



GRUAN / ICM-15

Modem M10 GDP progression and results overview

JC. Dupont (IPSL), A. Farah (MODEM), P. Jann (Meteo-France)
jean-charles.dupont@ipsl.fr



ICM-14 conclusions for Modem M10



- **WHAT** : Perform assessment of the data quality issues highlighted in Payerne parallel flights and assess whether it is feasible that M10 sondes can be processed to GRUAN products
- **HOW** : Further assessment of Modem M10 characterization including various parallel flights including M10-M10 paired flights to understand more fully data repeatability
- **BY WHOM** : Modem, Meteo-France, IPSL, Lead Center, Meteoswiss
- **BY WHEN** : ICM-15



Outline of the presentation

M10 Temperature Reproducibility issues

- Observation and problem identification
- Coating effect for day/night & solution
- Bending effect for day/night & solution
- Conclusions

Status of M10 GRUAN Data Product

- Suggestion for M10 certification
- M10 dataflow

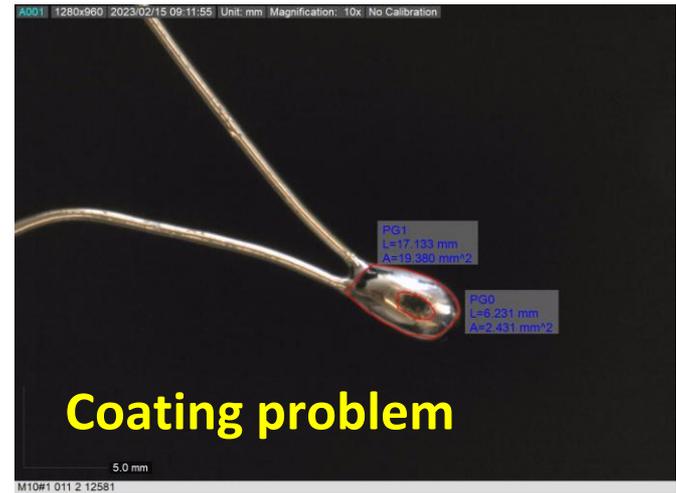
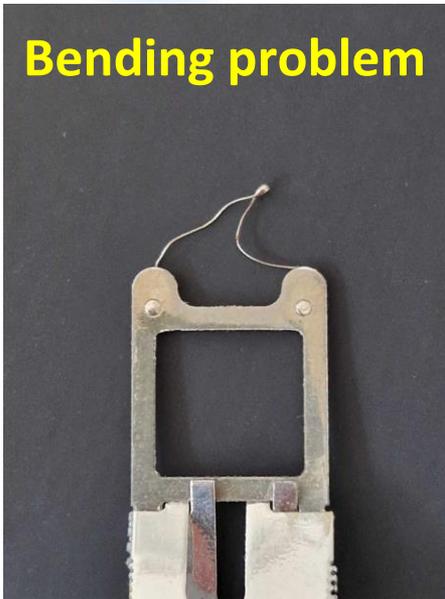
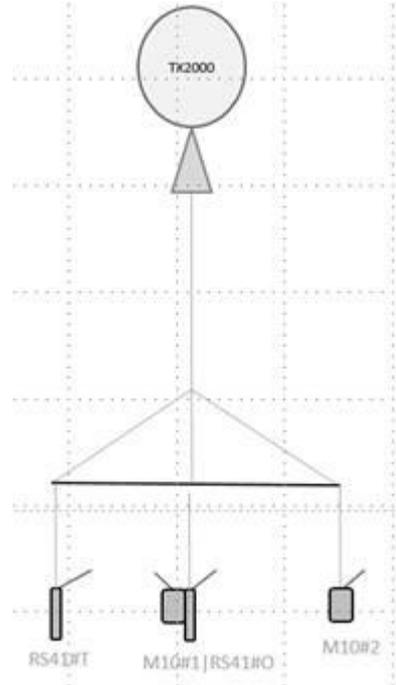
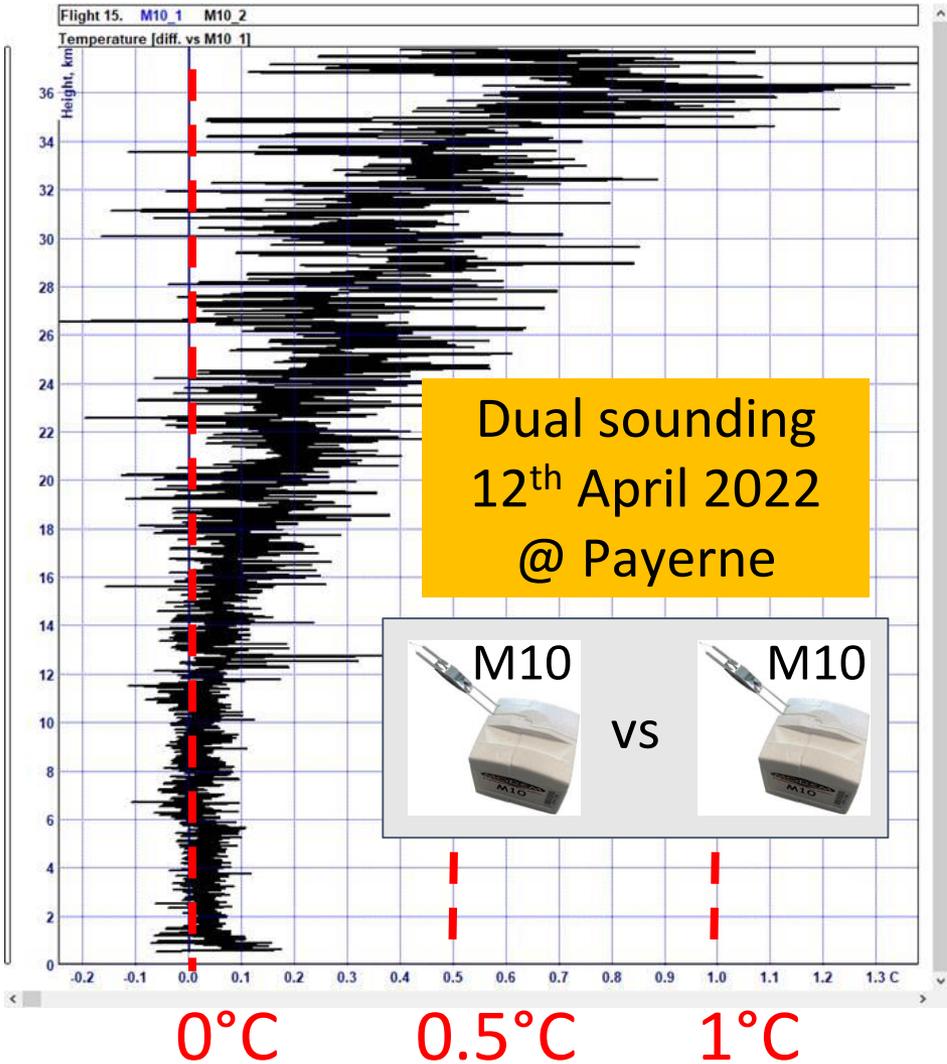
Metrics at Faa'a site

