

GNSS & ATOMMS RO and GRUAN

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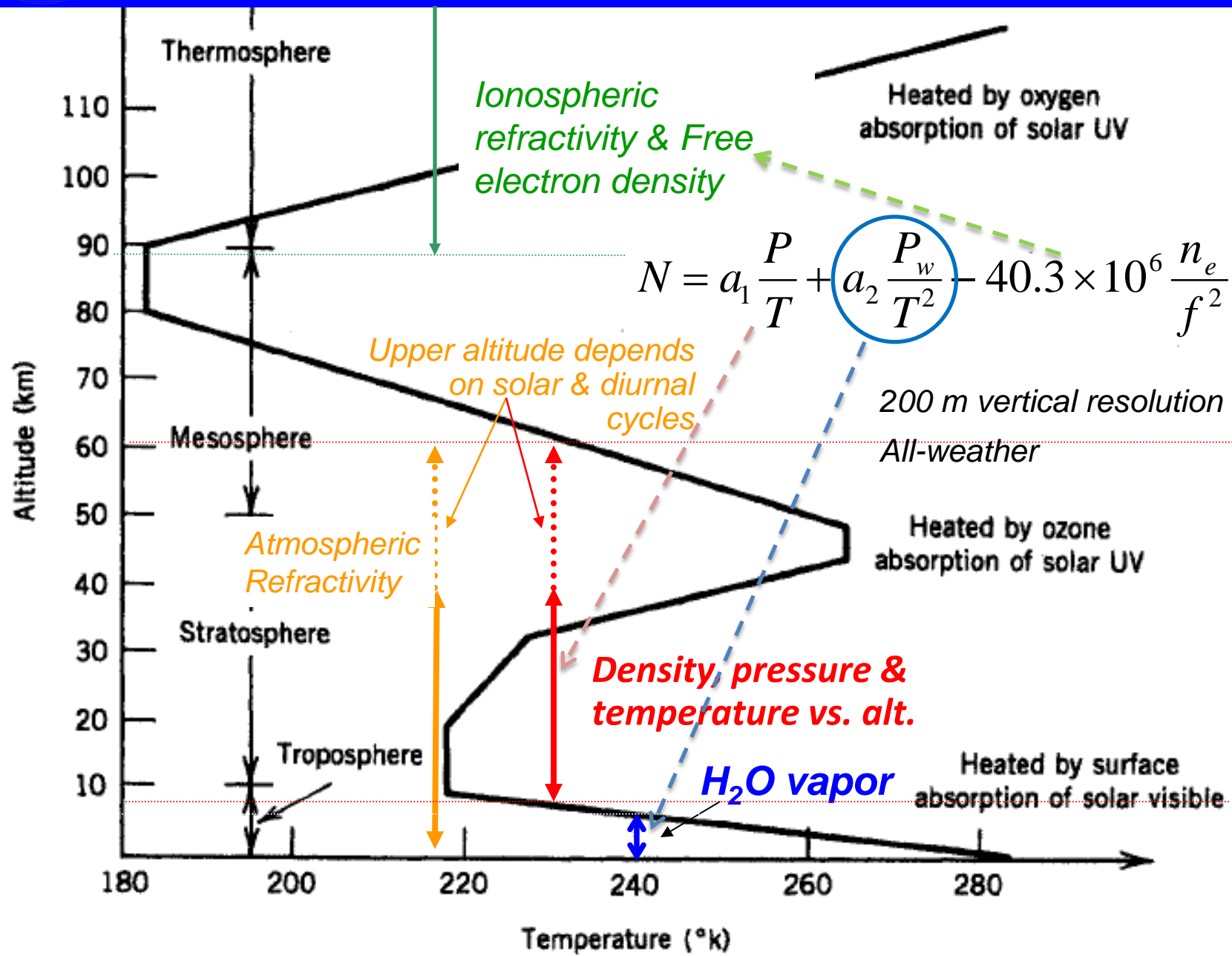
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Special thanks to Feiqin Xie (Texas A&M) & Mark Ringer (Met Office)

Outline

- GPS RO temperature items
- GPS RO error deconvolution
 - Description
 - Specific & relative humidity
 - Temperature dependence of negative tails
- 183 GHz spectroscopy
- Challenge of validating water vapor

GNSS RO Information vs. Altitude





Upper Altitude Boundary Condition

density ← retrieval — bending angle

$$n(a) = \exp \left[\frac{1}{\pi} \int_a^\infty \frac{da'}{\sqrt{a'^2 - a^2}} \alpha(a') \right]$$

Refractive index Impact parameter $a = n(r) r$ Bending angle

Old way:

- Calculate density by extrapolating noisy measurements vertically, or using a model
- Form monthly means of density

E.g. higher than 50 km

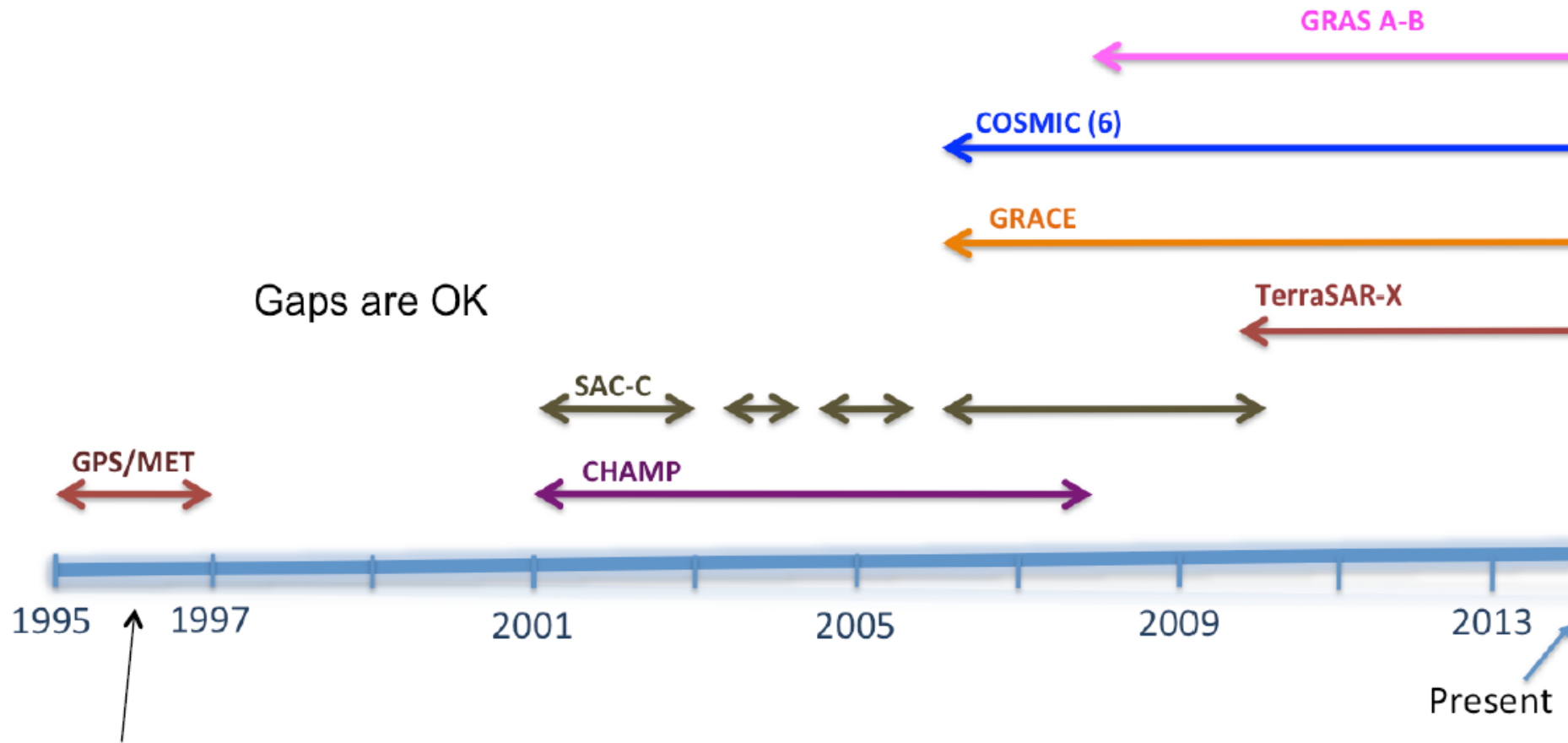
New way:

- Calculate monthly means of bending angle
- Extrapolate monthly mean bending angle vertically

Ao, C. O et al., GRL 2012



Plans for A GNSS-RO Data Set



Developing single-frequency processing

Two Methods for Extracting Water Vapor from GPS RO Refractivity Profiles

1. Direct Method: $N_{wet} = N_{tot} - N_{dry}$

- Determine dry refractivity (N_{dry}) from analysis temperature profile and hydrostatic equation
- Scale N_{wet} to get water vapor

2. (1D) Variational Method

- Combine GPS refractivity with
 - Analysis temperature & water vapor profiles and surface pressure
 - and error covariance estimates
- ⇒ Over-determined, least squares solution

Advantages of Direct Method:

- Not affected by biases in background water vapor forecast/analysis
- Can derive water vapor information to higher altitudes

Negative q and Error Deconvolution

Direct Method can and does produce negative q estimates

=> Produces an unphysical, negative tail in the q histograms

- This can be fixed by deconvolving the error distribution from histograms

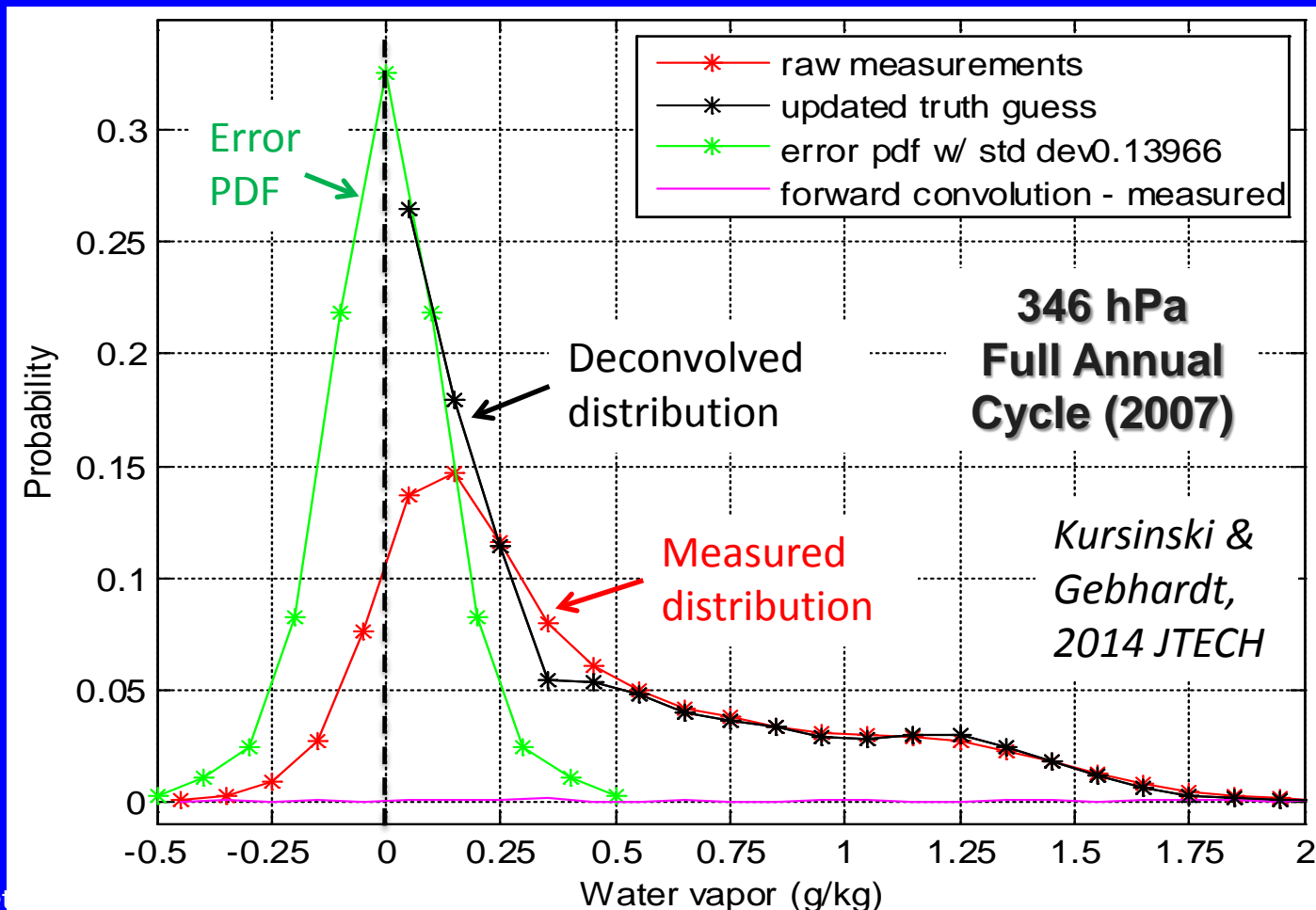
- Linearize error model: $q_{measured} = q_{true} + \varepsilon_q$
- Measured histogram (PDF) is then the convolution of the true PDF and the error PDF

