

RS41GDP / RS92GDP First comparison results

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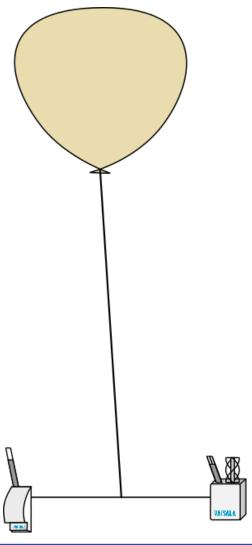
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Content



- Why do we need the comparison?
- Uncertainties handling
- Launch point problem for synchronization
- Temperature comparisons
- Relative humidity
- Pressure and Altitude
- Wind speed
- Outlook

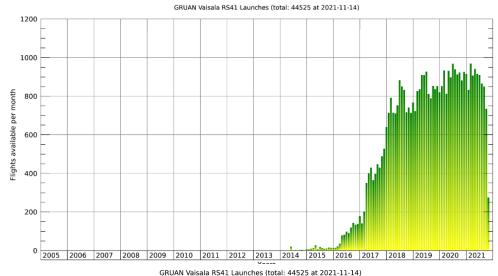


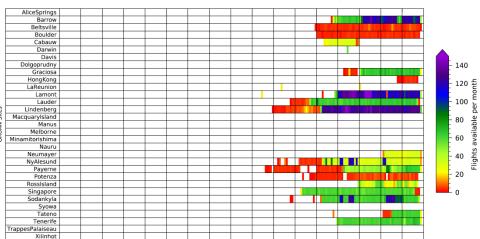


Why RS41 and RS92?



- RS41 is the follow-up radiosonde to the RS92
- RS92 used in 18/31 GRUAN sites
- RS41 used in 19/31 GRUAN sites
- For both sondes manufacturer created EDT products are available
- For both sondes GRUAN GDP's are created
- GDP's contain all measurements +
 estimated uncertainty budgets





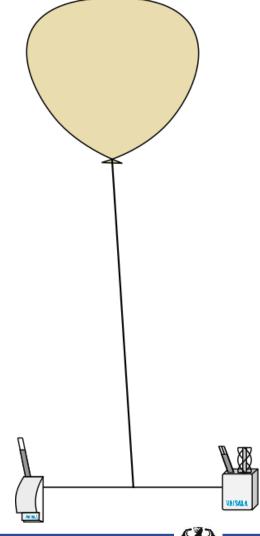


Available data and handling



- Each profile divided into layers 1km thick*
- Values averaged in each layer in each profile
- Values for all profiles for each station averaged for each layer
- Estimated uncertainties
 from GDP's

Station	N of flights
Lindenberg	276
Payerne	136
NyAlesund	112
Darwin	52
Neumayer	26
Lamont	9
Tateno	8





Simple scheme of uncertainties

Point in profile

Layer in profile

All profiles

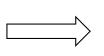


uncorrelated

(random)

correlated

(systematic)



$$u_{ucorr} = \int \sum u_{ucorr}^2$$

$$\sum u_{ucorr}^2$$



$$u =$$

$$= \sqrt{u_{ucorr}^2 + u_{corr}^2}$$

Only full uncertainties shown on plots



All profiles for Lindenberg

Blue points and blue uncertainties from <u>GDP</u> comparison! Red points from <u>EDT</u> comparison.

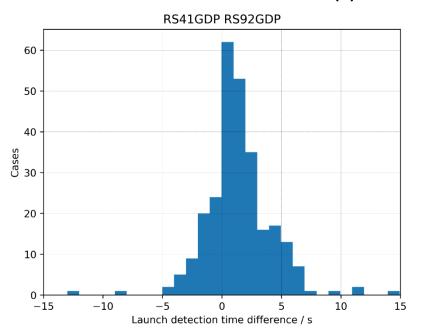


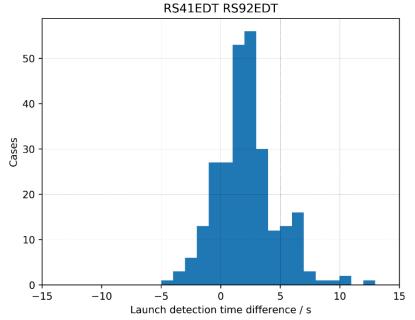
Launch point detection

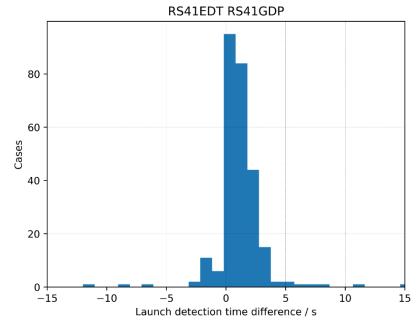


Independent launch detection for RS41GDP from RS41EDT. RS92GDP uses RS92EDT launch detection.