Conclusions and Perspectives

M10 Temperature Reproducibility Issues



1- Observations and problem

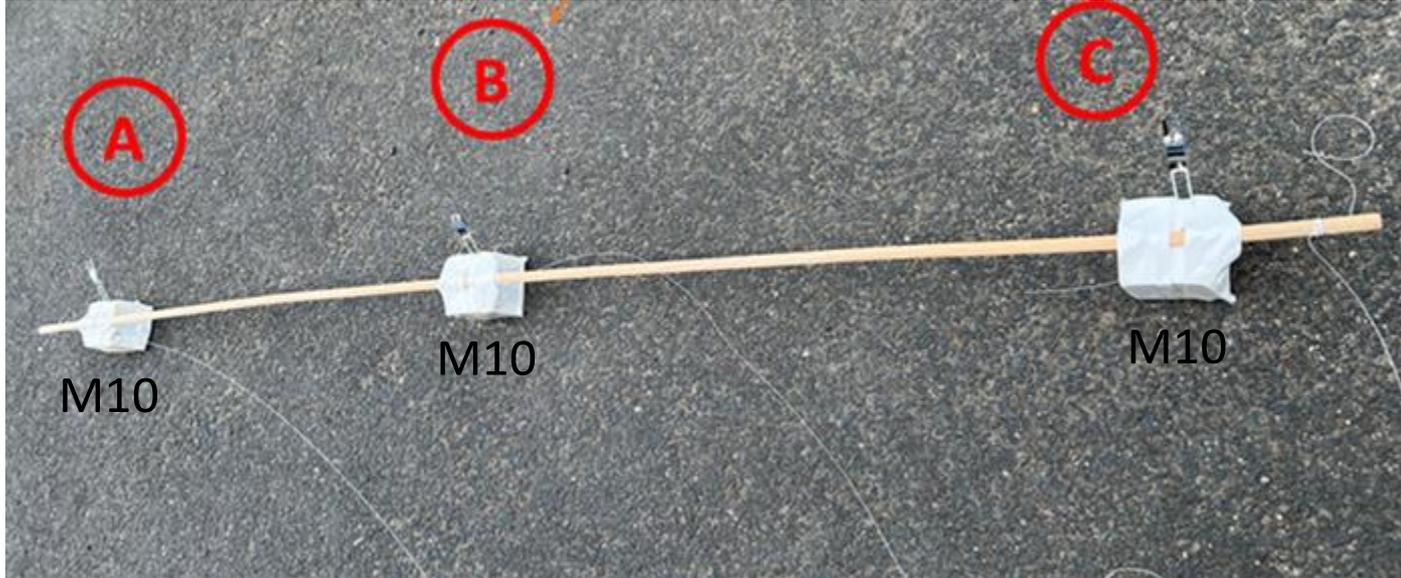
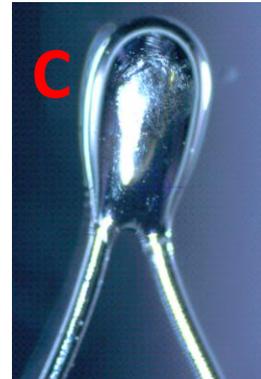
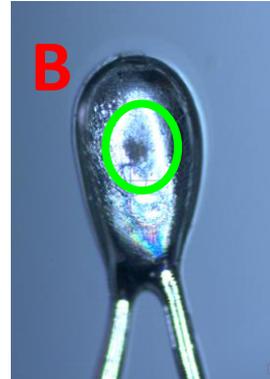
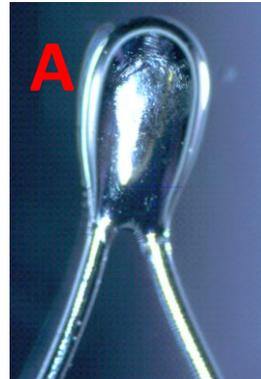


M10 Temperature Reproducibility Issues



2- Coating Effect - M10 vs M10 flights

Set-up



M10 Temperature Reproducibility Issues



2- Coating Effect - M10 vs M10 flights



Flight & Config & Day

Flight #	Date (dd/mm/yyyy)	# of M10	Fixing	Configuration
1	16/05/2023	3	Scotch	OK-KO-OK
2	30/05/2023	3	Scotch	OK-KO-OK
3	01/03/2023	3	Rope	OK-KO-OK
4	03/03/2023	3	Scotch	KO-OK-OK
5	07/04/2023	3	Scotch	OK-OK-KO

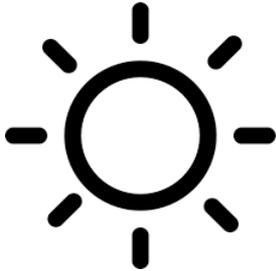
OK: un-damaged T-sensor
KO: damaged T-sensor

M10 Temperature Reproducibility Issues



2- Coating Effect - M10 vs M10 flights

Results, day

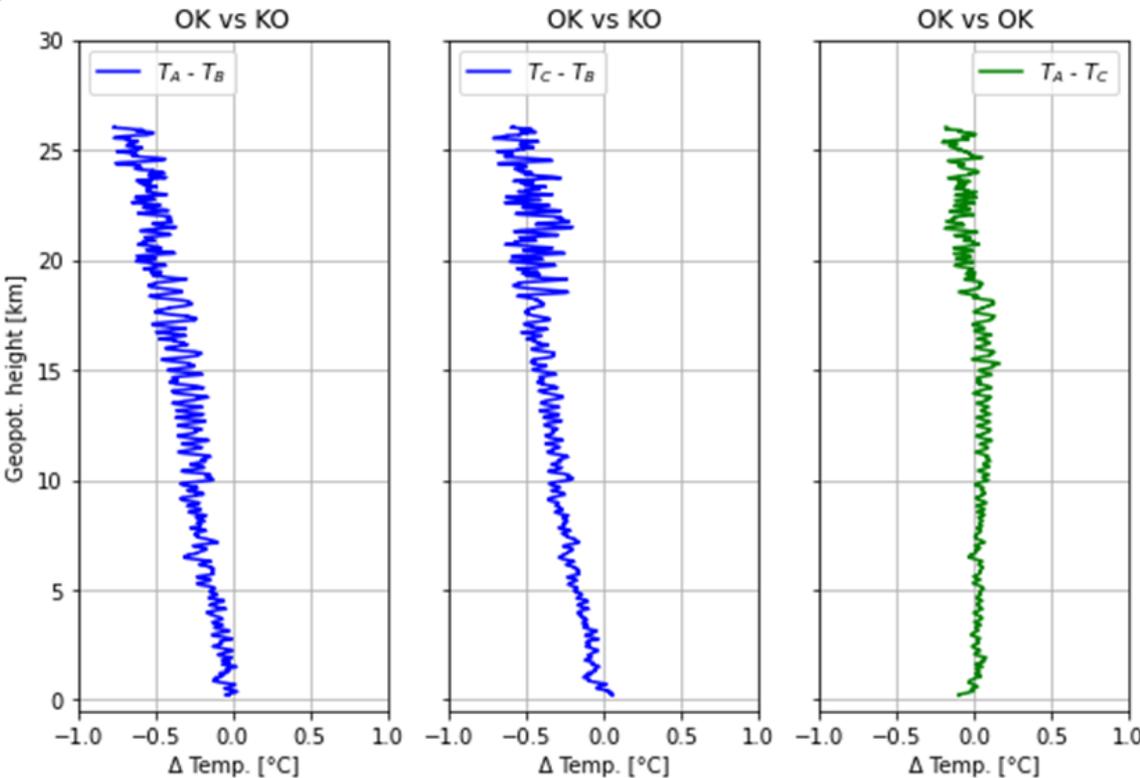


Ex: Flight #1

OK vs OK: There is a strong temperature correlation between two M10.

OK vs KO: A linear increase in temperature difference with altitude is seen, peaking at $\delta=0.7k$ at 26 km.