$$PDF_{q_{meas}} = PDF_{q_{true}} \otimes PDF_{\varepsilon}$$

- If we understand the error PDF, we can then deconvolve it from the measured PDF to recover the true PDF
 - Negative tail tells us shape of the error distribution
- Described in Kursinski & Gebhardt (2014) in JTECH

Error Deconvolution Low Latitude

- Adjust (1) (symmetric) Error PDF & (2) “true” q distribution PDF,
- Convolve them to generate estimate of “measured” PDF,
- Iterate adjustments until best fit to measured PDF is achieved



Random Error Deconvolution Method

- X = true water vapor distribution
- D = measured water vapor distribution
- A = convolution process that maps true distribution to measured distribution

$$D = A(X)$$

- Linearize the problem writing it as

$$D = A X$$

- A is now a matrix such that $A X$ represents the process of convolving the true moisture PDF with the error PDF.
- We want to find a forward convolved D' that closely approximates the measured D
- To find D' , we minimize the difference between D' and D by iteratively adjusting A and X

Random Error Deconvolution Method

- Expand D' around most recent estimate, $D'_0 = A_0 X_0$
 $D' = (A_0 + \Delta A) (X_0 + \Delta X) = A_0 X_0 + A_0 \Delta X + \Delta A X_0 + \Delta A \Delta X$
- Linearize: drop last term which is 2nd order

- Want to minimize the difference: $D' - D$

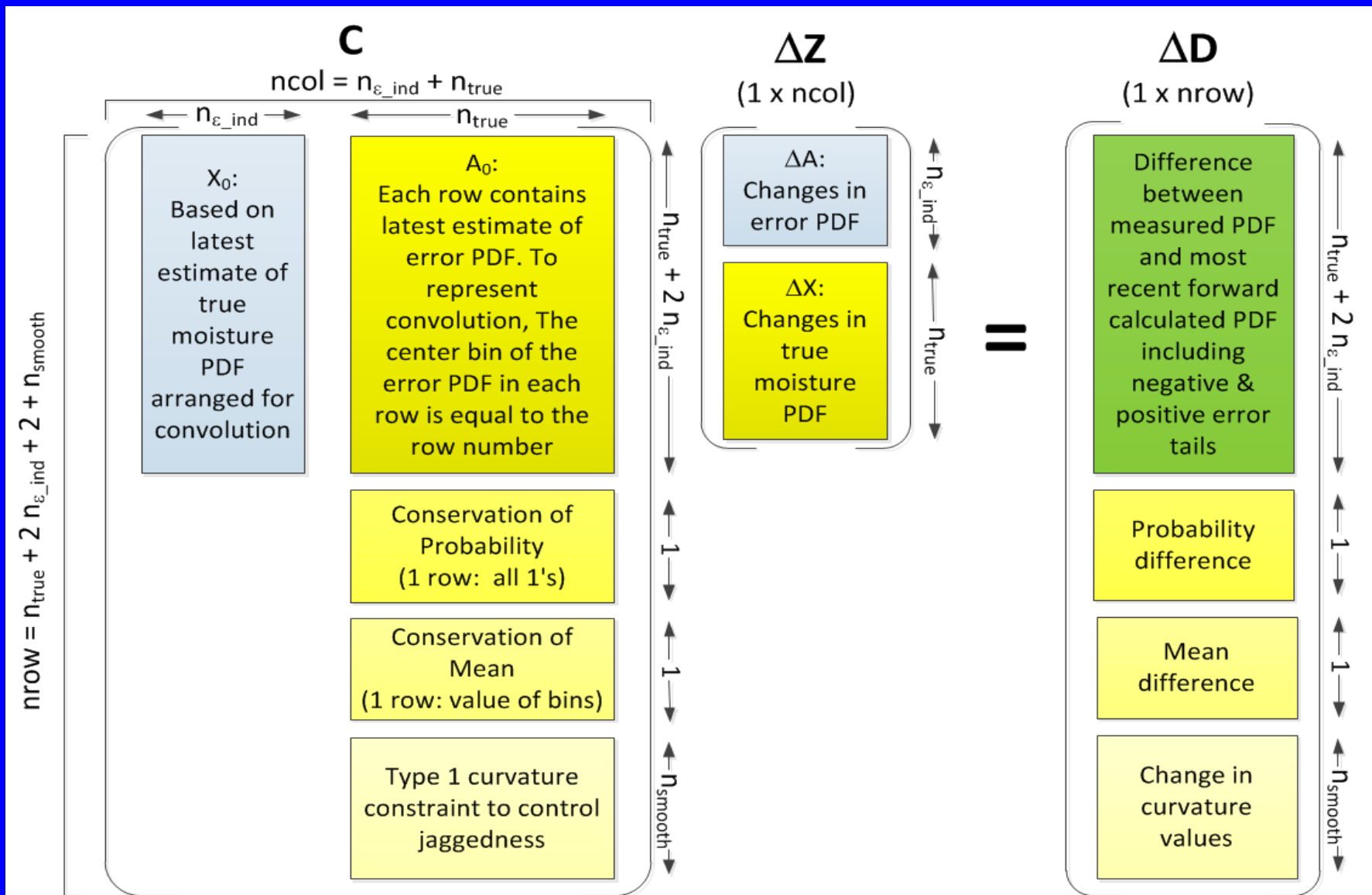
$$D' - D = A_0 X_0 + A_0 \Delta X + \Delta A X_0 - D$$

- Each iteration, find ΔX and ΔA such that

$$D - D'_0 = \Delta D = A_0 \Delta X + \Delta A X_0$$

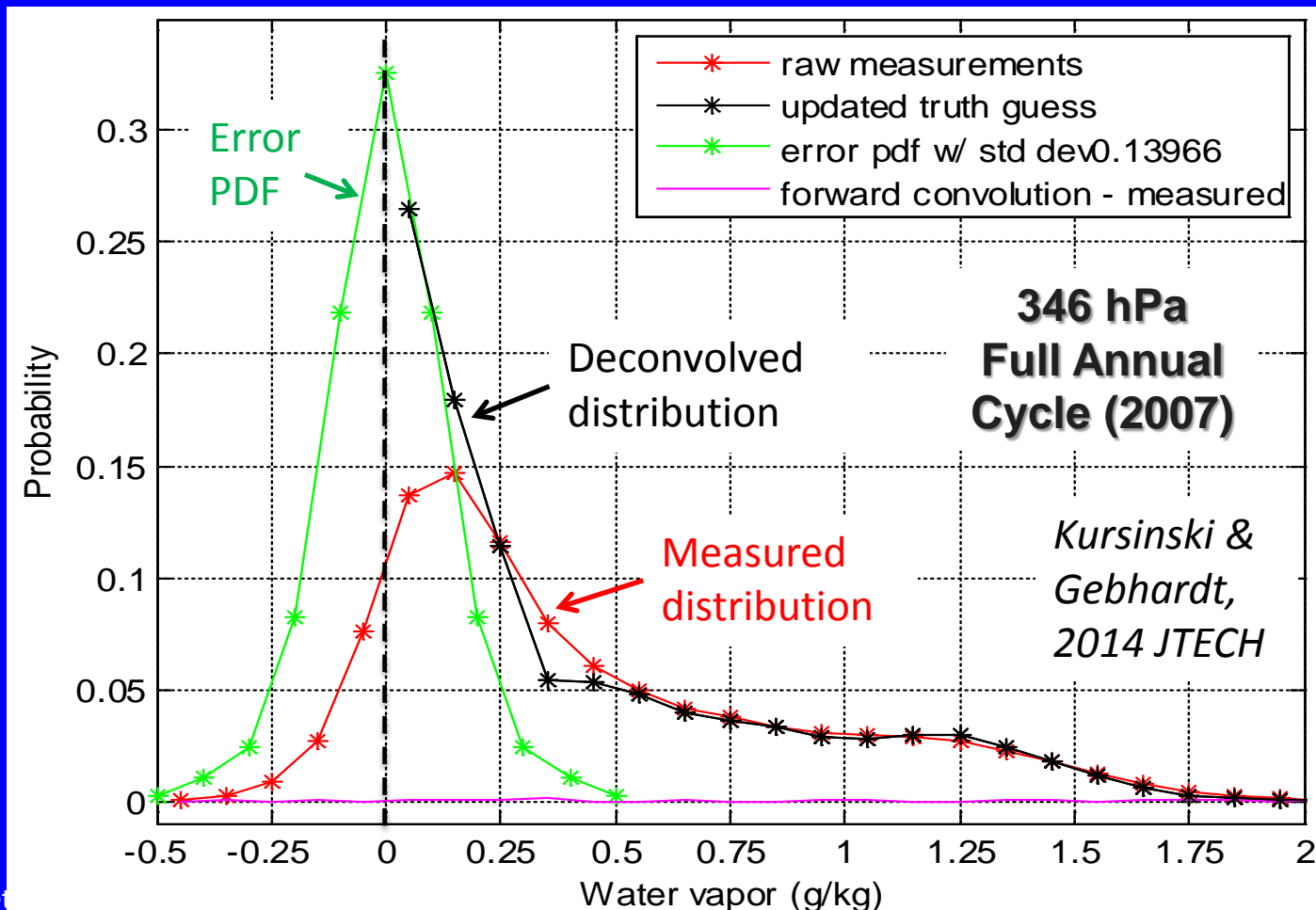
- Each iteration, find least squares solutions for ΔX and ΔA
- Then update D'_0 and do the next iteration

