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Conclusions

Update on RS92 -> RS41 transition Statistical analysis

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ICM10 - Potsdam, 24 April 2018



At ICM-9 I addressed the following question:

Do we have an universal formula

for harmonizing Vaisala transition ?

and I discussed the following points:

- 1. Use of GDP measurement uncertainty
- 2. Role of vertical correlation
- 3. Bias assessment using heteroskedastic local polynomial least squares.
- 4. Bias adjustment and harmonization

Dataset of dual soundings

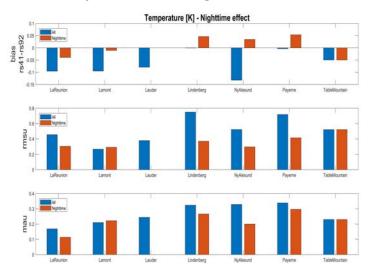
RS41-EDT.1 vs RS92-GDP.2



Site	Num of colocations						
	24 h	Nighttime					
LAU	49						
LIN	186	77					
NYA	114	17					
PAY	110	49					
REU	18	9					
SGP	16	6					
TMF	17	17					
	510	175					

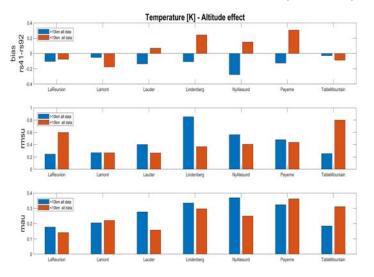
Nighttime: $SEA < -10^{\circ}$

Temperature - Nighttime effect



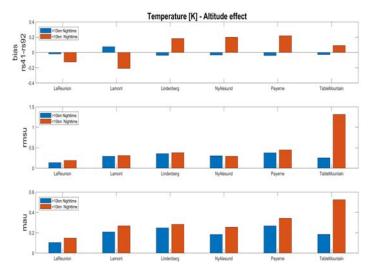
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Temperature - Altitude effect (alldata)

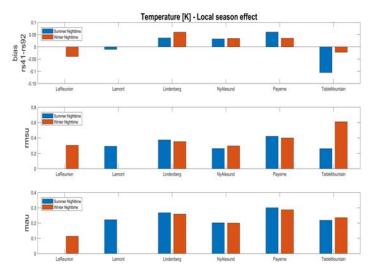


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Temperature - Altitude effect (Nighttime)



Temperature - Season effect

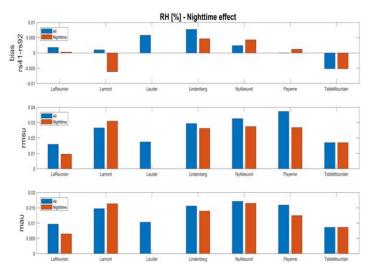


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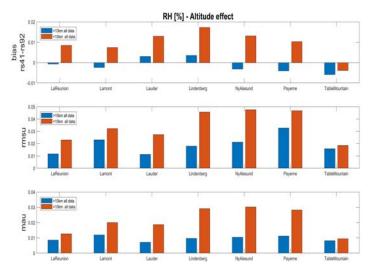
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Humidity - Nighttime effect

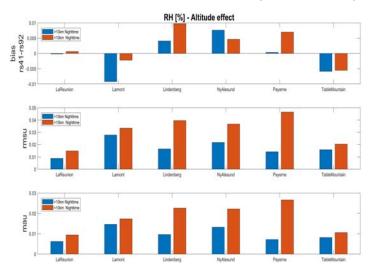


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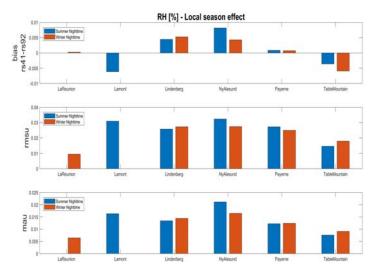
Humidity - Altitude effect (alldata)