- Gaussian distribution figures from 276 flights from Lindenberg
- Differences up to 150s (!)
- Dependent on station when RS41SGP is used, launch detection is from pressure sensor
- EDT's at 2s resolution (!)







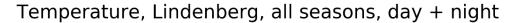


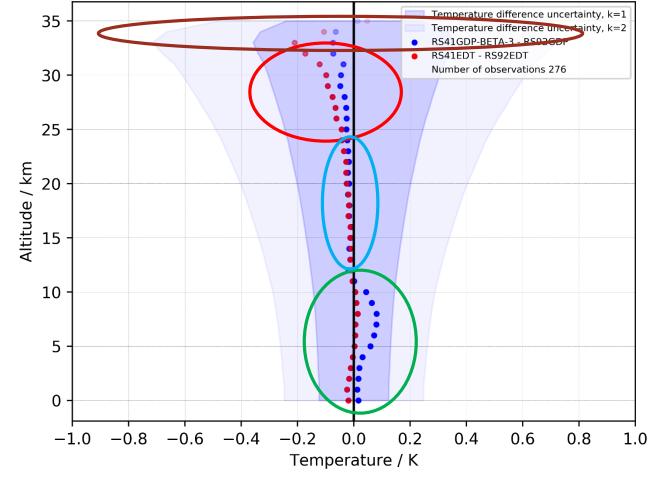
Effects on temperature



Observed features in the comparison:

- Top of profiles night flights reach higher altitudes more often, which decreases overall uncertainty
- Middle stratosphere differences in radiation corrections
- Lower stratosphere little to no bias between RS41 and RS92
- Troposphere time lag difference between RS41 and RS92 temperature sensors









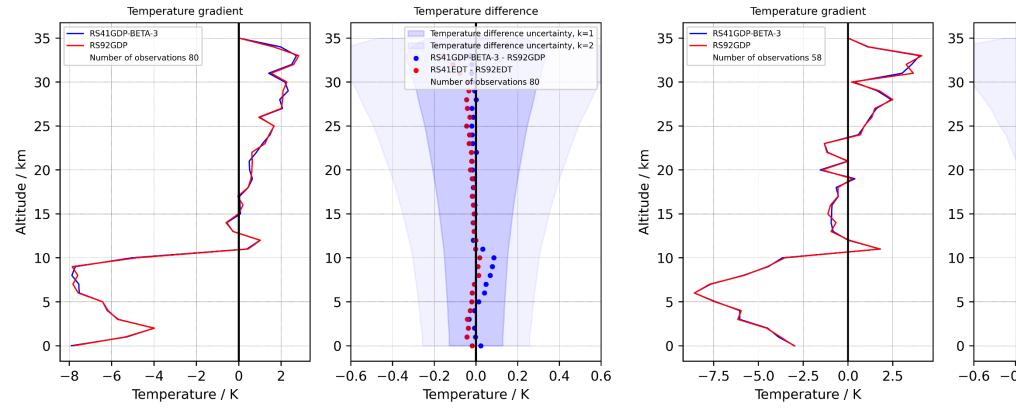
Time lag in the troposphere

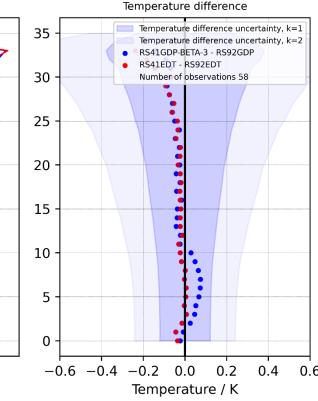


- Time lag dependent on the gradient in the Troposphere
- The effect disappears at the Tropopause, which is dependent on the season