Random Error Deconvolution Method



Error Deconvolution Low Latitude

- Adjust (1) (symmetric) Error PDF & (2) “true” q distribution PDF,
- Convolve them to generate estimate of “measured” PDF,
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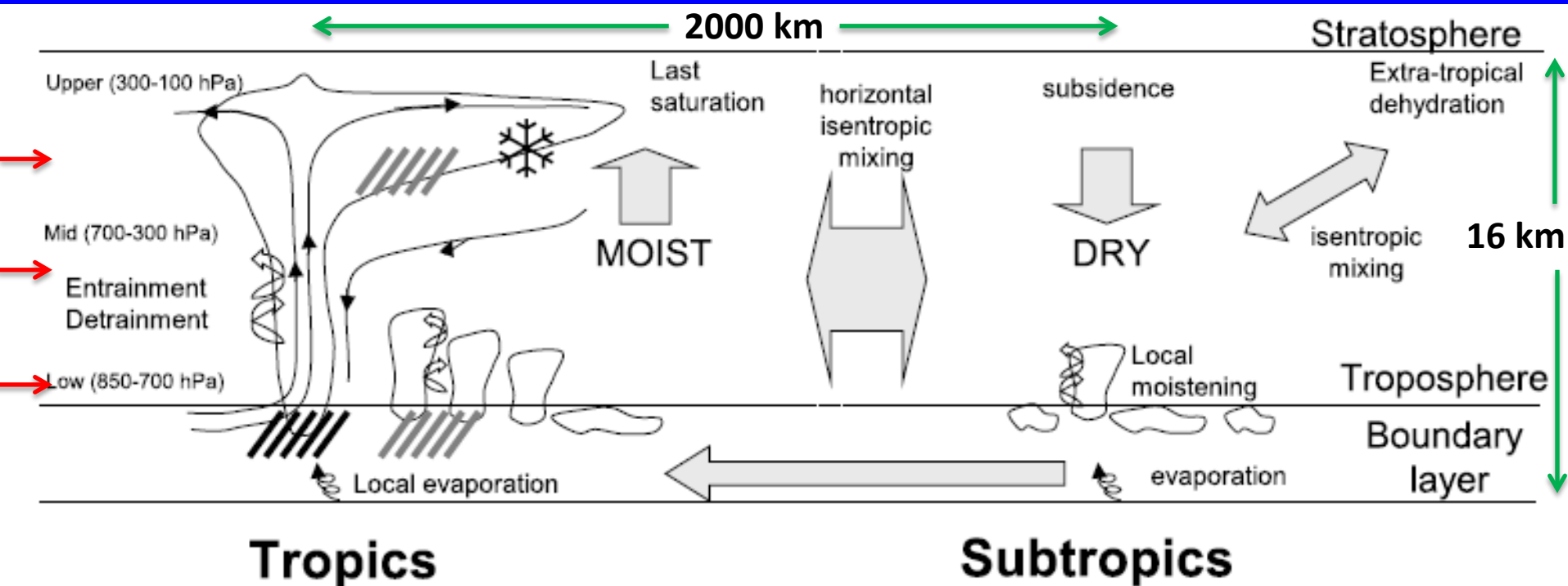
Separating the Errors

- Estimate water vapor error from negative tail of distribution (Kursinski & Gebhardt, 2014)
- Resulting errors somewhat smaller than predictions of Kursinski & Hajj, 2001
 - In part because low lat. analysis temperature errors are smaller

	Specific Humidity Error (g/kg)		Fractional Refractivity Error (%)		Temperature Error (K)		Reference Pressure Error (%)	
Pressure level (hPa)	KH01	Error deconv	KH01	Error deconv	KH01	Error deconv	KH01	Error deconv
346	0.24	0.14	0.2	0.2	1.5K	0.85K	0.3%	0.19%
547	0.31	0.25	0.5	0.6	1.5K	0.85K	0.3%	0.19%
725	0.47	0.39	0.9	1	1.5K	0.85K	0.3%	0.19%

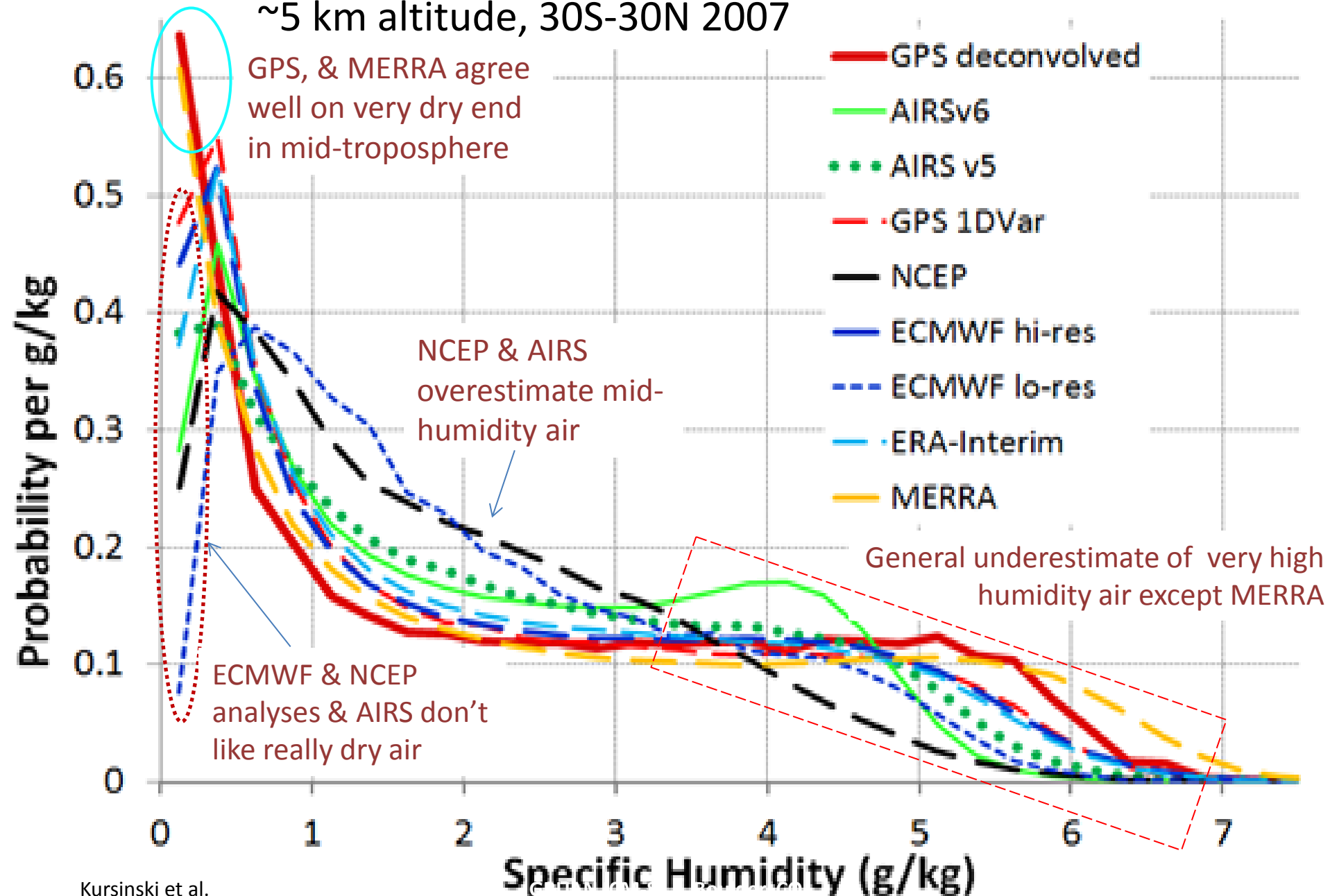
Low Latitude Moisture

- Convection creates extremes, stretching the H₂O vapor distribution
- **Mixing & diffusion compress distribution toward its center**
- Specific humidity is conserved in the absence of sources & sinks => **tracer**
- Relative humidity important for conversion between vapor & condensed phases => **clouds & precipitation**



