

# Empirical estimation of uncertainty in radiosondes, radio occultations and model forecast with the Three Cornered Hat method

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ROM SAF

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# Outline

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## Planning ROM SAF CDR v2

### Generalized Three Cornered Hat (G3CH)

Independent data, RO, GRUAN and ERA5 forecast.

ERA5, RO, GRUAN random uncertainty and error correlations

### G3CH on temperature

### Error components

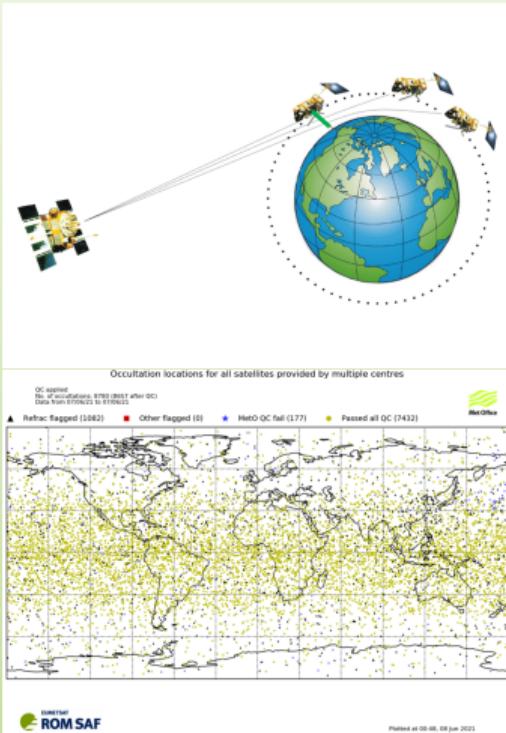
Representativeness uncertainty

Dealing with different vertical footprints

### Results

### Conclusions

# The RO technique



Bending angle → Refractivity

$$N = k_1 \frac{P_{\text{dry air}}}{T} + k_2 \frac{P_{\text{water}}}{T} + k_3 \frac{P_{\text{water}}}{T^2}$$

600-700 daily profiles per LEO

- ▶ Vertical resolution < 250 m
- ▶ Horizontal resolution < 300 km

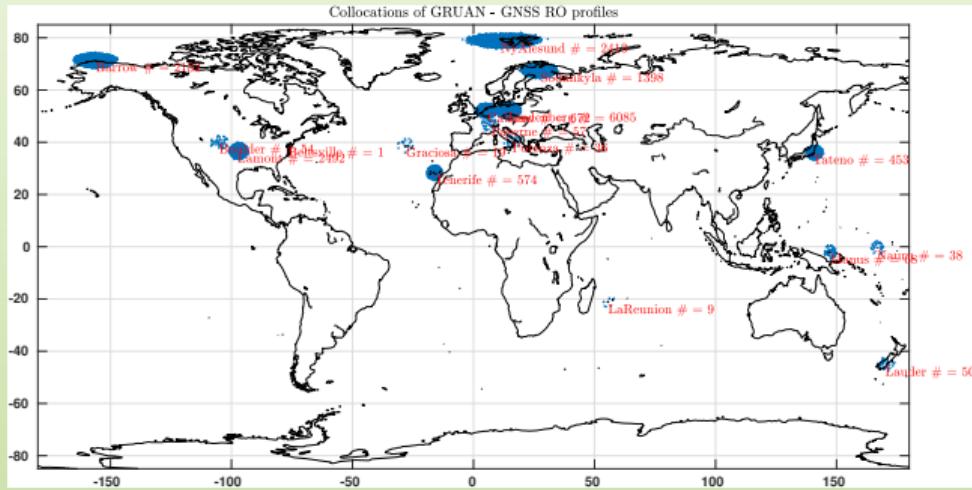
# Planning ROM SAF CDR v2 (2023)

- ▶ Missions: COSMIC 1, Metop A-B-C, CHAMP, GRACE, (Sentinel 6A,... Spire)
- ▶ More than  $10^7$  profiles
- ▶ Time span: 2001-present
- ▶ Variables: Bending angle, Refractivity, Dry temperature, Temperature, Spec. humidity, Pressure, Surface pressure  
+ gridded data
- ▶ GRUAN radiosondes to be used to estimate random uncertainty (error covariance matrices).
- ▶ Improved Level 1A, ionosphere, troposphere, boundary layer parameters, uncertainty and error covariance from 3CH analysis