Inter M10 difference [Daytime - 2023/05/16]



M10 Temperature Reproducibility Issues



2- Coating Effect - M10 vs M10 flights



Results, day

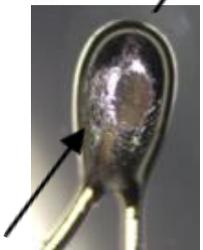
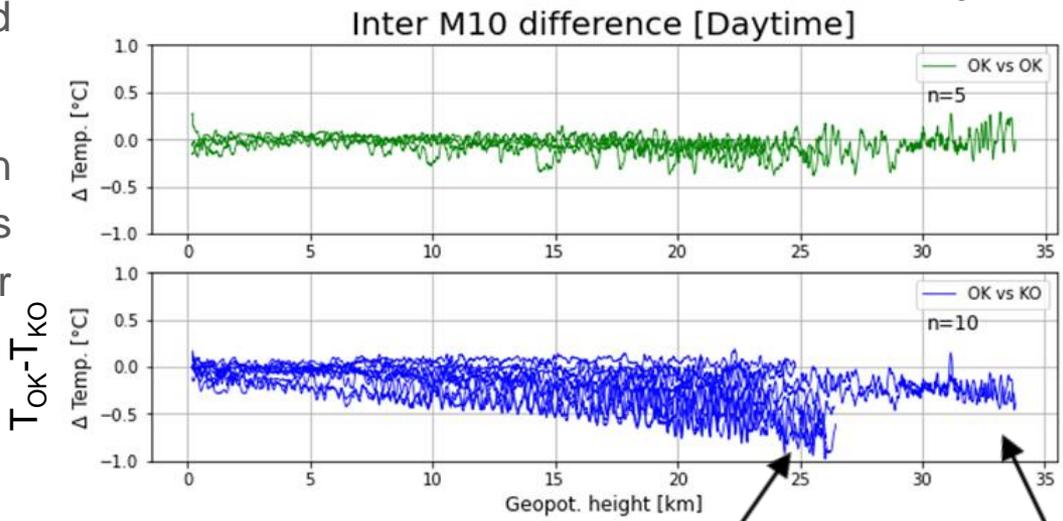
OK vs OK: There is a very good agreement between the two M10.

OK vs KO: A linear increase in temperature difference with altitude is seen, peaking at $\Delta=0.8k$ at 26 km (for certain soundings).

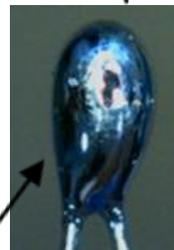
Summary:

Coating problem

- ↳ black stain on T sensor
- ↳ more solar absorption
- ↳ higher temperature for T_{KO}



Big stain on the temperature sensor

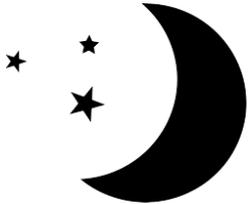


Small stain on the temperature sensor

M10 Temperature Reproducibility Issues



2- Coating Effect - M10 vs M10 flights



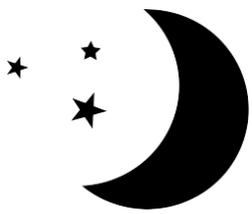
Flight & Config & Night

Flight #	Date (dd/mm/yyyy)	# of M10	Fixing	Configuration
1	20/02/2024	3	Rope	A: [OK + 0°] B: [OK + 90°] C: [KO + 0°]
2	28/02/2024	3	Rope	A: [OK + 0°] B: [OK + 90°] C: [KO + 0°]

OK: un-damaged T-sensor
KO: damaged T-sensor

M10 Temperature Reproducibility Issues

2- Coating Effect - M10 vs M10 flights

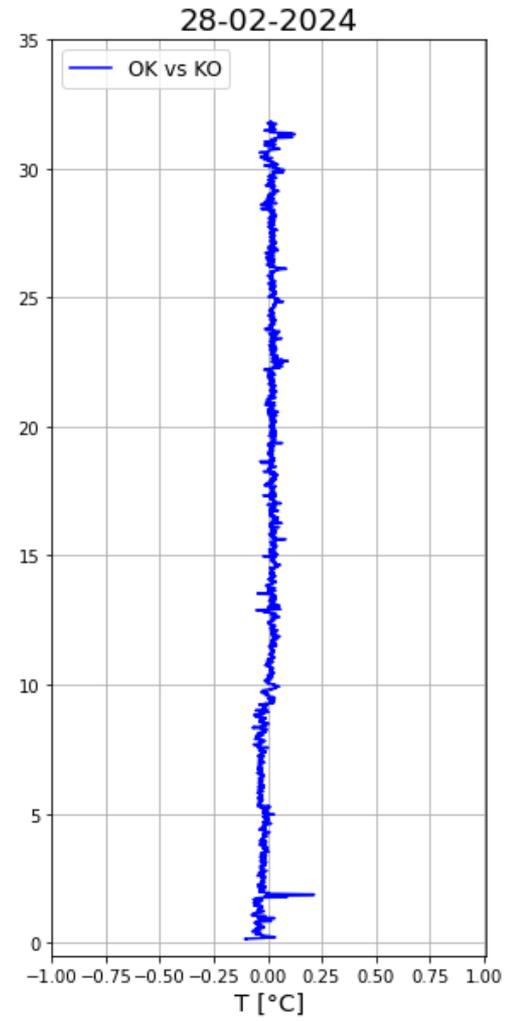
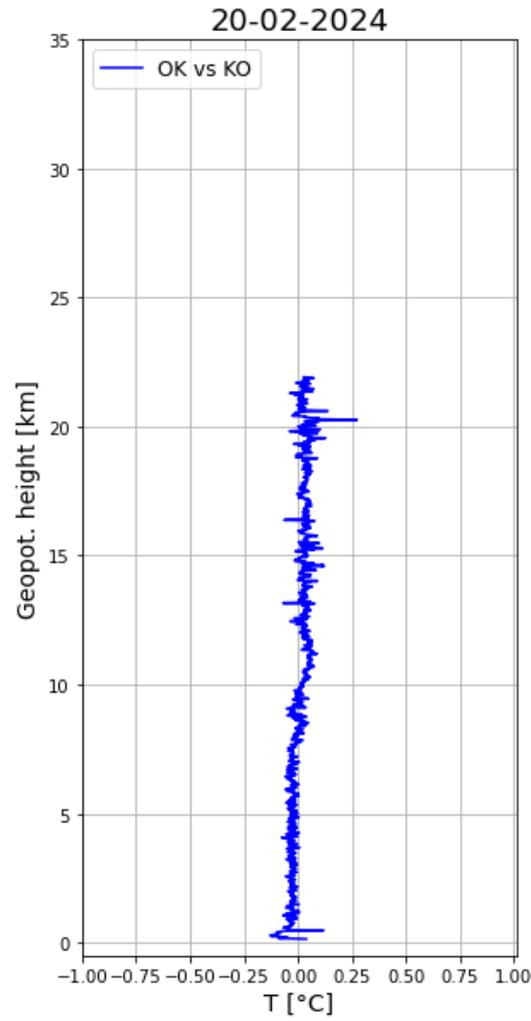


Results, Night

OK vs KO: No bias, no tendency between two M10.

Summary:

The issue with the temperature sensor coating has no impact on temperature measurements.