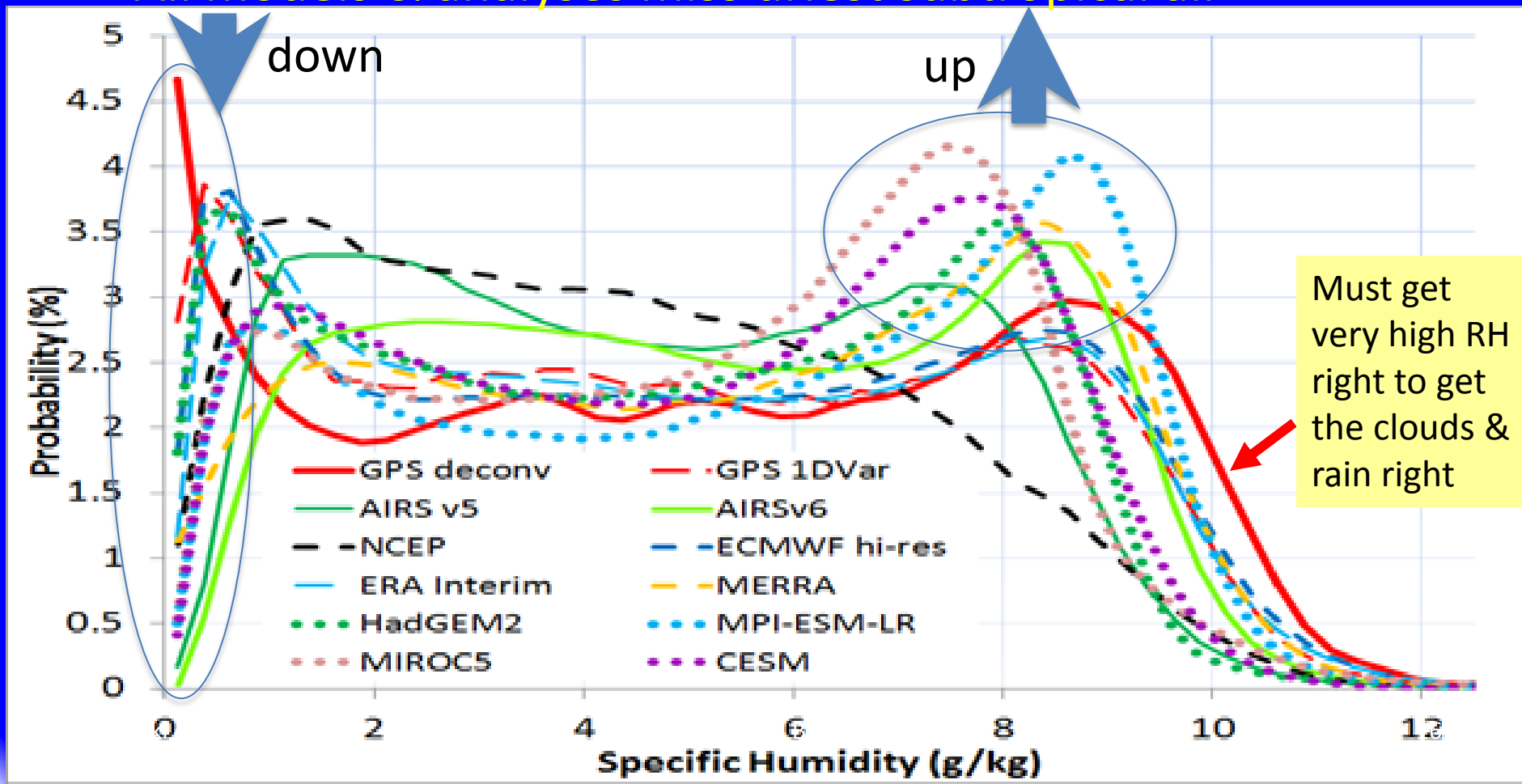
547 hPa Specific Humidity Comparisons

~5 km altitude, 30S-30N 2007



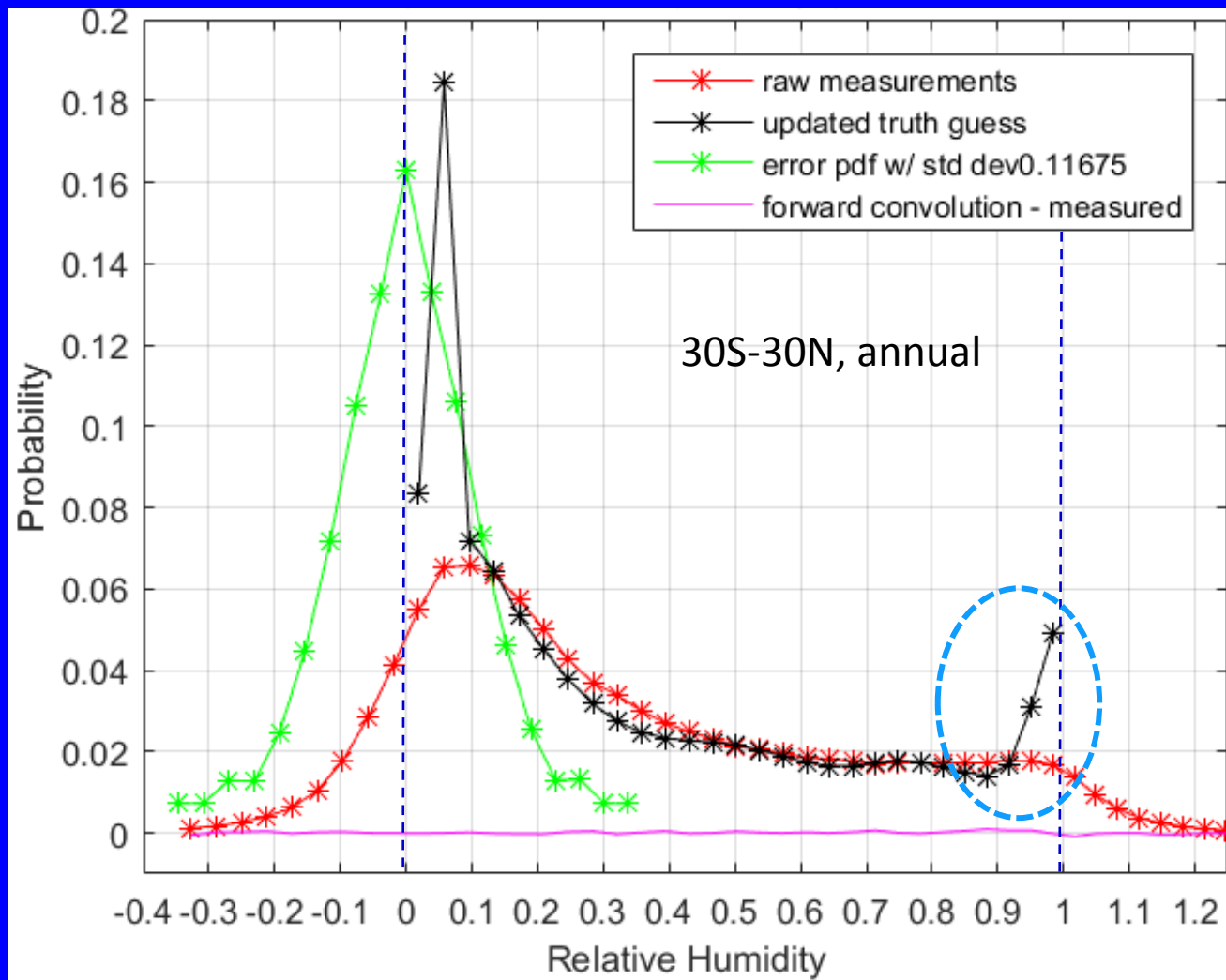
Climate Model & Analysis Comparison 725 mb

- Model peak q on wet end is a bit small except in MPI
- Modeled % of wet air near the peak is too high
- MERRA % too high; ECMWF slightly too low
- All models & analyses miss driest subtropical air



Relative Humidity Deconvolution Results at 346 mb

- Deconvolution indeed yields a peak near 100% RH



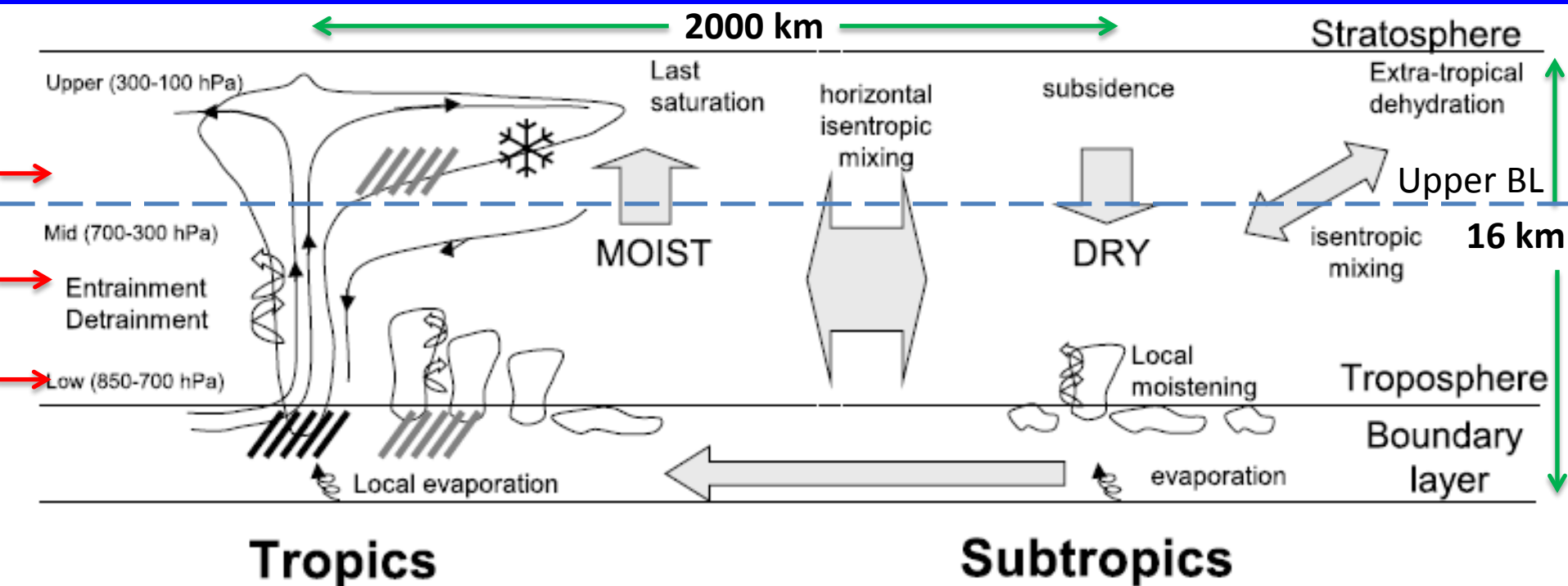
Signature of Convective Boundary Layers

Classical convection: “hot” boundary layer at the bottom bringing heat into the system + “cold” boundary layer at the top removing heat from the system

In Earth’s atmosphere,

- The bottom boundary layer is heated by the hot surface heated by the sun
- The upper boundary layer in the UT cools the atmosphere by radiating IR to space
- Air rising into this upper layer diverges and spreads out horizontally

The observed peak near 100% RH in the 346 mb histogram is a signature that this air is in the upper boundary layer