# Empirical determination of observation error covariance matrices

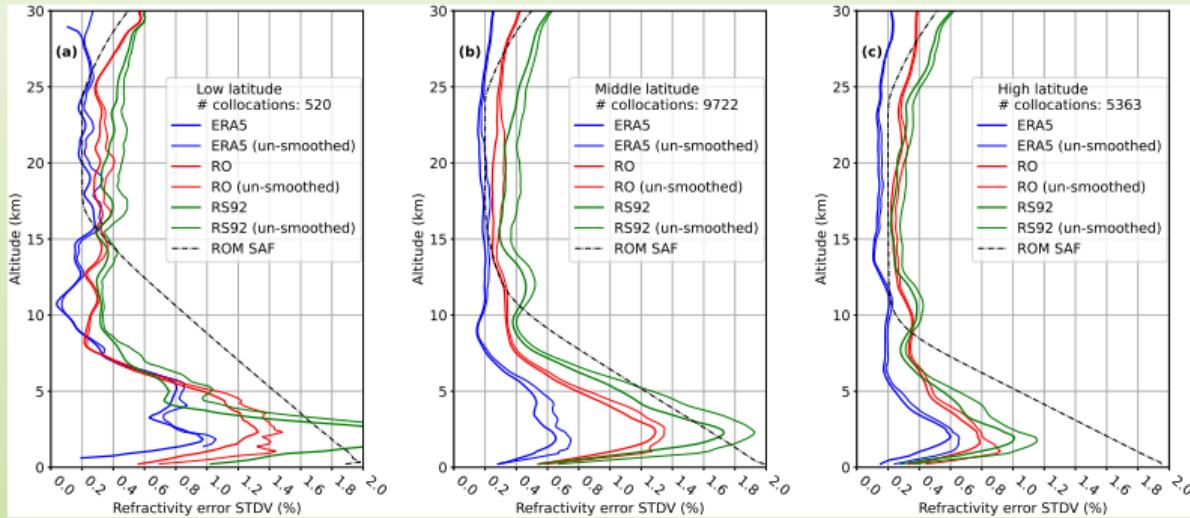
- ▶ Collocated ERA5 **forecast**, GRUAN radiosondes and RO profiles are used to estimate random uncertainty (error covariance matrices) for refractivity and temperature.
- ▶ Three independent data sets meaning: Zero error cross correlation.  
 $\langle \varepsilon_{\text{ERA5}} \varepsilon_{\text{RO}} \rangle = 0, \langle \varepsilon_{\text{RO}} \varepsilon_{\text{GRUAN}} \rangle = 0, \langle \varepsilon_{\text{ERA5}} \varepsilon_{\text{GRUAN}} \rangle = 0$
- ▶ 17552 collocations 2006-2016. dist < 300km, t < 3 h
- ▶ G3CH; algebraic estimation of vertical uncertainty covariance matrices:  
$$\text{Cov}(g) = \frac{1}{2} \langle (g - b)(g - b)^T + (g - r)(g - r)^T - (r - b)(r - b)^T \rangle$$
- ▶ Can in principle handle large bias and random noise of GNSS RO dry temperature

# GRUAN-RO collocations



Night time only

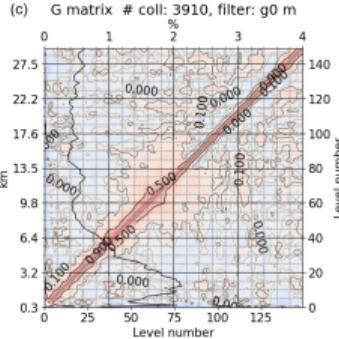
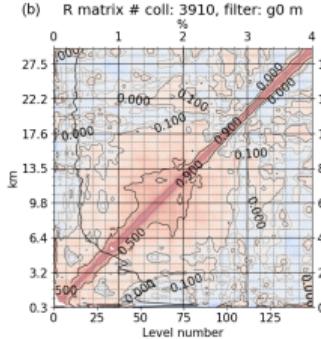
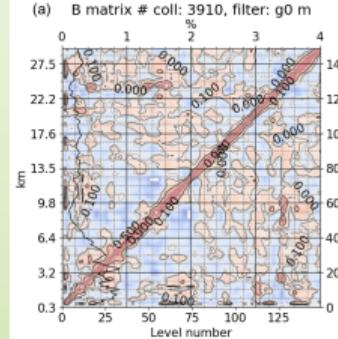
# 3CH estimated random uncertainties



