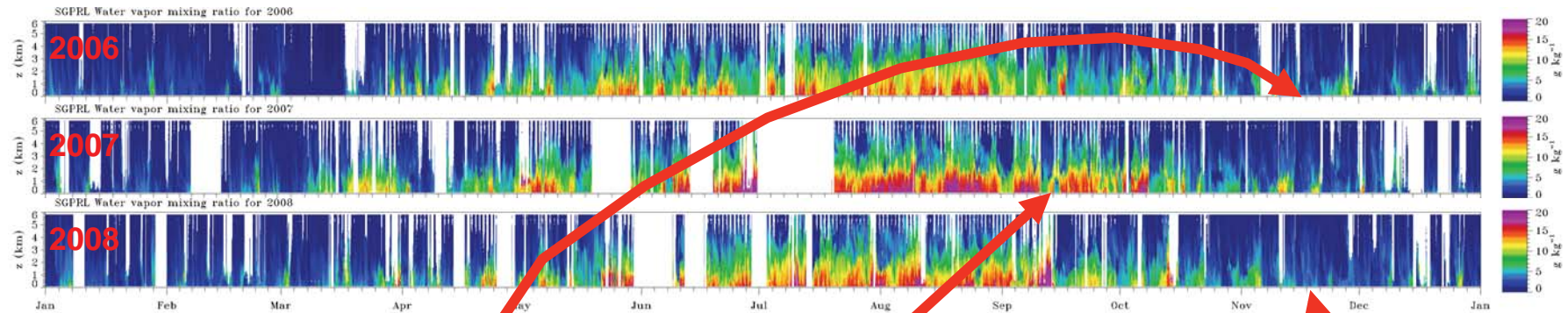
▶ Derived Data Products

- Water Vapor Mixing Ratio (75 m, 10 sec and 10 min)
- Temperature (300 m, 10 and 60 min)
- Aerosol (75 m, 1 or 2 and 10 min)
 - Extinction coefficient
 - Volume backscatter coefficient
 - Linear Depolarization Ratio

ARM

CLIMATE RESEARCH FACILITY

ARM Raman Lidar Data Products



ARM High Spectral Resolution Lidar

- ▶ Built by Ed Eloranta and team at Space Sciences and Engineering Center, University of Wisconsin, Wisconsin, USA
- ▶ Major Specs:
 - Wavelength = 532 nm
 - Min/Max range = 100 m to 30km
 - Time resolution: 2.5 sec
 - Range resolution: 7.5 m
 - Autonomous, 24/7 mode of operation