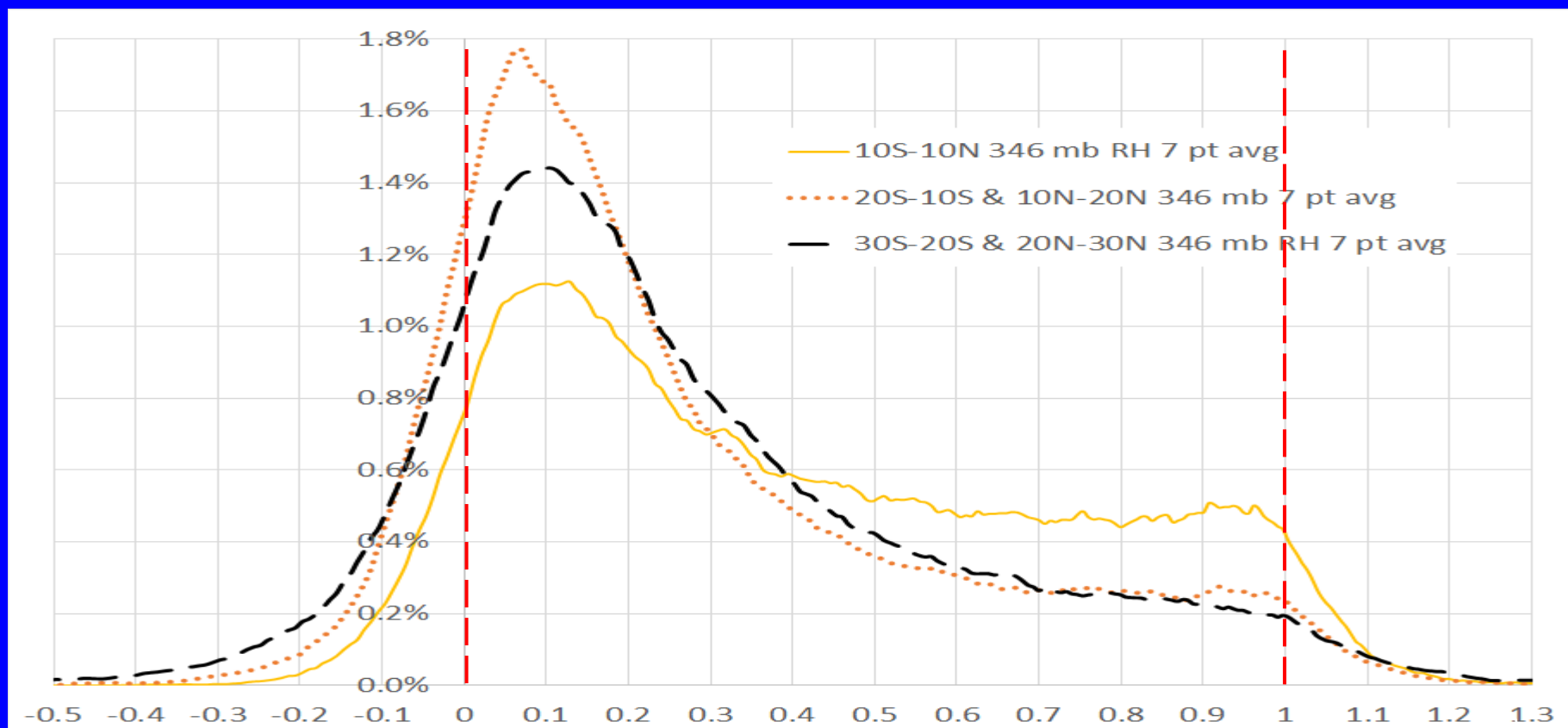


Temperature Error Influence on RH Histograms

Width of unphysical tails varies with latitude

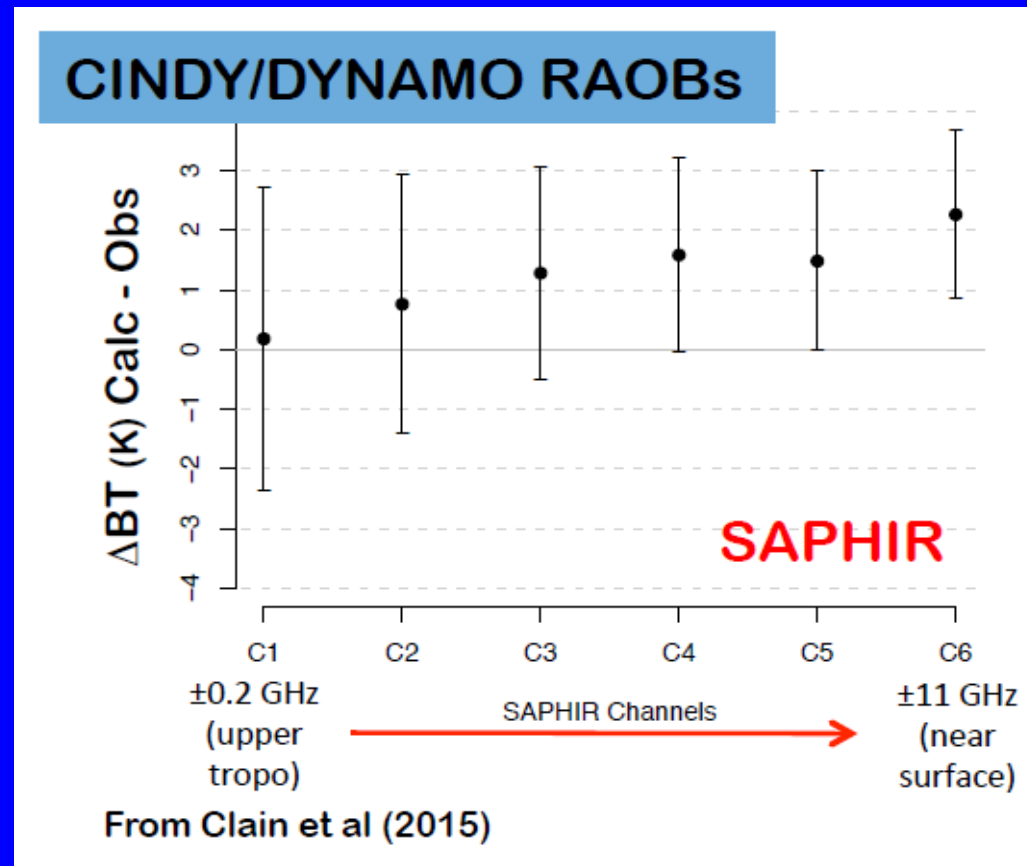
- Narrower in the 10S to 10N interval (where Coriolis is ~ 0)
- Widest in the 20 to 30 interval

Due primarily to analysis temperature error variation with latitude

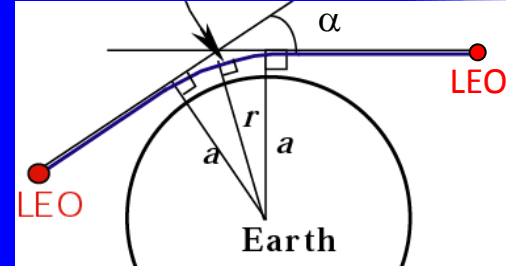


183 GHz Problem

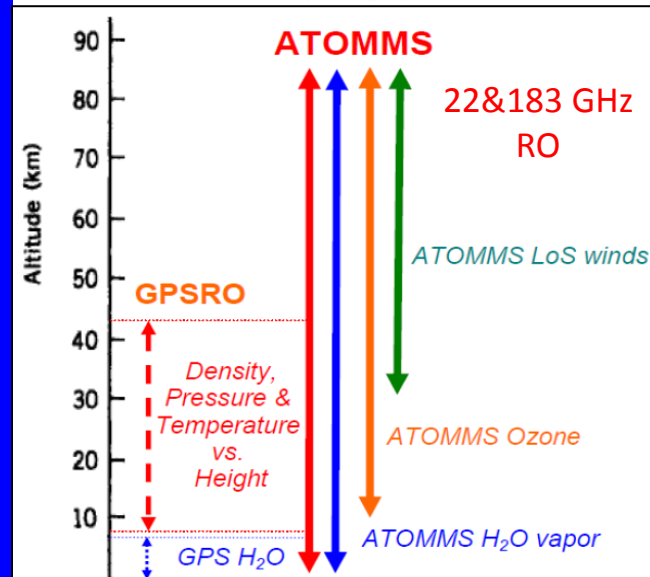
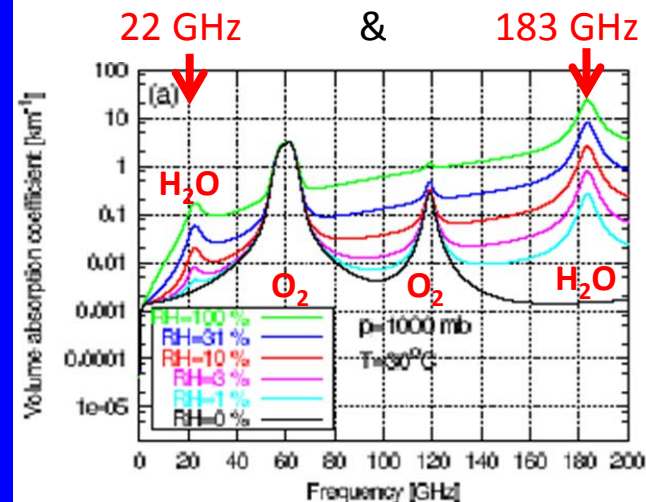
- Mismatch in the wings of 183 GHz line between measured radiances & forward radiative transfer calculations: **Too little opacity in the modeled wings**
- June 2015 Workshop in Paris
- Brogniez et al. in review in *AMT*



22 & 183 GHz RO Active Spectrometer



RO geometry: Transmit & Receive



- Profiles speed of light (like GPS RO) + attenuation of light (unlike GPS RO)

⇒ Profiles H₂O vapor, temperature & pressure versus height **simultaneously**, unlike GPS RO

in clear & cloudy air, over land & water

- 22 GHz: surface into upper troposphere
- 183 GHz: upper troposphere to mesopause

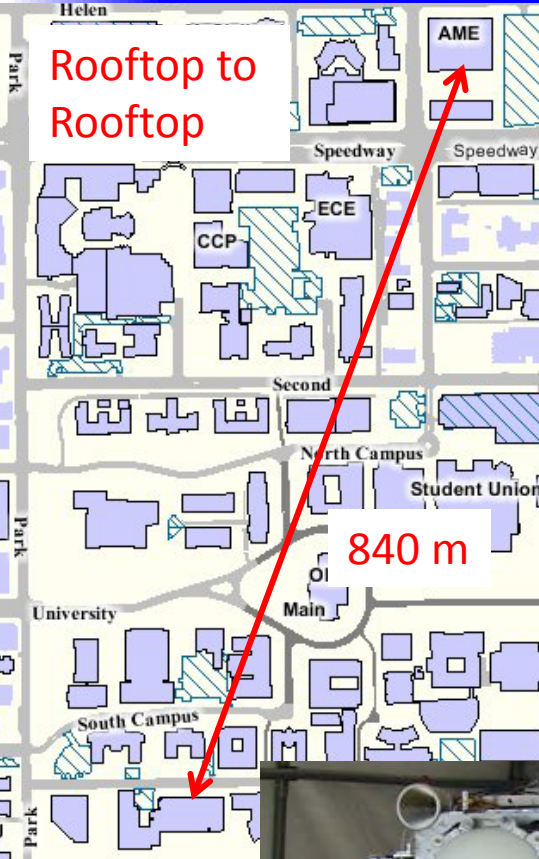
⇒ Also cloud LWC, O₃, NO₂, water isotopes, turbulence, LoS winds above 10 mb level

RO: Self calibrating, **no drift**

Resolution: ~100 m vertical, ~70 km horiz.

H₂O vapor: < 3% precision, < 1% accuracy

Temperature: 0.4K precision, < 0.05 K accuracy

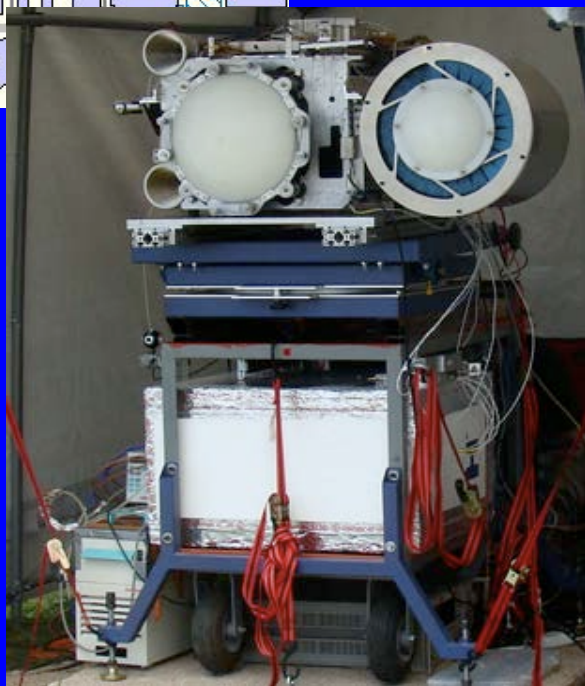
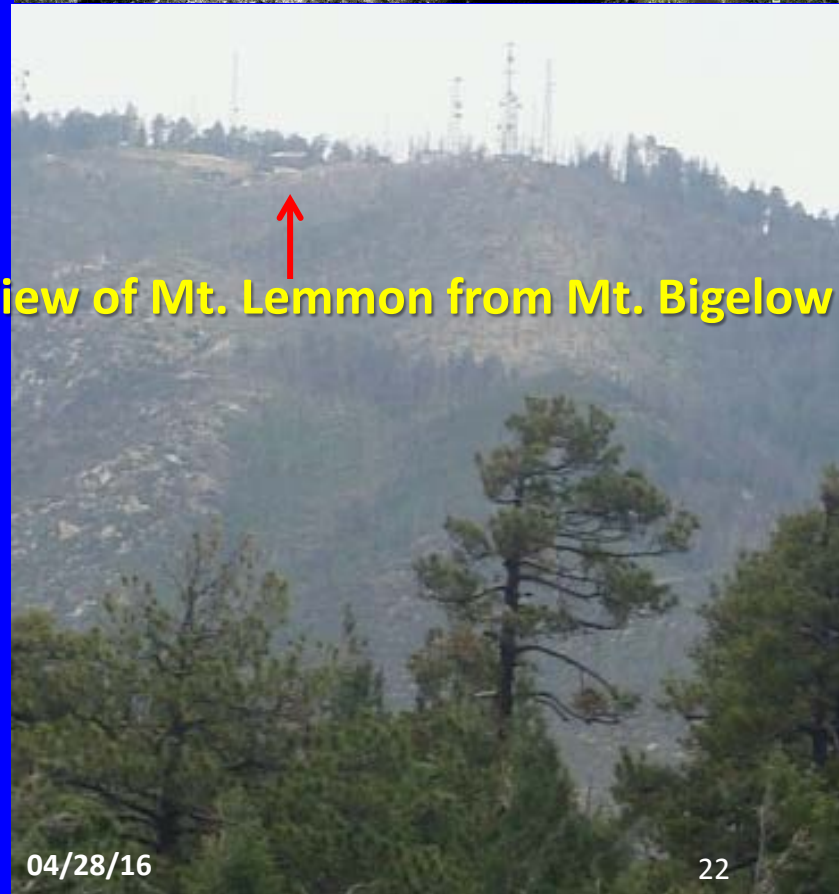