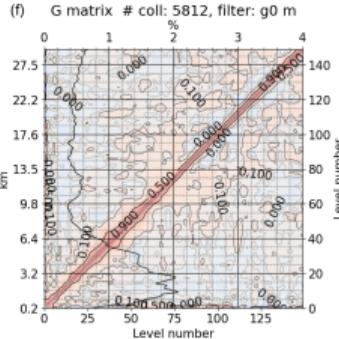
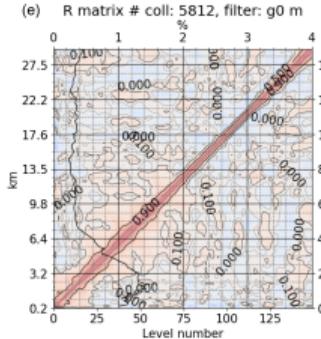
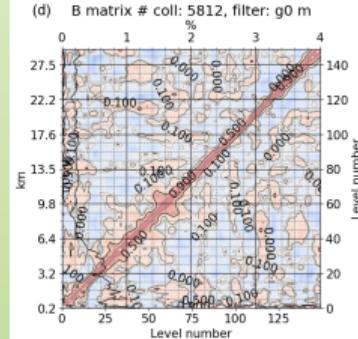
Refractivity uncertainties (standard deviations), for ERA5, RO and RS92, at low (a), middle (b) and high (c) latitudes. Smoothing explanation below. <https://doi.org/10.5194/amt-15-6243-2022>

# G3CH estimate of error covariance matrices

Rising:



Setting:



ERA5 (a,d), RO (b,e)  
and RS92 (c,f)  
refractivity vertical error  
covariance matrices at  
middle latitude, with  
superimposed standard  
deviation as function of  
height (black line).

## Uncertainty validation

Generalized Three Cornered Hat (G3CH)

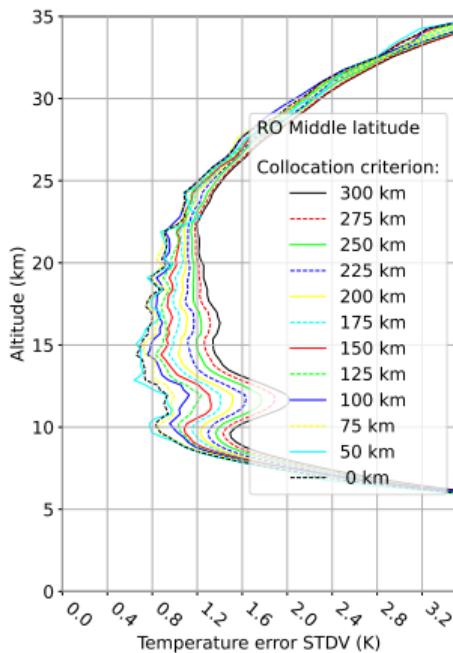
ERA5, RO, GRUAN random uncertainty and error correlations

# Now temperature

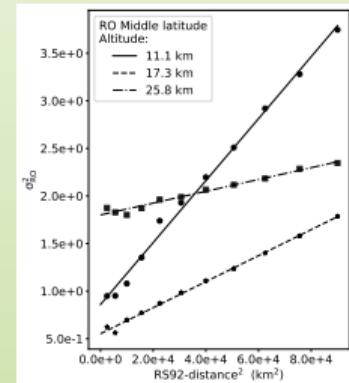
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- ▶ Three temperature data sets: GRAUAN RS92 (GDP.2), ERA5.1 temperature forecast and RO-Dry temperature (Metop and COSMIC missions ).
- ▶ For this presentation ERA5 is interpolated to GRUAN position and time (trajectory center of mass.)
- ▶  $T_{\text{dry}}$  is calculated directly from refractivity, with the assumption that  $q = 0$