ARM HSRL Measurements and Current Deployment Locations

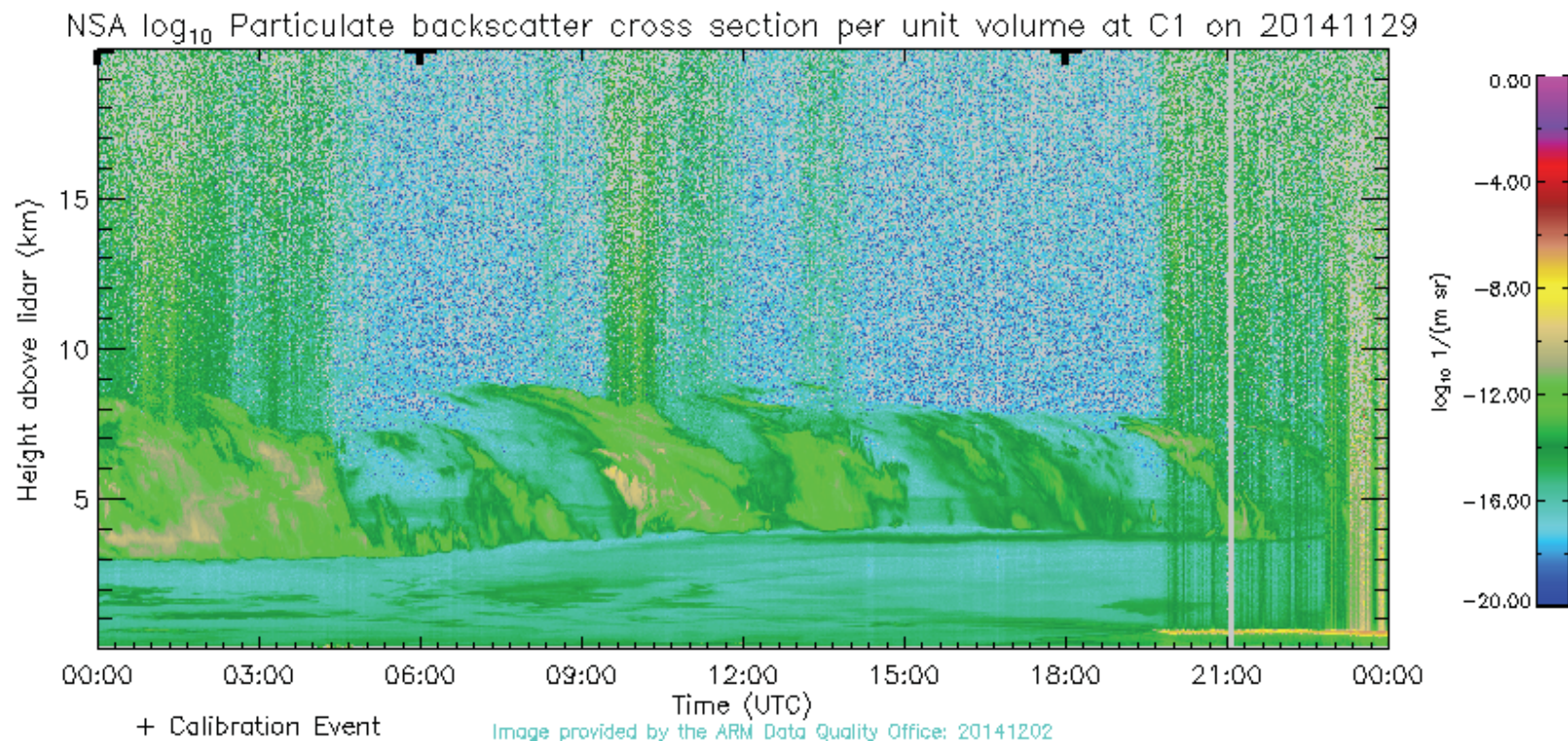
► Measurements

- Aerosol backscatter, aerosol extinction, aerosol depolarization ratio.
- Maximum measurement height is ~30 km
- In complete overlap limits the measurement accuracy below ~2 km.

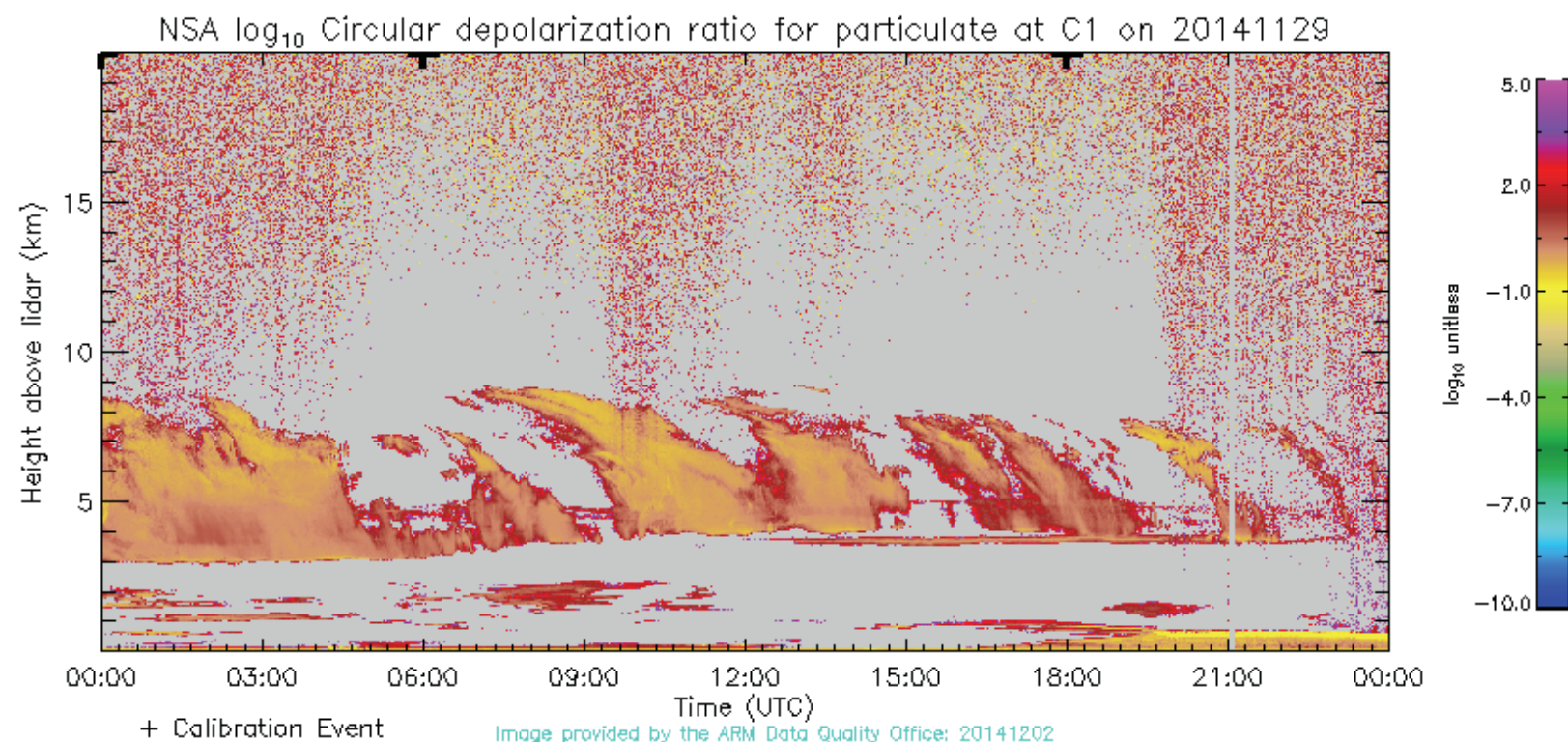
► ARM currently operates 2 HSRL systems at the following sites:

- North Slope of Alaska, Barrow, Alaska, USA, 2011 to present
- 2nd ARM Mobile Facility (AMF2)
 - Steamboat Springs, Colorado, USA, 2010-2011
 - Gan Island, Maldives, 2011-2012
 - Ship-based between CA and HI, USA, 2012-2013
 - Hyytiälä Finland, 2014
 - Ship-based between CA and HI, USA, 2015

HSRL Volume Backscatter Coefficient



HSRL Circular Depolarization Ratio



Questions?