3 Field Test Geometries

- Rooftop: 840 m
- Lemmon to Bigelow: 5.4 km
- Hopkins to Lemmon: 84 km

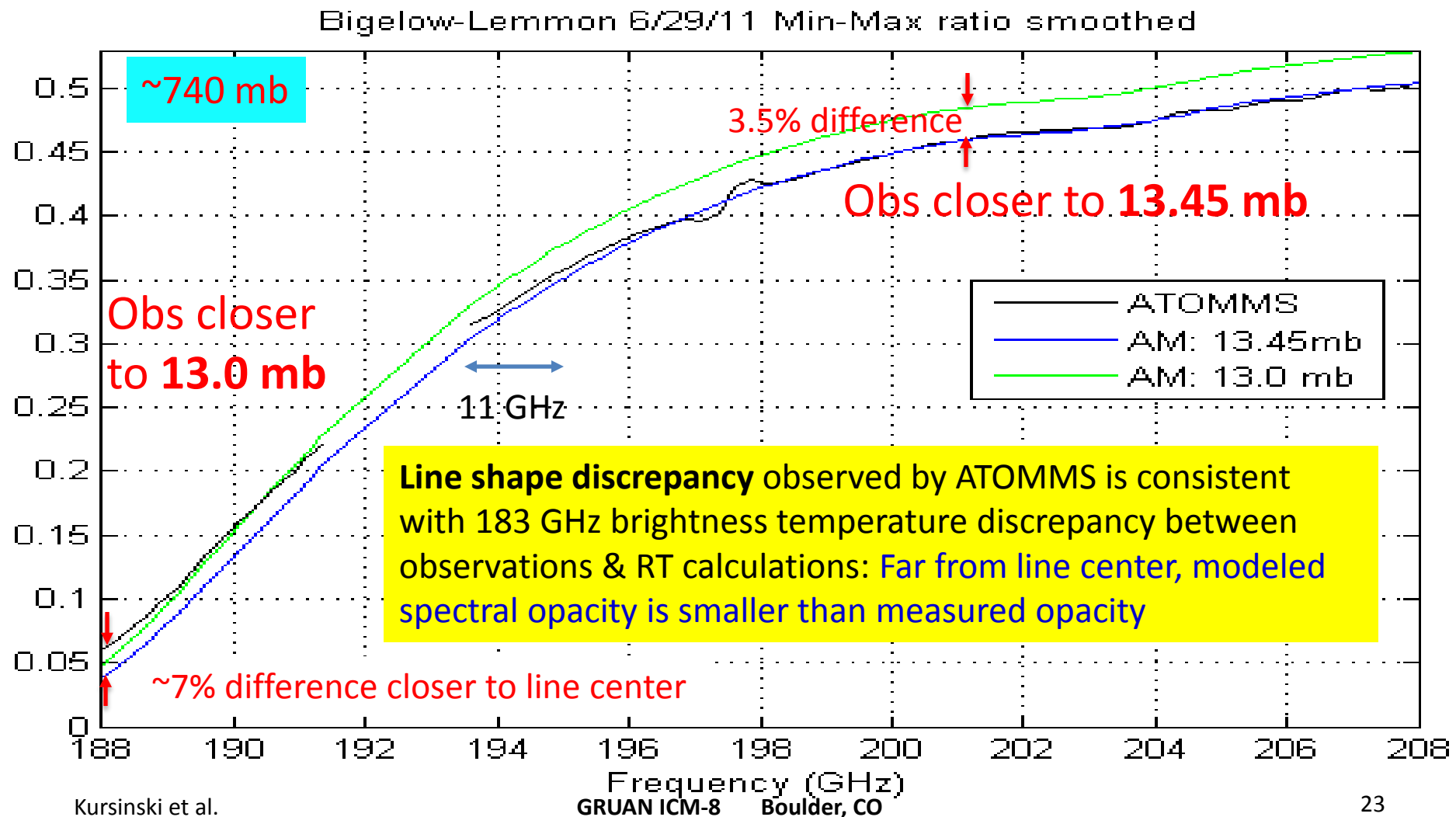


View of Mt. Lemmon from Mt. Bigelow



5.4 km Path Spectrum Reveals Spectral Discrepancy

- Spectral model AM6.2 of Scott Paine based on HITRAN and uses the MT_CKD water vapor continuum model

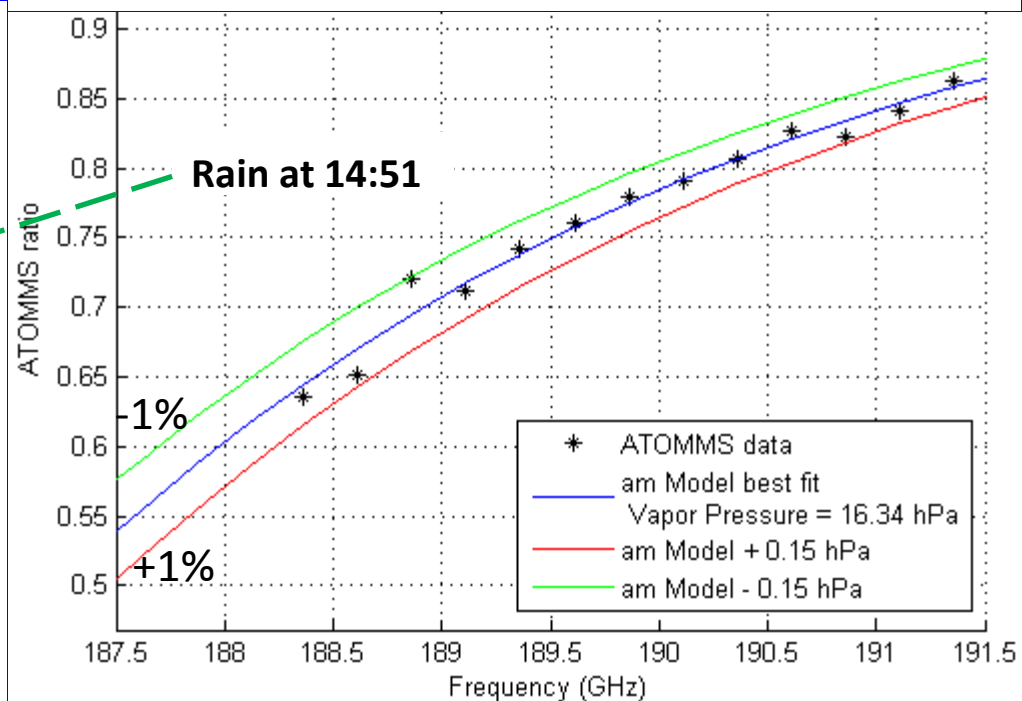
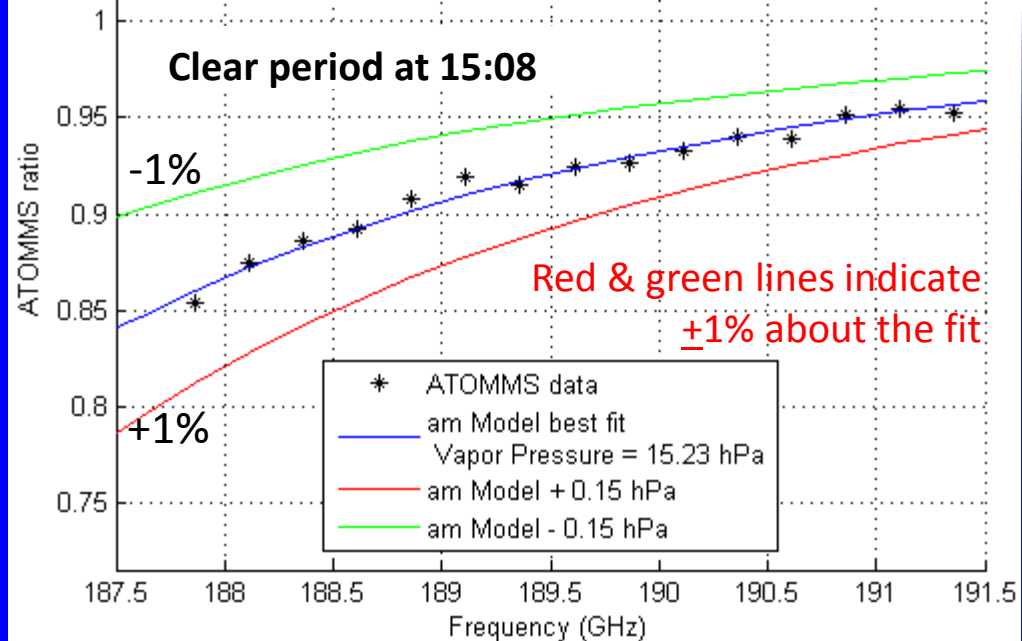
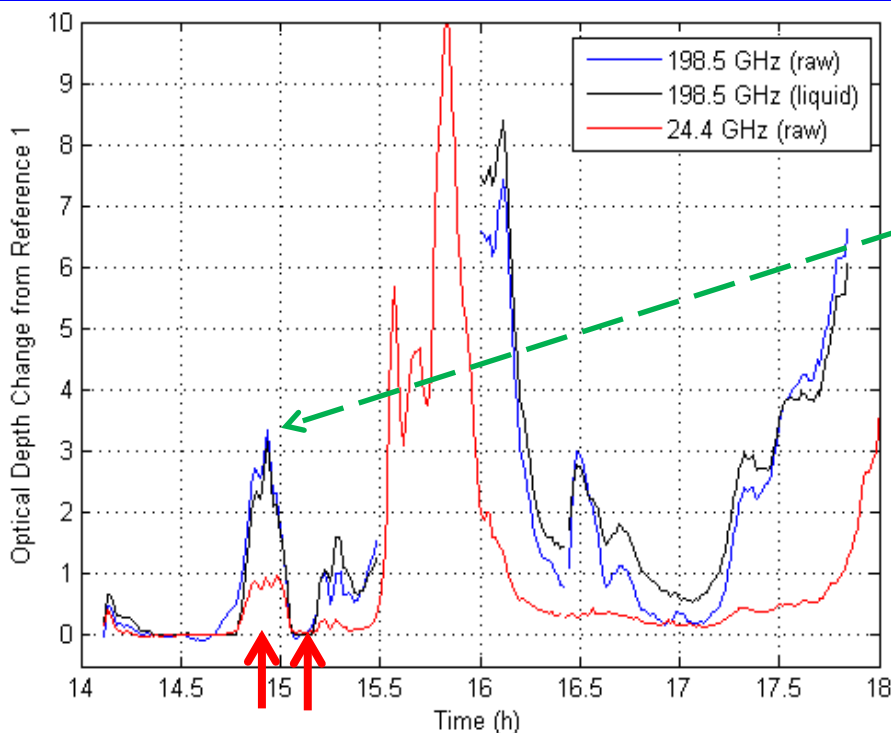