# Collocation error

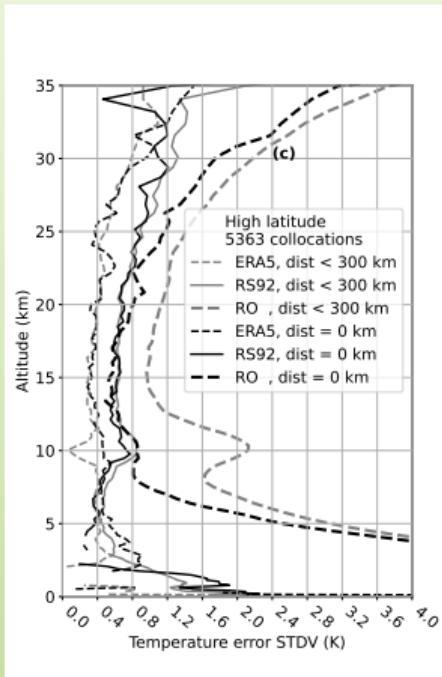
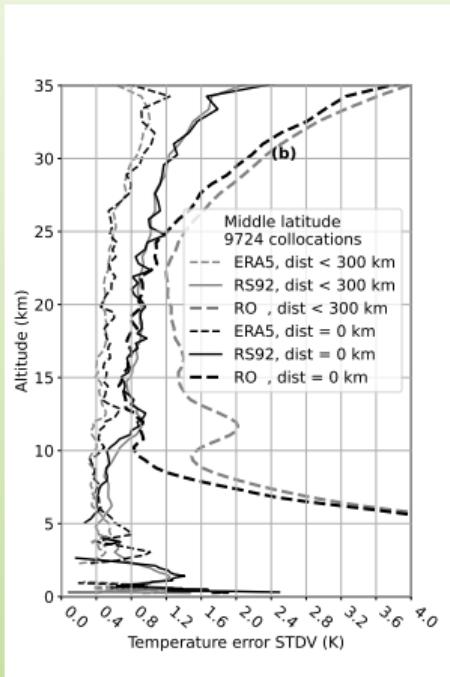


Temperature uncertainty of radio occultations for a series of collocation criteria. Black dashed curve shows extrapolation to zero collocation distance.



Extrapolation of temperature error variance of RO to zero collocation criterion at 3 different altitudes.