M10 Temperature Reproducibility Issues



3- Coating problem - origine

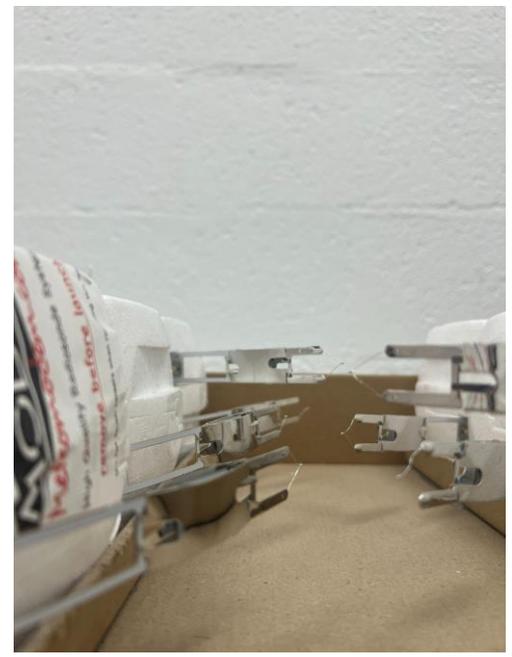
Packaging Before June 2023



M10 Temperature Reproducibility Issues

3- Coating problem - solution

Packaging After June 2023

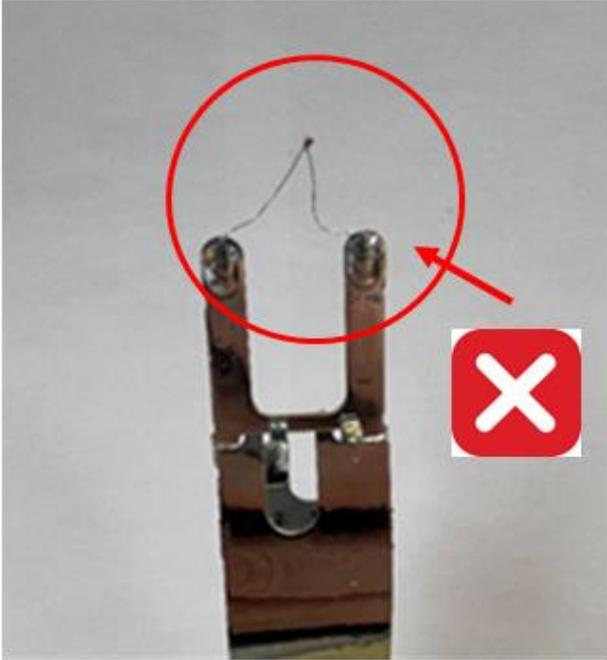
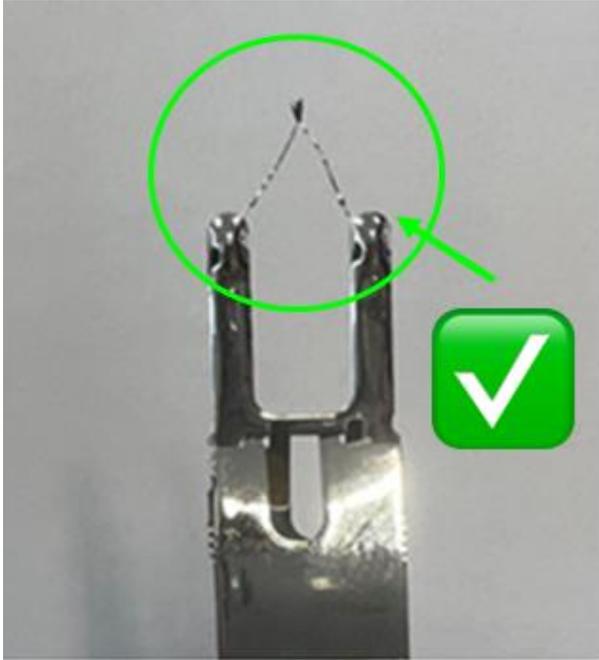


There is no contact between the temperature sensors

M10 Temperature Reproducibility Issues



4- Bending problem ?!

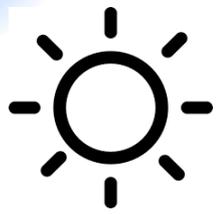


Bending problem A



Bending problem B

M10 Temperature Reproducibility Issues



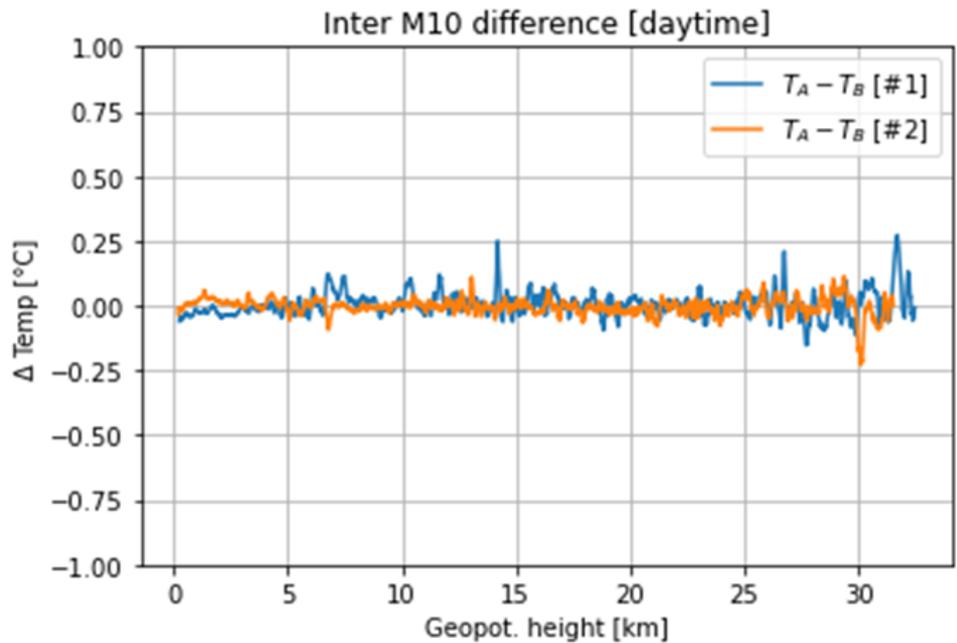
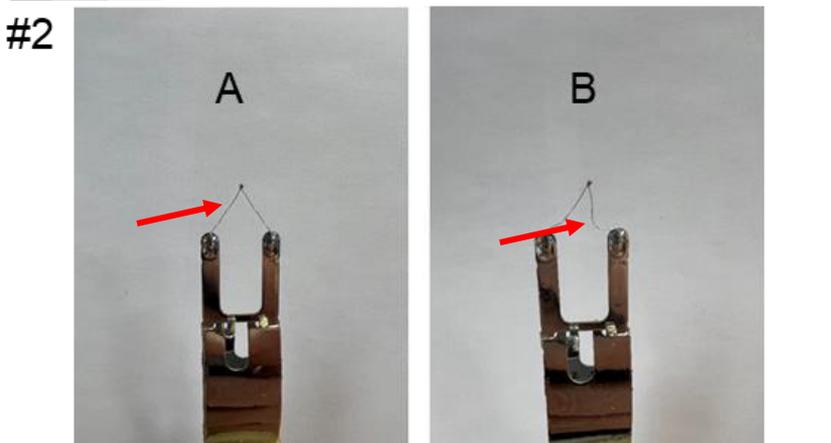
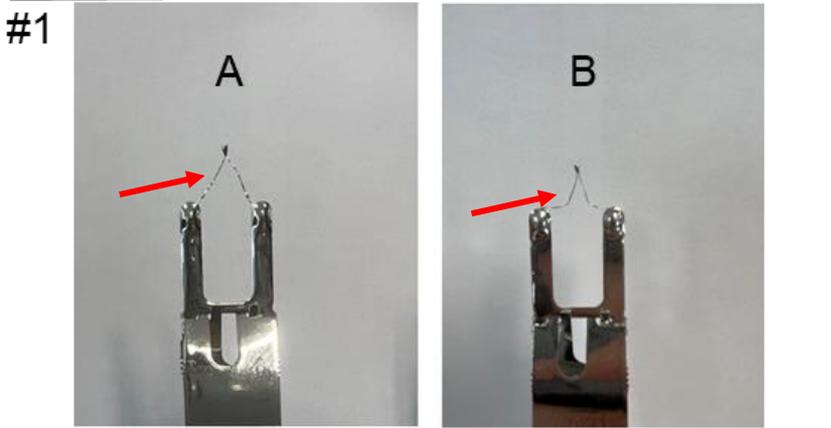
4- Bending Effect A

Set-up

Flights :

#1 : 03/09/2022

#2 : 06/09/2022



Summary:

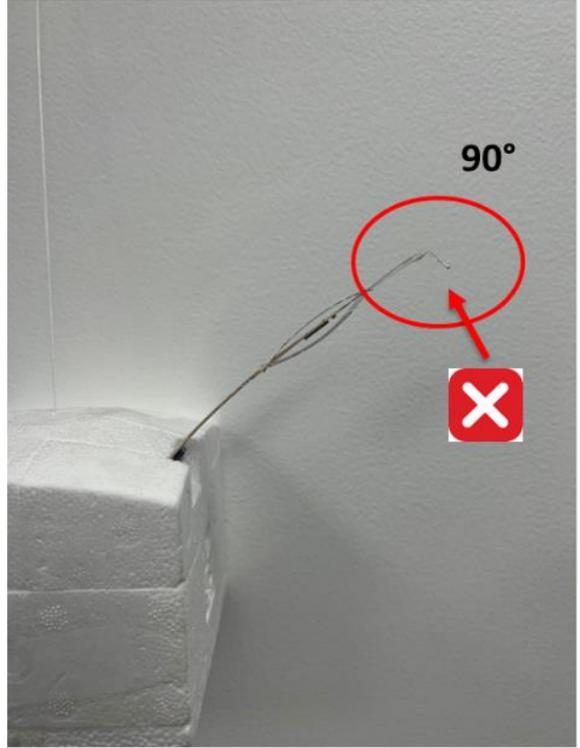
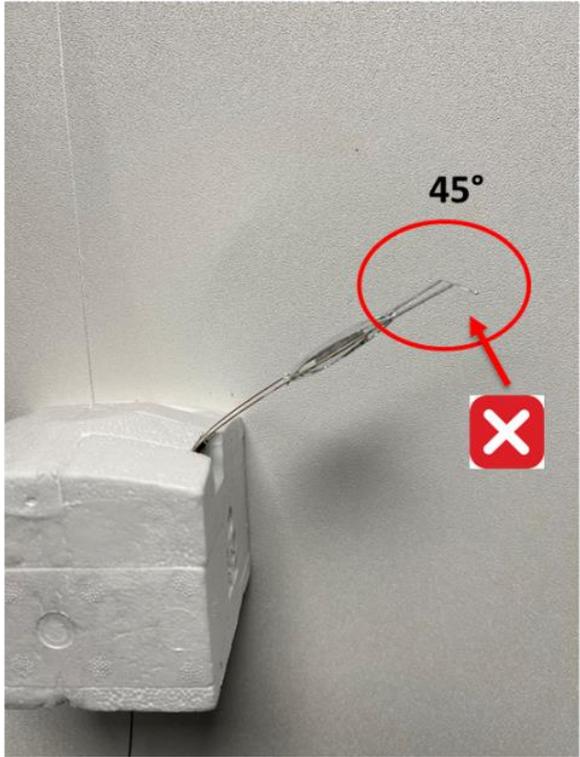
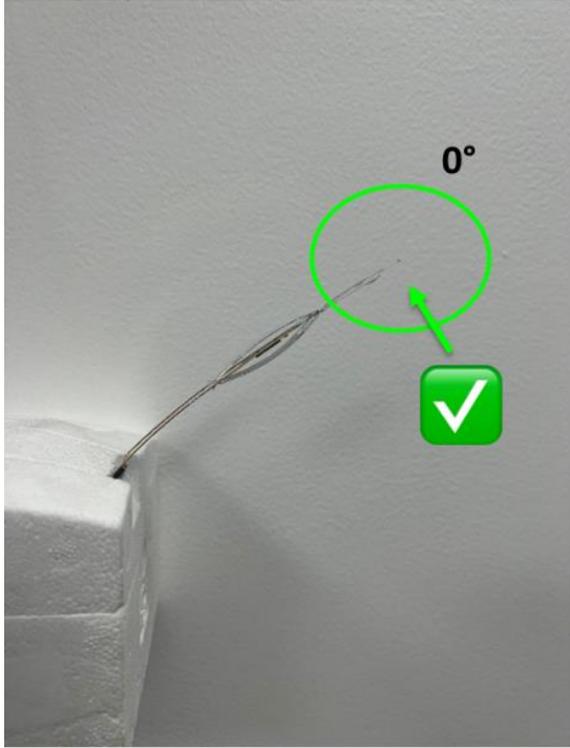
The temperature variances exhibit symmetry around zero in both setups (#1 and #2). This implies that this bending shape of the temperature sensor wire has no impact on temperature measurements.

M10 Temperature Reproducibility Issues



5- Bending Effect B

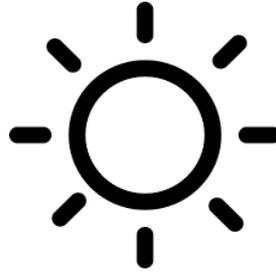
Set-up : Tilt compared to the sensor boom



M10 Temperature Reproducibility Issues

5- Bending Effect B - M10 vs M10 flights

Flight & Config & Day



Flight #	Date (dd/mm/yyyy)	# of M10	Fixing	Configuration (°)
1	21/12/2022	3	rope	0-0-90
2	26/01/2023	3	rope	0-0-45
3	27/01/2023	4	rope	0-0-45-90
4	26/07/2023	3	scotch	0-45-90
5	07/08/2023	3	scotch	0-45-90

M10 Temperature Reproducibility Issues



5- Bending Effect B - M10 vs M10 flights

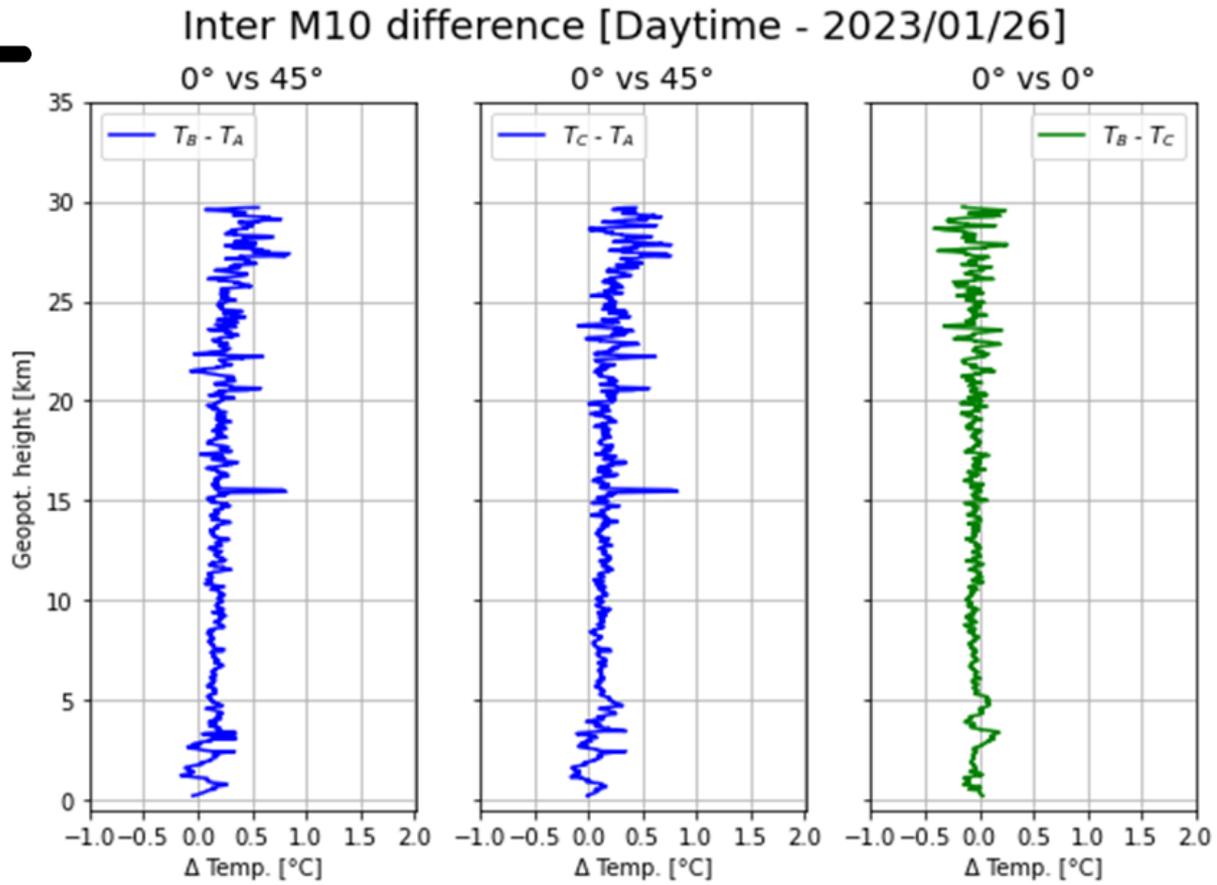


Results, day

Ex: Flight #1

0° vs 0°: There is a strong temperature correlation between two M10.