ATOMMS

Mountaintop Water Vapor Retrievals

During clear and rain

Random uncertainties <1%



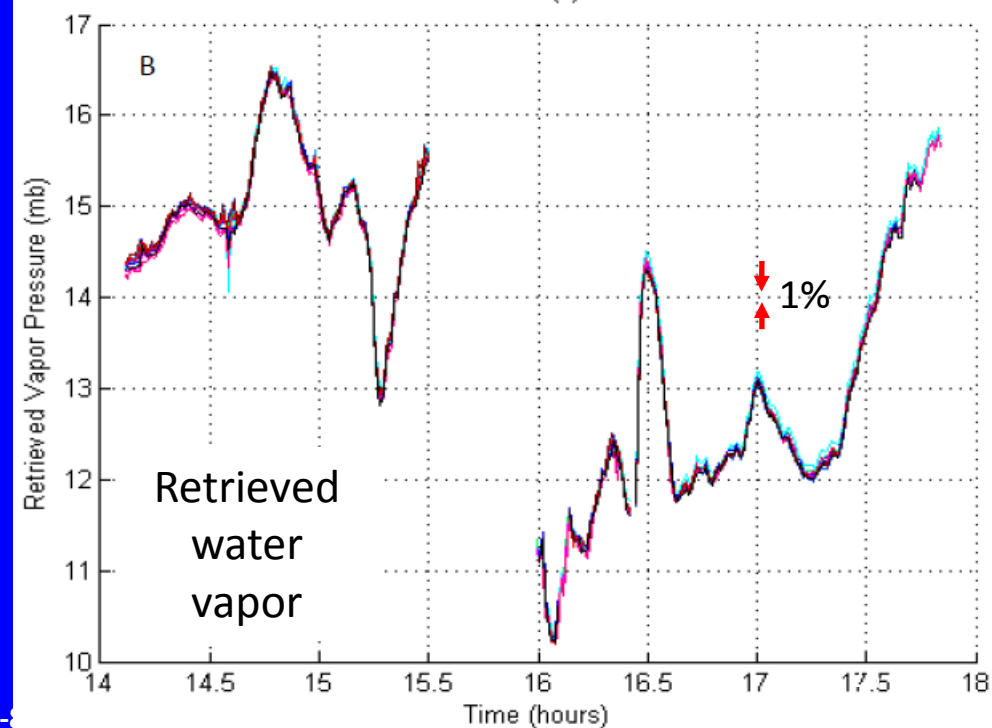
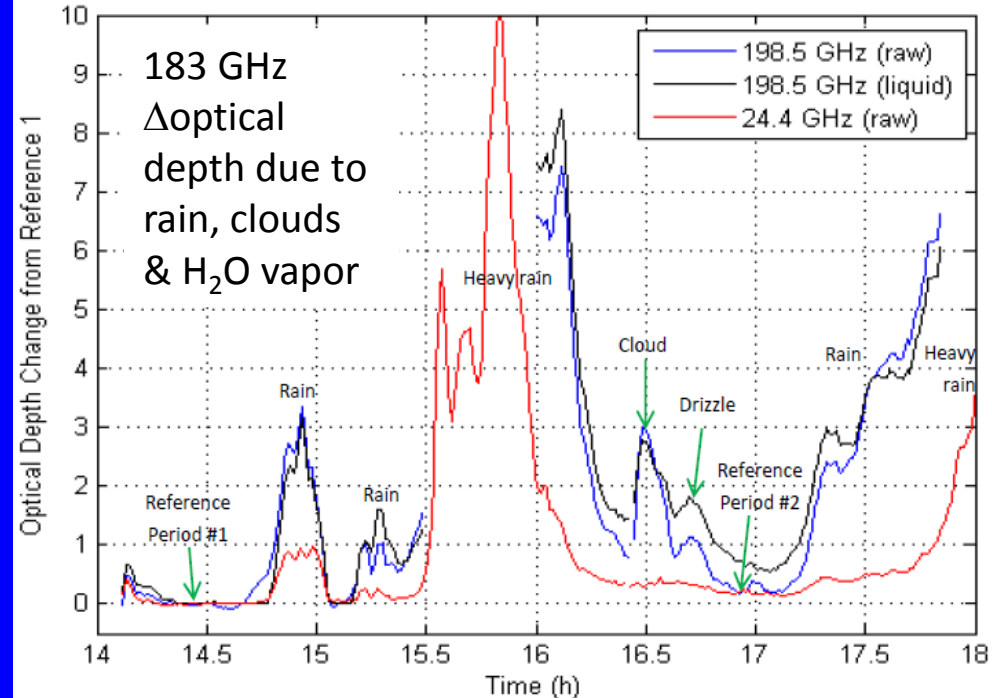
ATOMMS Mountaintop Results Summary

Mtn-top retrievals

- In clear, cloud & rain
- Optical depth up to 17

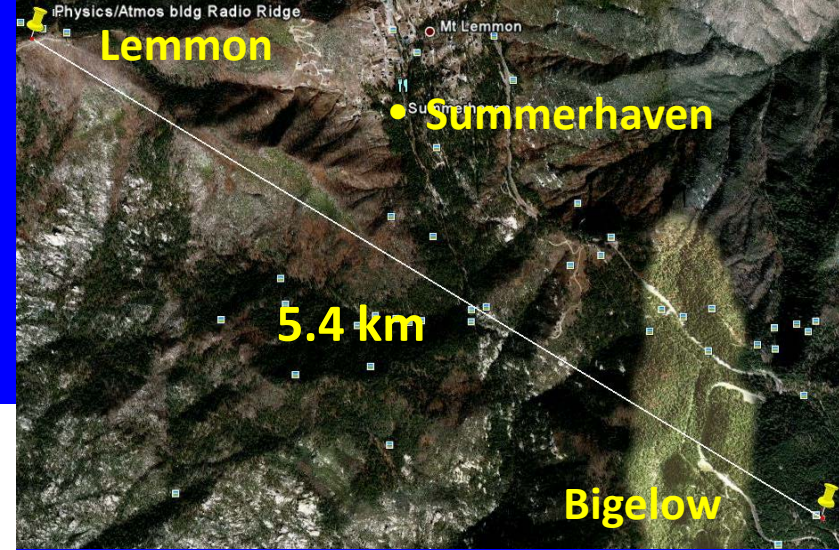
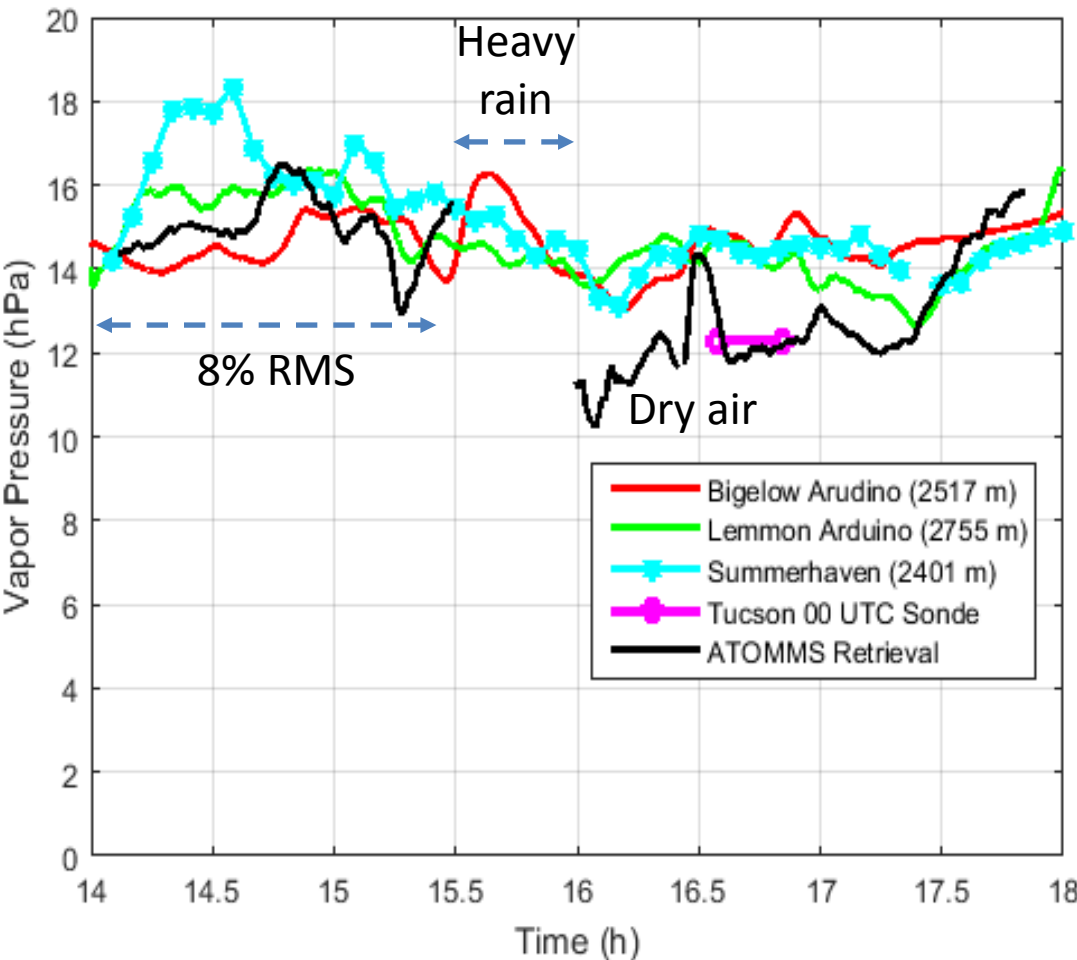
Water vapor retrievals

- Extremely little ambiguity even in rain
- Stdev < 1%
- Ward et al. (2015) resubmitting to GRL