# Collocation-corrected uncertainty estimates

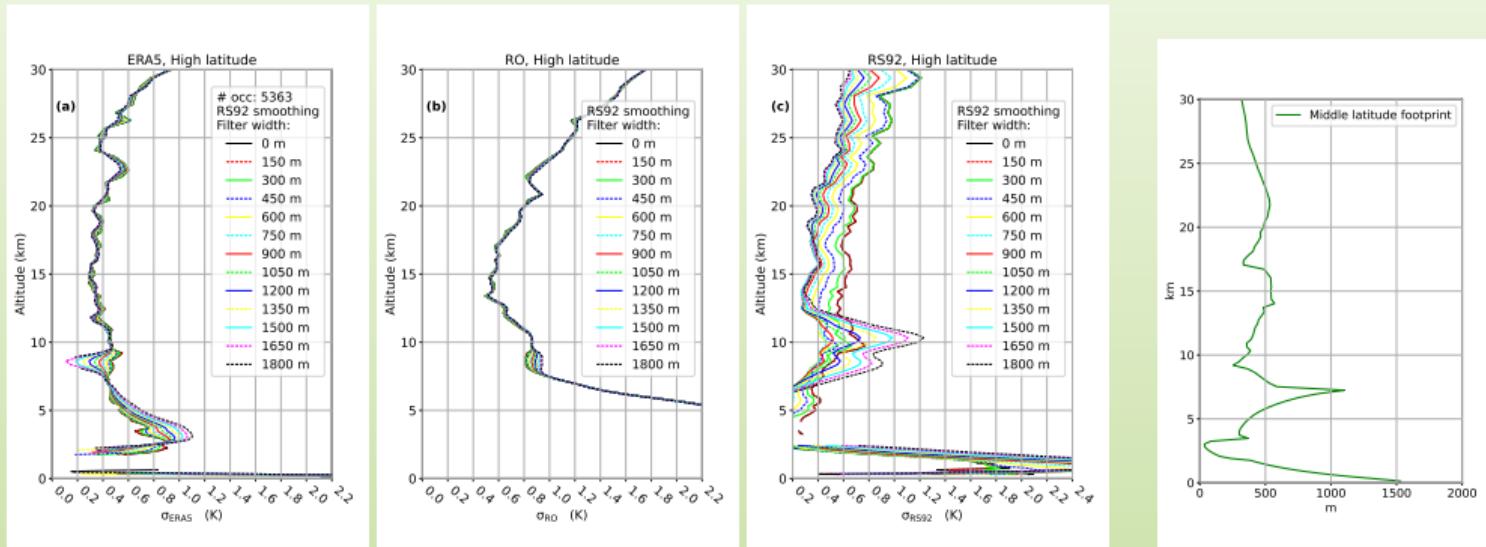


The tropospheric dry temperature uncertainty (RO) is completely overestimated because it includes specific humidity fluctuations.

# The issue with vertical correlations

- ▶ ERA5 footprint > RO footprint > RS92 footprint
- ▶ RS92 is blamed for highly resolved features which are interpreted as noise by the G3CH
- ▶ Method: Filter to the (vertical) footprint least well resolved data set.
- ▶ Uncertainties stated with respect to vertical footprint 500 m

# Effect of smoothing on error standard deviations



Smoothing of RS92 up to 1800 m brings it closer to ERA5, and only slightly further from RO. — Except at the tropopause.

The ERA5 vertical footprint: **Filter width minimizing  $\sigma_{\text{ERA5}}$ , when applied to RO and RS**

# Error components

Raw G3CH yields combination of instrument, representation, collocation and cross correlation errors:

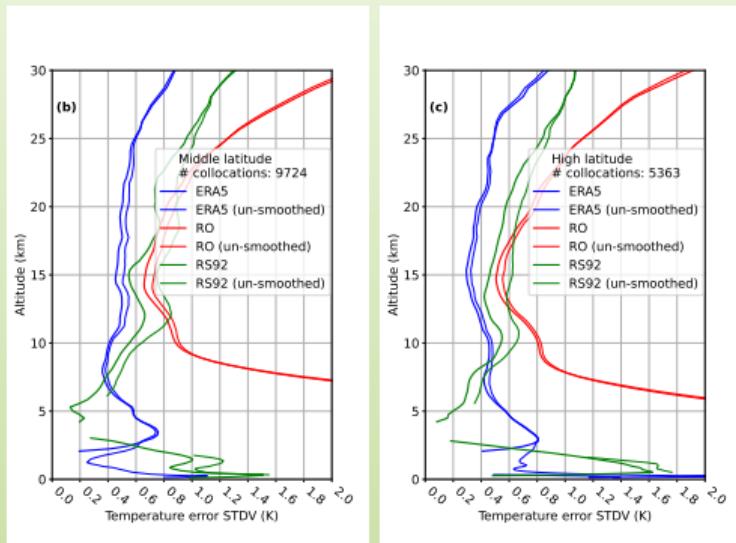
$$\varepsilon_{\text{G3CH}} = \varepsilon^I + \varepsilon^R + \varepsilon^C + \varepsilon^X \quad (1)$$

We are able to remove  $\varepsilon^C$  and the  $\varepsilon^X$  components of the three data sets. So:

$$\varepsilon = \varepsilon^I + \varepsilon^R \quad (2)$$

The final estimate of  $\varepsilon$  is stated with reference to a common vertical footprint of the three data sets, determined by the data set with the largest vertical footprint, ERA5. There is still a residual representativeness uncertainty due to different geometries of measurements.

# Results: Temperature STDV and vertical correlations.



The estimated RS92 temperature random uncertainty: green thick curve.  
ERA5 and RO have comparable horizontal footprints, hence 3CH attributes the residual representativeness uncertainty component to RS92.

# Conclusions

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- ▶ Uncertainty estimates of ERA5, RO and RS92 temperatures have been obtained.
- ▶ Collocation and vertical footprint issues have been handled
- ▶ Residual representativity RS92 uncertainty is due to sub-grid horizontal inhomogeneity
- ▶ Uncertainty must always be related to footprint in time and space.