Humidity - Altitude effect (Nighttime)



Humidity - Season effect



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Modelling of bias (T&q)

We assume that RS41-RS92 difference at altitude (h) is such that

bias(h) = E (measurement difference |local conditions)

=> a smooth function of altitude (h) and, => a locally-linear function of solar elevation angle (SEA) :

$$b\left(h\right) = \alpha\left(h\right) + \beta\left(h\right) SEA^{*}\left(h\right)$$

where

$$\mathit{SEA}^* = \left\{ egin{array}{cc} \mathit{SEA} + 10 & \mathit{Day}: \mathit{SEA} > -10^\circ \\ 0 & \mathit{Night}: \mathit{SEA} < -10^\circ \end{array}
ight.$$

=> No assumptions about smoothness of measurements are made.

Conclusions

Using uncertainty of GDP

• Having detailed measurement uncertainties is not only important from metrological point of view but it is also important for data analysis, either climate & trend analysis or measurement and networks quality understanding.

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- In practice we move

from simple average $\bar{y} = \frac{1}{n} \sum_{i=1}^{n} y_i$ to weighted average $\bar{y}_w = \frac{1}{u_{TOT}^{-1}} \sum_{i=1}^{n} y_i u_i^{-1}$

In fact if $Var(y_i) = u_i^2$, \bar{y}_w is the optimal estimator of $E(y_i)$.

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• Some results in the following pictures ...



Methods

For each site, bias at altitude h is denoted by b(h) and is obtained by minimizing

$$\sum_{i,j} \left(y_{i,j} - b\left(h\right) \right)^2 K_{\lambda} \left(h_i - h\right) \omega_{ij}$$

where

j = 1, ..., N (# of co-locations) $i = 1, ..., n_j$ (# of measurements of co-location j) h_i = altitude of measurement $y_{i,j}$ K = Gaussian kernel with bandwidth λ ($\lambda = 100m$) $\omega \propto uncertainty^{-1}$ Vertical correlation taken into account in IC's of α and β

Vertical correlation not taken into account in averaging and/or estimation

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About vertical correlation

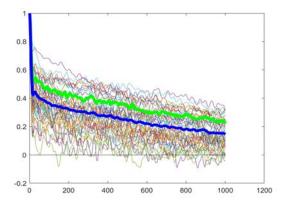


Figure: Lauder temperature-difference vertical correlation.

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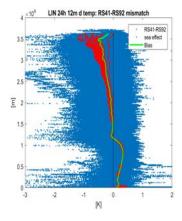
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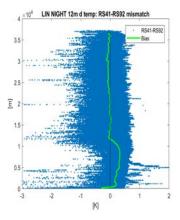
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Temperature SEA & Nighttime (1/3)





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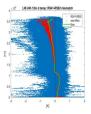
T profiles

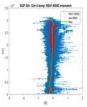
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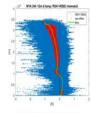
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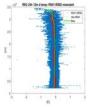
Conclusions

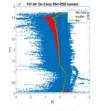
Temperature SEA & Nighttime (2/3)

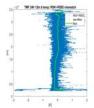


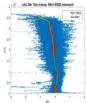












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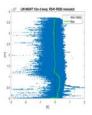
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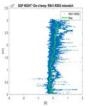
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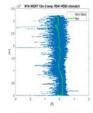
Harmonization

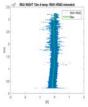
Conclusions

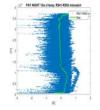
Temperature SEA & Nighttime (3/3)

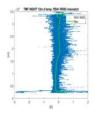












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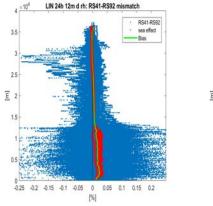
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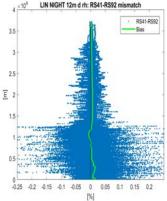
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Humidity SEA & Nighttime (1/3)