Lindenberg, summer, day + night

Lindenberg, winter, day + night



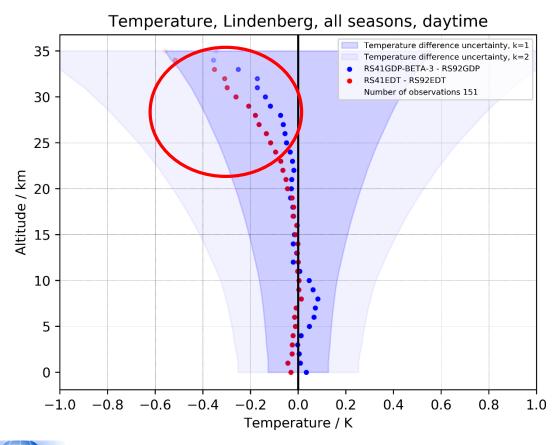


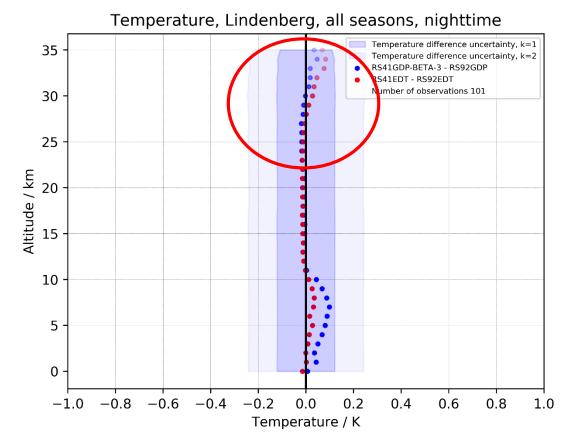


Radiation influence on temperature



• Larger radiation corrections for both RS92 products, compared to the RS41 data







Temperature processing differences



RS92GDP:

- Sensitivity estimated from experiments in radiation chamber at various **p** and **v**
- Solar radiation from RTM, based on **solar elevation**
- Use of a look-up table with pre-computed (simulated)
 cases -- but only a few different cases

RS41GDP:

- Sensitivity of T-sensor to solar radiation measured with SISTER as function of *p*, *v*, the combination of *boom angle* and **solar elevation**, and as averaged effect over a <u>rotating</u> sonde
- Solar radiation from RTM
- online simulation of each flight case (up to 100 simulations per flight because change of time and solar angles)

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Laboratory characterisation of the radiation temperature error of radiosondes and its application to the GRUAN data processing for the Vaisala RS41

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Abstract.

The paper presents the Simulator for Investigation of Solar Temperature Error of Radiosondes (SISTER), a setup that was developed to quantify the solar heating of the temperature sensor of radiosondes under laboratory conditions by recreating as closely as possible the atmospheric and illumination conditions that are encountered during a daytime radiosounding ascent.

- 5 SISTER controls the pressure (3 hPa to 1020 hPa) and ventilation speed of the air inside the windtunnel-like setup to simulate the conditions between the surface and 35 km altitude, to determine the dependence of the radiation temperature error on the irradiance and the convective cooling. The radiosonde is mounted inside a quartz tube, while the complete sensor boom is illuminated by an external light source to include the conductive heat transfer between sensor and boom. A special feature of SISTER is that the radiosonde is rotated around its axis to imitate the spinning of the radiosonde in flight. The characterisation
- of the radiation temperature error is performed for various pressures, ventilation speeds and illumination angles, yielding a 2D-parameterisation of the radiation error for each illumination angle, with an uncertainty smaller than 0.2K (k = 2) for typical ascend speeds. This parameterisation is applied in the GRUAN processing for radiosonde data, which relies on the extensive characterisation of the sensor properties to produce a traceable reference data product which is free of manufacturer