0° vs 45°: A linear increase in temperature difference with altitude is observed.



M10 Temperature Reproducibility Issues



5- Bending Effect B - M10 vs M10 flights

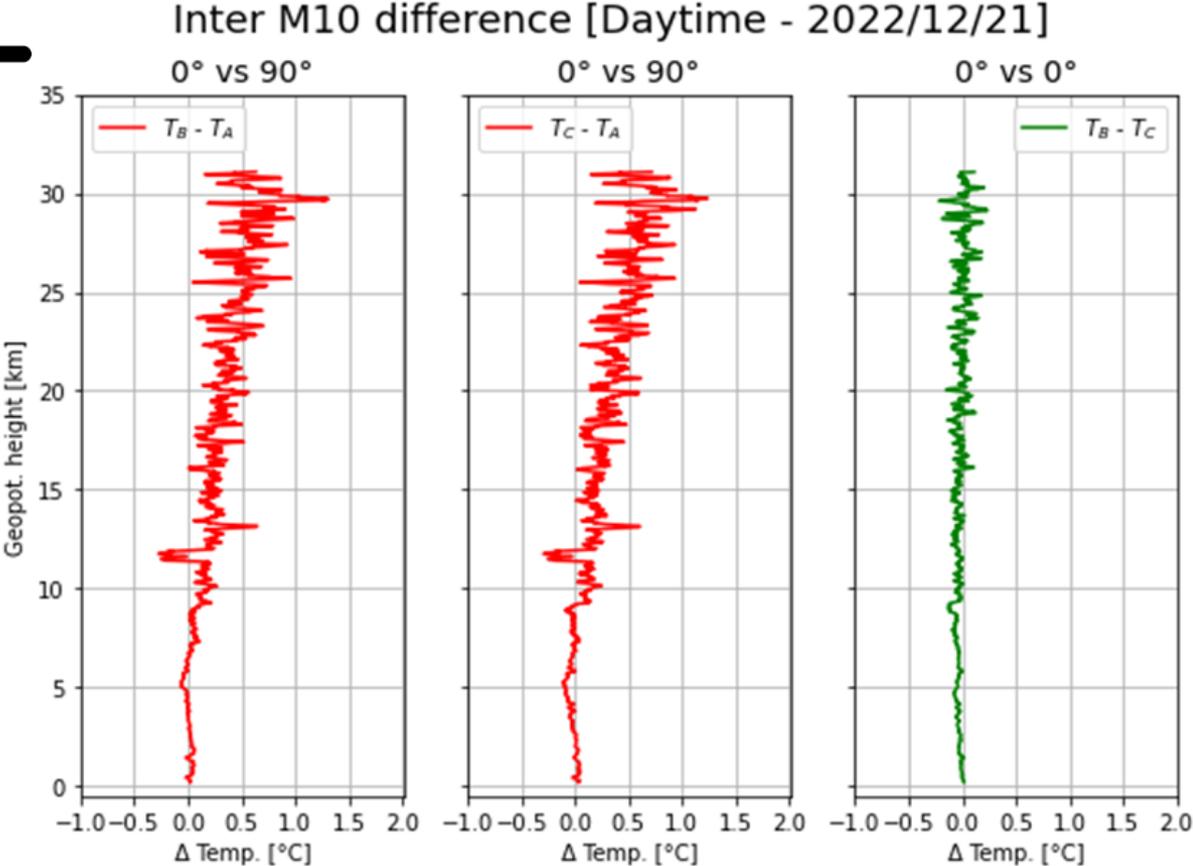


Results, day

Ex: Flight #2

0° vs 0°: There is a strong temperature correlation between two M10,

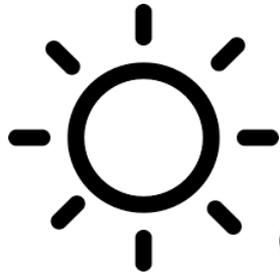
0° vs 90°: A linear increase in temperature difference with altitude is observed, peaking at $\Delta=1.2\text{k}$ at 30 km.



M10 Temperature Reproducibility Issues



5- Bending Effect B



Results, day

0° vs 0°: There is a strong temperature correlation between two M10

0° vs 45°: A linear increase in temperature difference with altitude is observed, reaching $\Delta = 0.7k$ at 33 km.

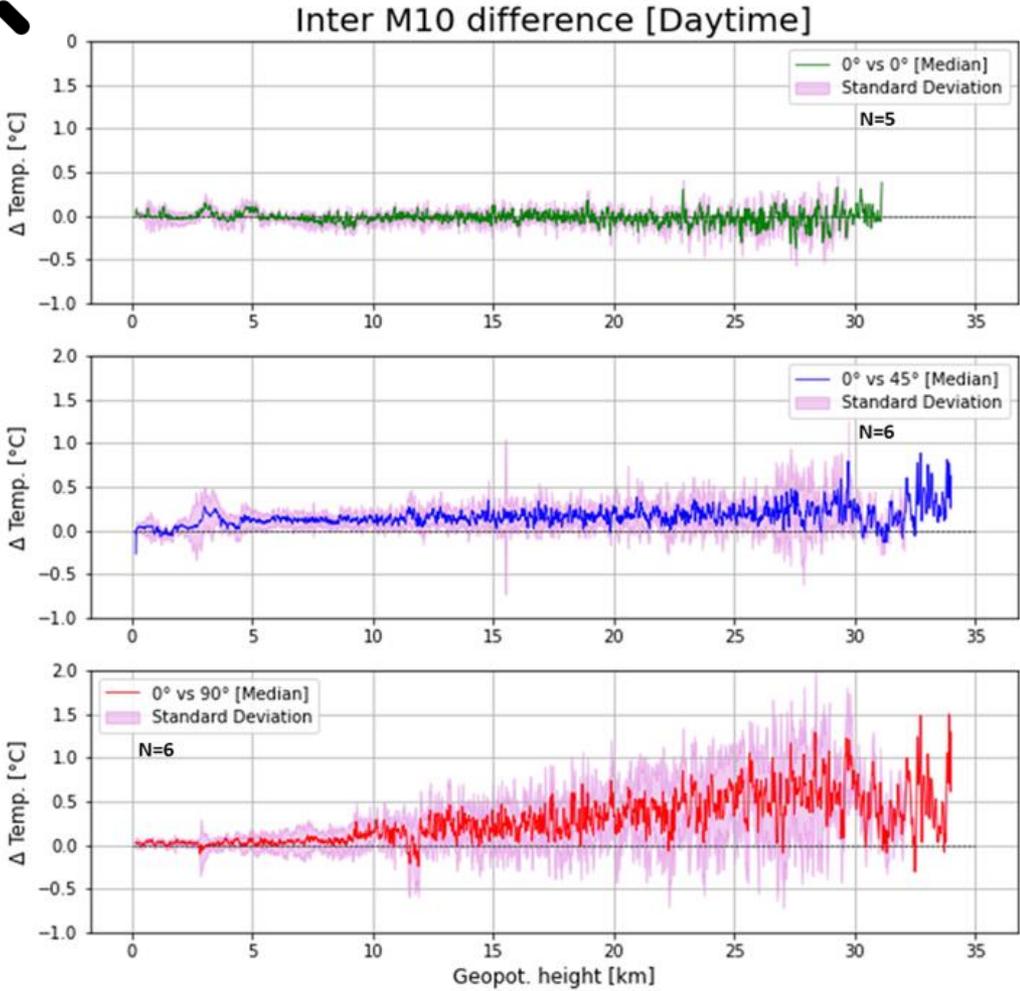
0° vs 90°: A linear increase in temperature difference with altitude is seen, peaking at $\Delta = 1.5k$ at 33 km (for certain soundings).

Summary:

Bending problem B has a « cooling » impact on the temperature, much cooler for 90° compared to 45°.

Why ?