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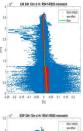
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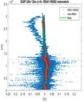
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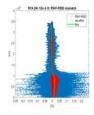
Harmonization

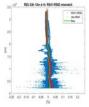
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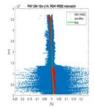
Humidity SEA & Nighttime (2/3)

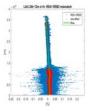


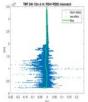












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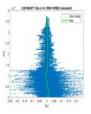
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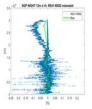
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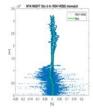
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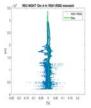
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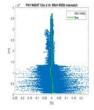
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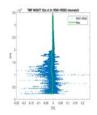












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Harmonization

• Local (in situ) bias reduction using in situ DS data.





Harmonization

- Local (in situ) bias reduction using in situ DS data.
- Global bias reduction using a "sufficiently representative" DS network



Harmonization

- Local (in situ) bias reduction using in situ DS data.
- Global bias reduction using a "sufficiently representative" DS network
- Local "out of situ" bias reduction ?



• The dataset for each single site is randomly divided in two parts:



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1. Estimation dataset (70%)



- The dataset for each single site is randomly divided in two parts:
 - 1. Estimation dataset (70%)
 - 2. Validation dataset (30%)



- The dataset for each single site is randomly divided in two parts:
 - 1. Estimation dataset (70%)
 - 2. Validation dataset (30%)
- The above SEA model is estimated on the first and applied to the second one

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Temperature Harmonization Lindenberg valid. data

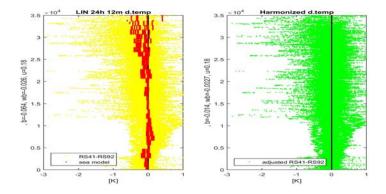


Figure: Left: differences and SEA effect in red. Right: differences after harmonization.

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Temperature Harmonization Payerne valid. data

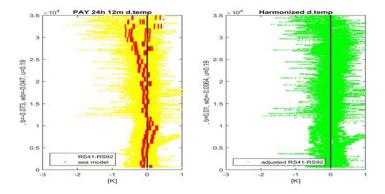


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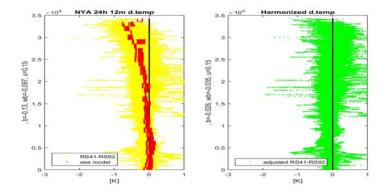


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RH Harmonization

LIMITED VALUE of RH CORRECTION

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Conclusions (1/2)

• Temperature



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- Temperature
 - 1. Total co-loc uncertainty

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Conclusions (1/2)

- Temperature
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1.1 Lower nighttime (solar radiation effect).

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Conclusions

- Temperature
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 - 1.1 Lower nighttime (solar radiation effect).
 - 1.2 Higher in upper atmosphere (solar radiation). Not relevant nighttime.

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- Temperature
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Conclusions (1/2)

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2.1 RS41 is warmer in lower atmosphere (also nighttime).

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 - 3. Possible attenuated effect in the tropics (REU) but little data.

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 - 3. Possible attenuated effect in the tropics (REU) but little data.
 - 4. Limited seasonal effect nighttime.
 - 5. Harmonization (bias reduction) is possible in-situ provided a representative network of DS is available.



Conclusions (2/2)

• Humidity



- Humidity
 - 1. Total co-loc uncertainty



Conclusions (2/2)

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- Humidity
 - 1. Total co-loc uncertainty
 - 1.1 Lower in upper atmosphere.



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Conclusions (2/2)

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Conclusions (2/2)

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RS41 is wetter in lower atmosphere daytime; limited difference nighttime.

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Conclusions (2/2)

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- 4. Limited seasonal effect nighttime

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THANKS FOR YOUR ATTENTION