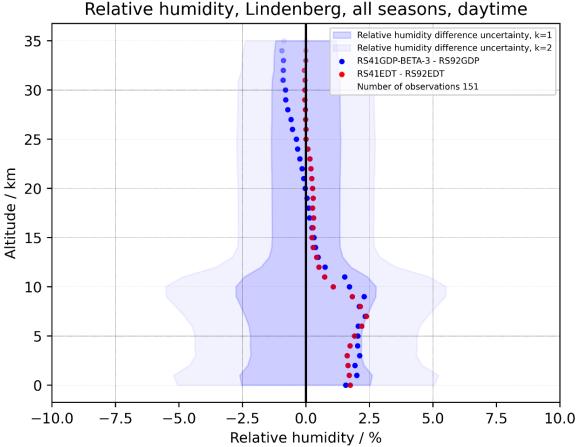


Relative humidity comparisons

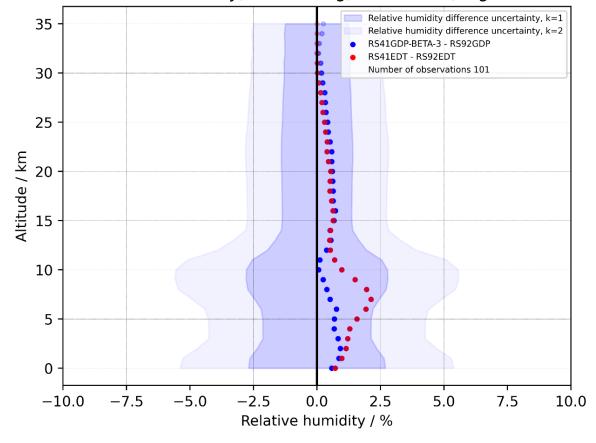


• Influence of time lag in the Troposphere





Relative humidity, Lindenberg, all seasons, nighttime



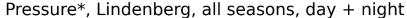


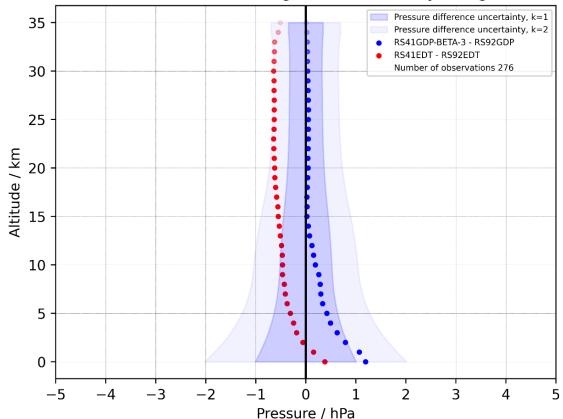


Altitude and Pressure differences



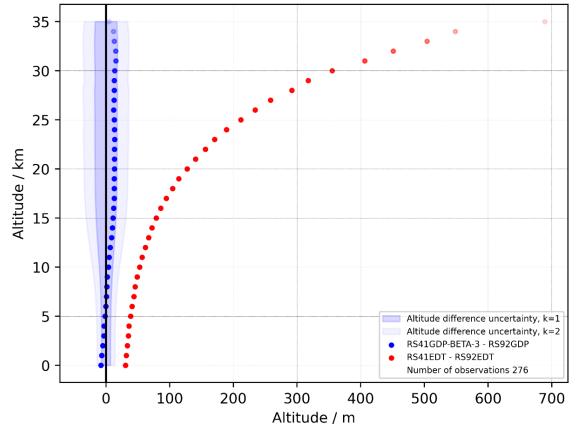
- RS41GDP uses EGM2008 geoid
- RS92GDP uses EGM96 geoid





- RS41EDT uses EGM96 geoid (?)
- RS92EDT uses WGS84 ellipsoid (?)

Altitude*, Lindenberg, all seasons, day + night





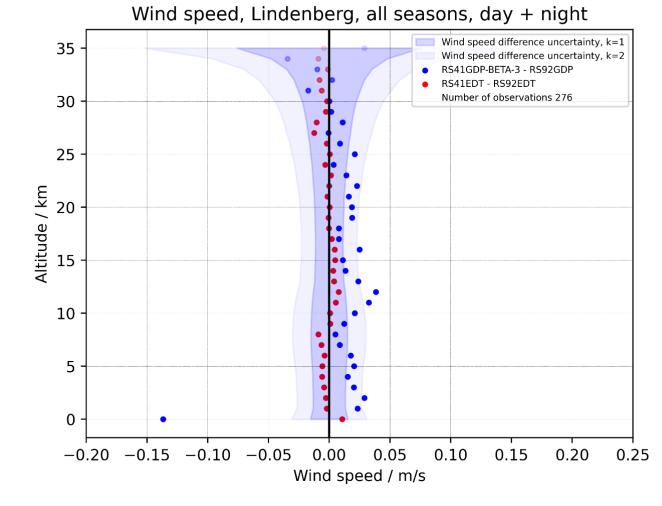


Wind speed comparisons



Observed features in the comparison:

- Small uncertainties, since all uncertainties are uncorrelated
- Both EDT wind speed calculated from Doppler GPS observations
- Both GDP wind speed calculated from differences between absolute positions
- Small differences in results for all sites and all seasons





Summary and outlook



- First results from comparison from all GRUAN sites
- Temperature and relative humidity comparisons to be published in paper for the RS41GDP certification
- Further paper on pressure,
 coordinates and wind to follow