- ✓ Sensor boom shadow on the T sensor ?
- ✓ Different reflexion between T sensor and M10 box



M10 Temperature Reproducibility Issues



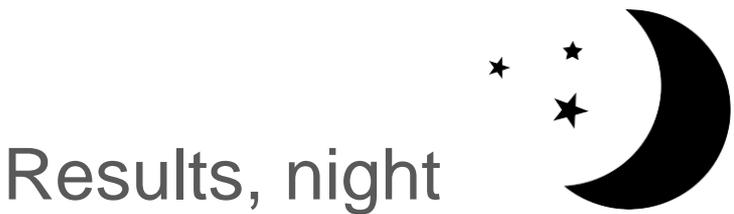
5- Bending Effect B - M10 vs M10 flights

Flight & Config & Night

Flight #	Date (dd/mm/yyyy)	# of M10	Fixing	Configuration (°)
1	20/02/2024	3	Rope	A: [OK + 0°] B: [OK + 90°] C: [KO + 0°]
2	28/02/2024	3	Rope	A: [OK + 0°] B: [OK + 90°] C: [KO + 0°]

M10 Temperature Reproducibility Issues

5- Bending Effect B - M10 vs M10 flights

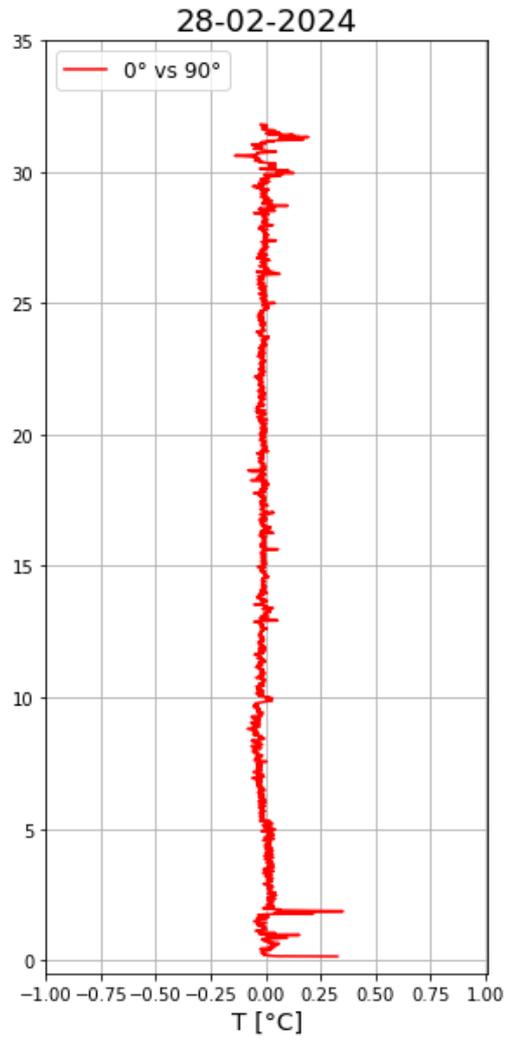
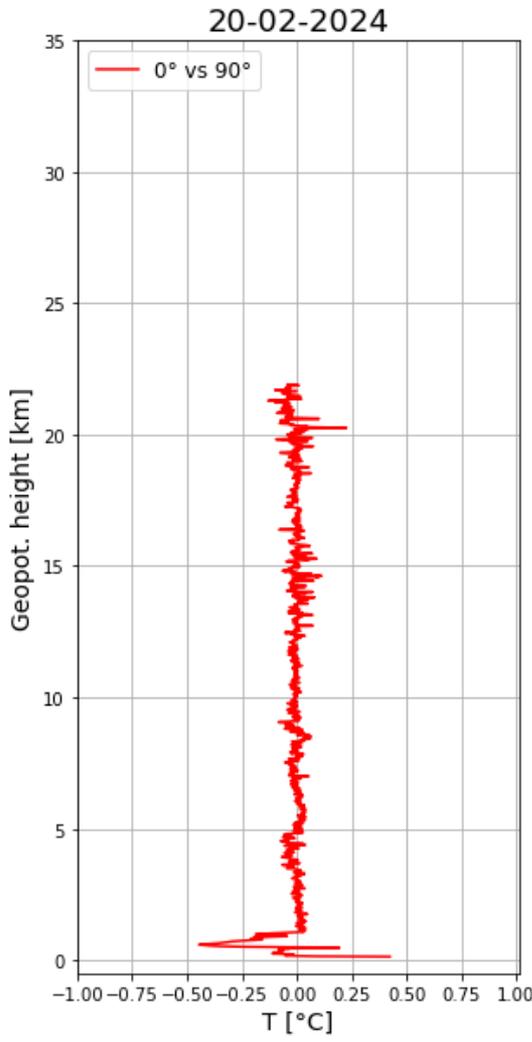


Results, night

0° vs 90°: There is a strong temperature correlation between two M10

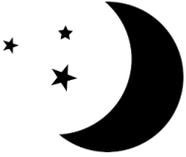
Summary:

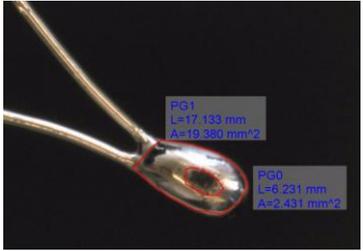
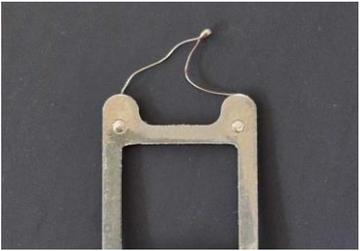
The orientation of the temperature sensor has no influence on temperature measurements.



M10 Temperature Reproducibility Issues



	Bending effect A	Bending effect B	Coating effect
	 ~ 0	 Colder max 0.7k @ 33km for 45° max 1.5k @ 33km for 90°	 Warmer max 0.8k @ 26km
	 ~ 0	 ~ 0	 ~ 0



Status of M10 GRUAN Data Product



- Suggestion for M10 certification

Period	Before June 2023		After June 2023	
Variables	Day	Night	Day	Night
Pressure	✓	✓	✓	✓
Wind	✓	✓	✓	✓
Relative humidity	✓	✓	✓	✓
Temperature	✗	✓	✓	✓

For the M10 certification, we would like to send the technical document (1) for all the variables, (2) for day and night sounding, and (3) for the whole period ; **except for** temperature where we recommend not to use the daytime launch before June 2023 (new packaging technic), due to possible bias reaching max value around 2°C.

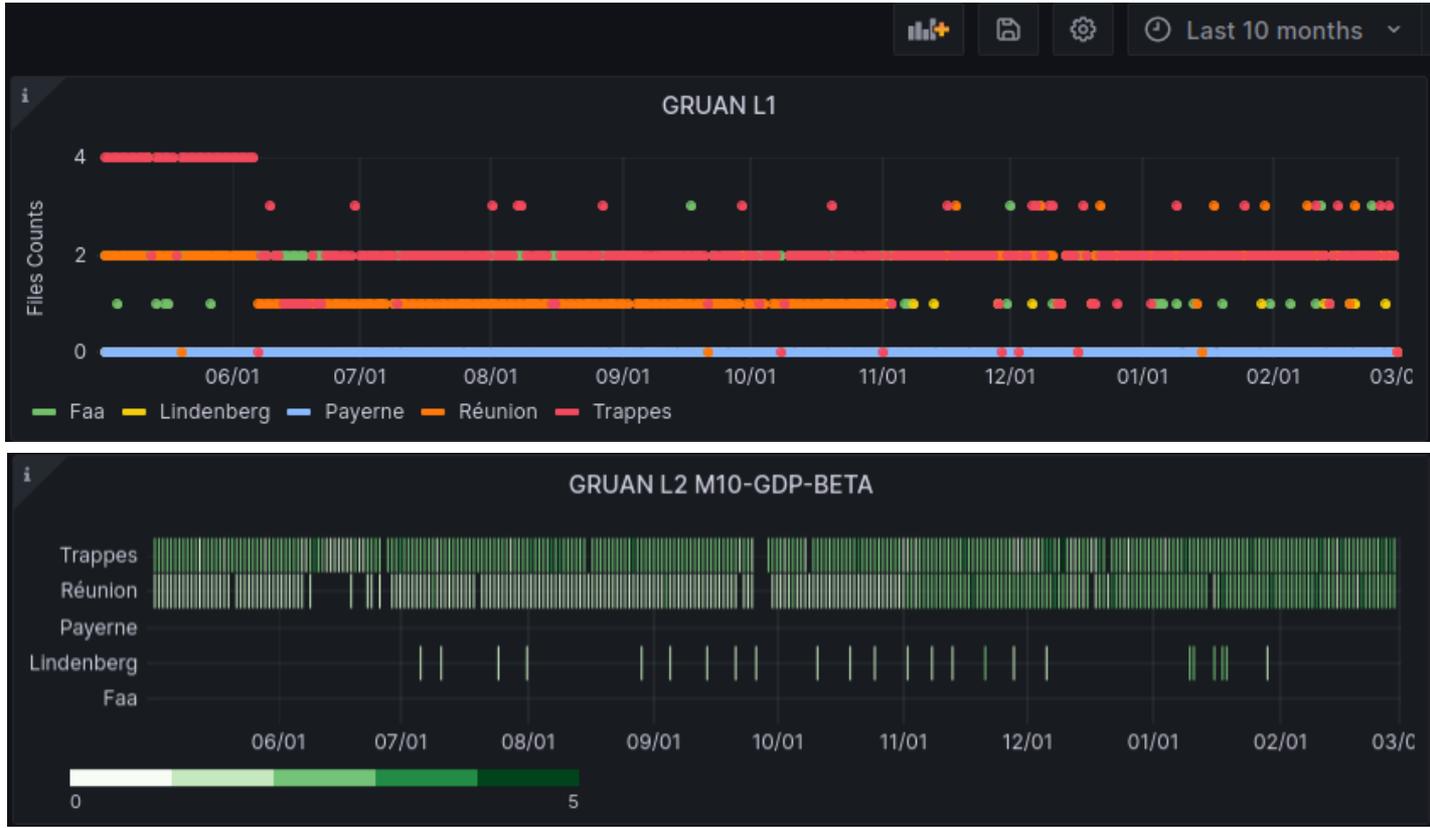
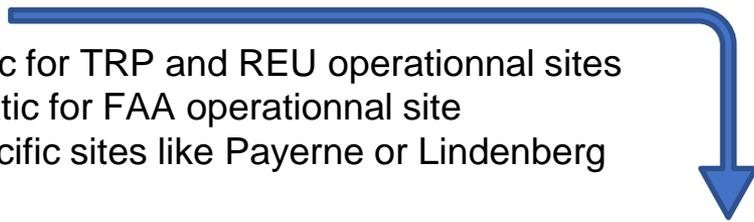
Take home message : if T-sensor is non-damaged and align with the sensor boom, reproducibility is perfect for day & night !

Status of M10 GRUAN Data Product



- M10 dataflow

- M10 GDP production is ensured by AERIS Data Center
- M10 GDP data flow is monitoring with GRAFANA software
- Since more than 2 years, M10-GDP processing is automatic for TRP and REU operational sites
- Since October 2022, M10 L1 Product processing is automatic for FAA operational site
- Since last week, M10-GDP processing is automatic for specific sites like Payerne or Lindenberg

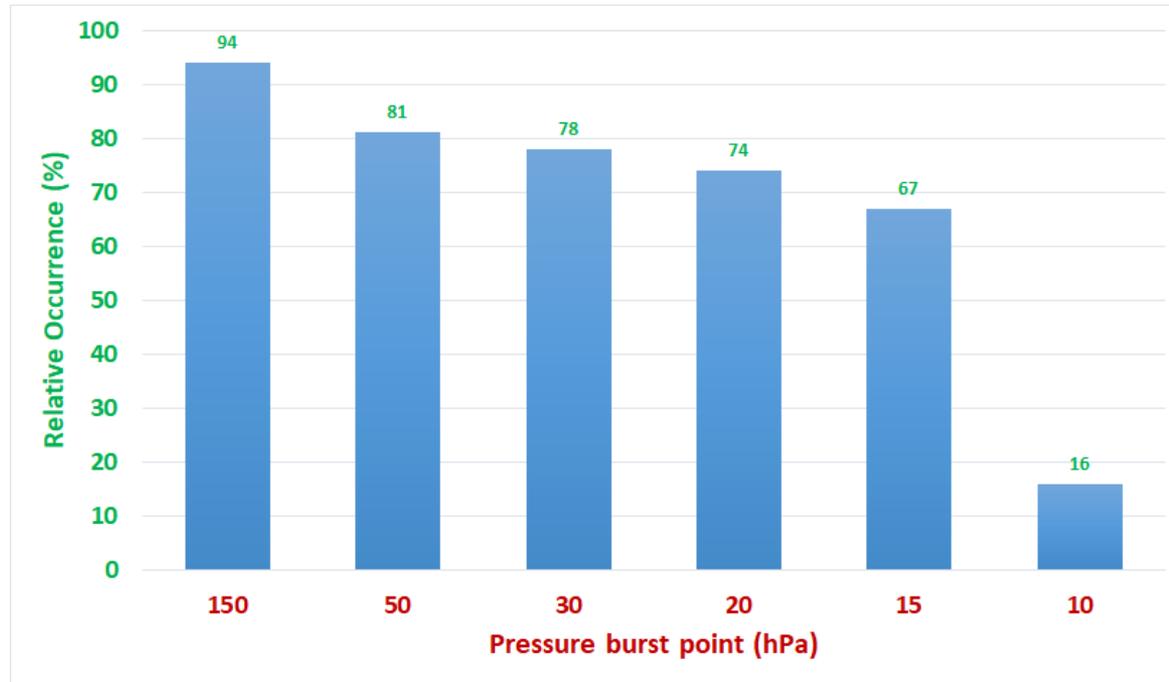


Faa'a statistics since Oct. 2022



MODEM robotsonde since october 2018

... with GRUAN procedures (GC) since october 2022



In 2023 : 703 M20 profiles (raw data availability L1)

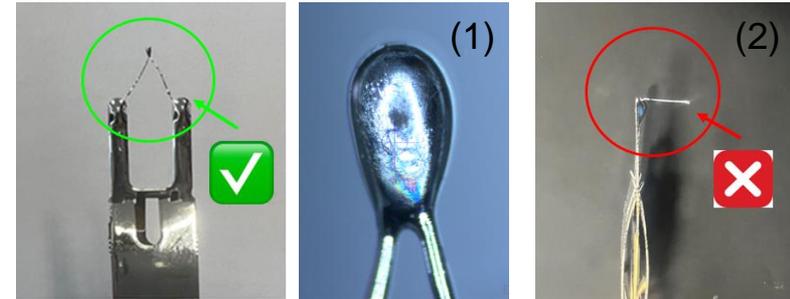
Conclusions



Take Home Message

Reproducibility issue has been identified :

- (1) Coating problem
- (2) Bending problem



AND solutions have been implemented :

- (1) new packaging
- (2) revised set-up before launch



The sensor boom must be at a 45° angle, if it is not the case : (2)

- Carefully adjust the sensor boom to a 45° angle (as illustrated below).

The temperature sensor must be aligned with the sensor boom, if it is not the case :

- Carefully lift and align the temperature sensor with the sensor boom, avoiding contact with the metallization ball (as illustrated below).

- **Step 1**. Find an optimal solution for MODEM M10 GDP certification. We have to take some decisions on :
 - Variables (P, T, U, V)
 - Period (before/after June 2023)
 - Day/Night (solar effect)

⇒ **M10 GDP submission before mid of 2024 !**
- **Step 2**. Start the certification for MODEM M20
- Ensure/Monitor the M10 GDP data flow for operational sites (TRP, REU, ?).
- Ensure/Monitor the M20 L1 data flow for non-operational sites (LIN, PAY, ?).

Questions?

Thank you for your attention