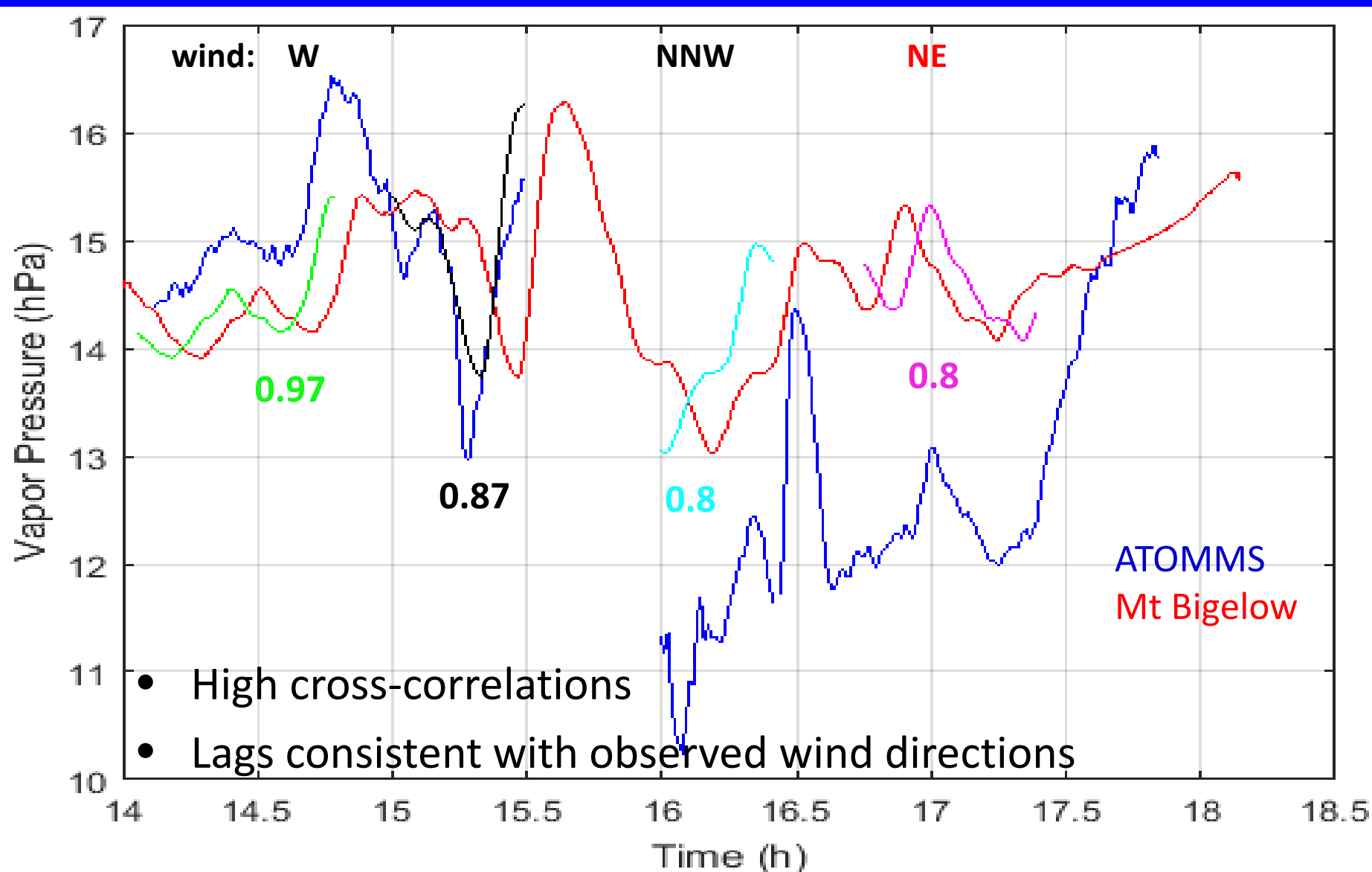


ATOMMS - *in situ* Water Vapor Comparison

- 3 nearby *in situ* sensors

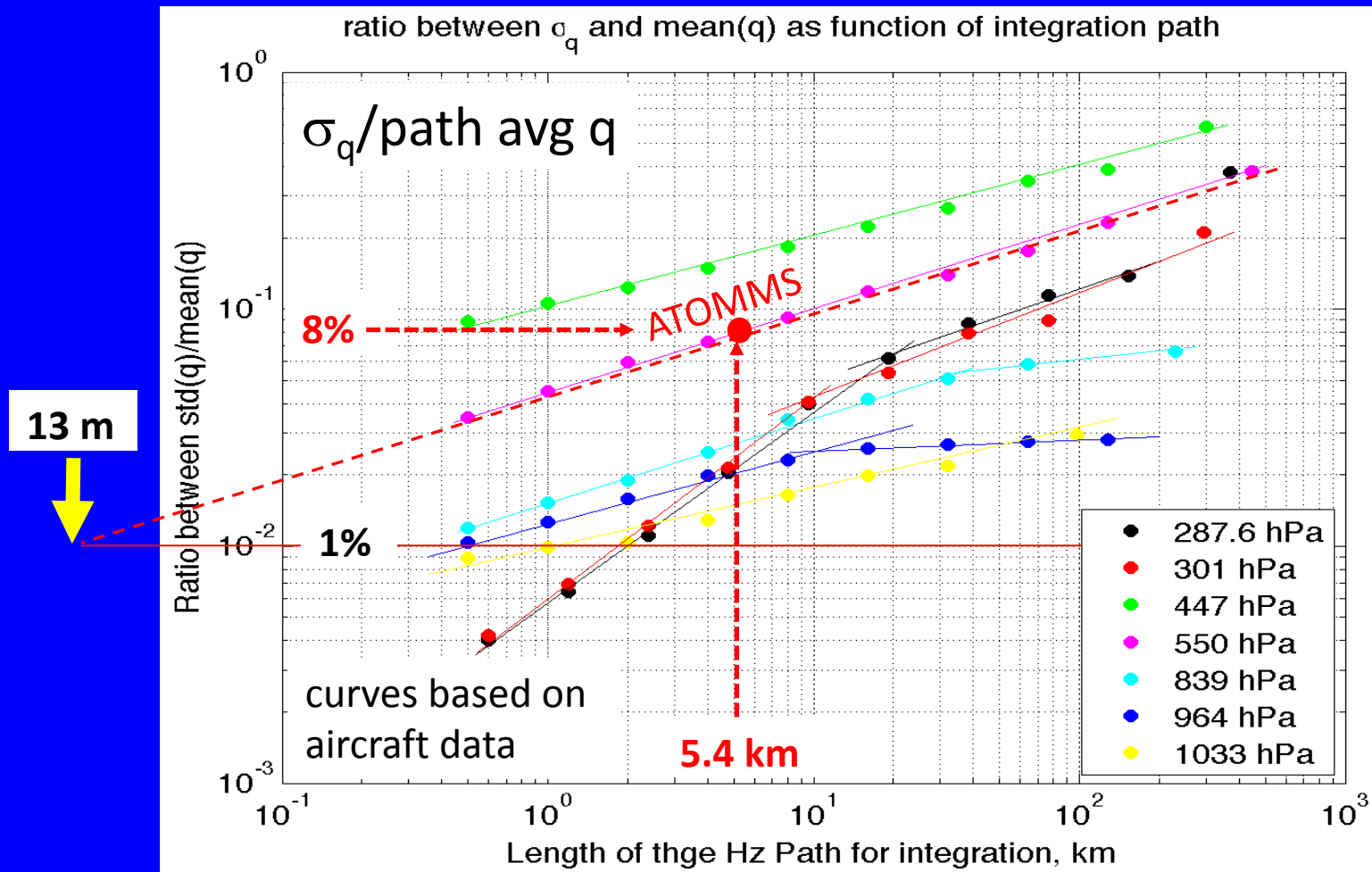


Correlations: **ATOMMS** vs. *Mt Bigelow in situ*



Challenge: How to validate a 5.4 km path average to 1%

- Requires ~400 1% *in situ* sensors, placed every 13 m along the **elevated** path, that operate to 1% in intense thunderstorms
 - Is this realistically doable?



Backup slides

Example: High Latitude Profiling

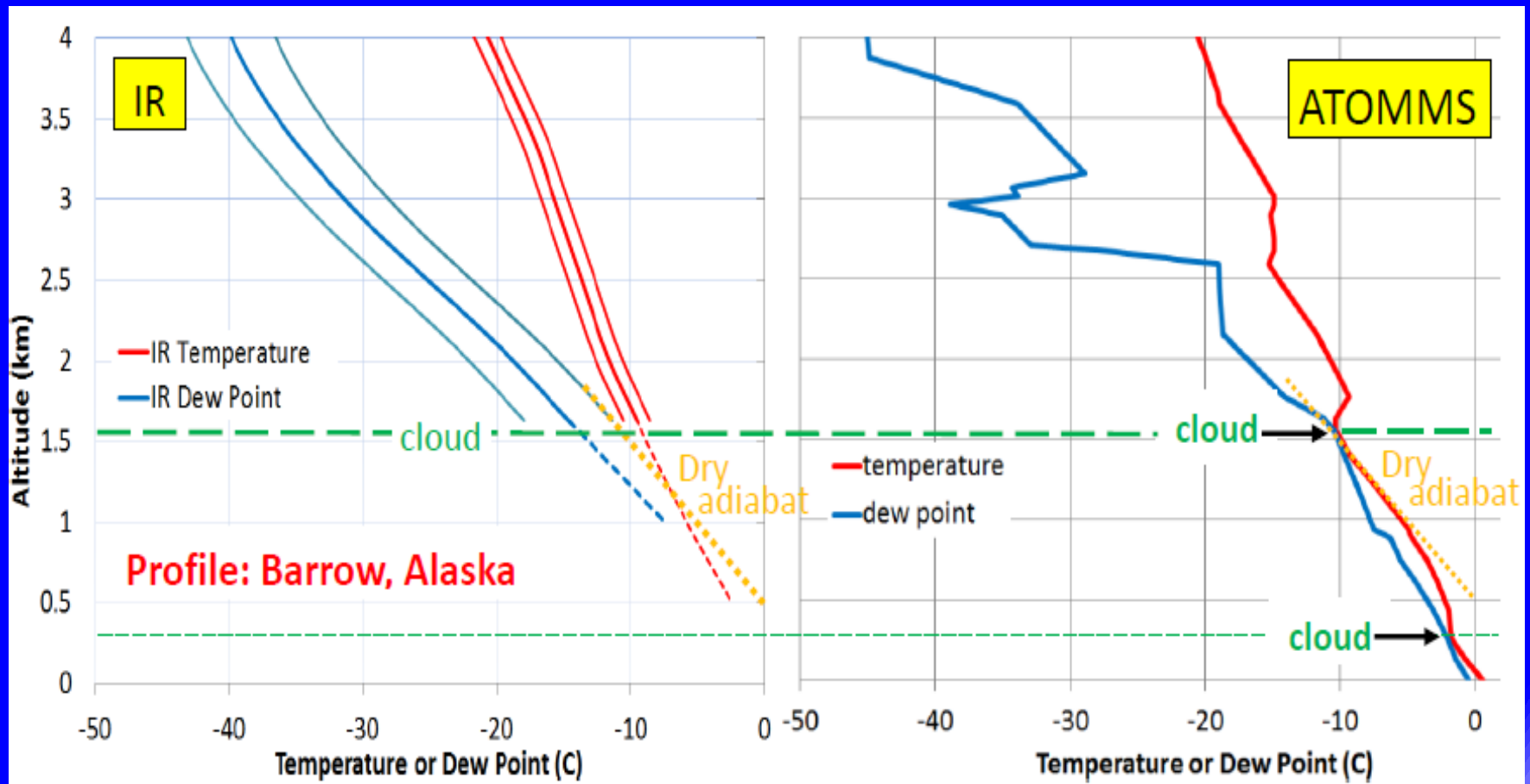
Large spread among sea ice melting predictions

- Uncertainties in modeled clouds & energy fluxes

Passive obs limited utility due to vertical resolution & sensitivity to surface emissivity & clouds

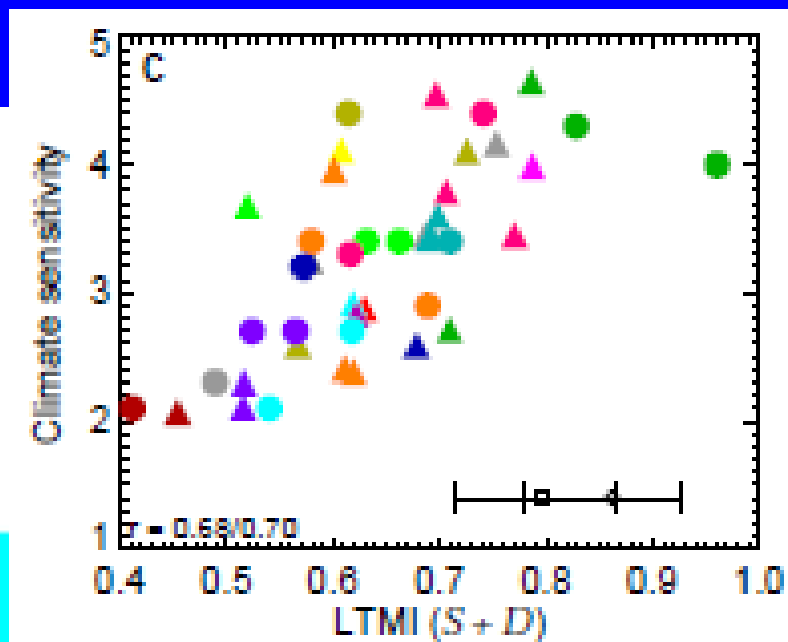
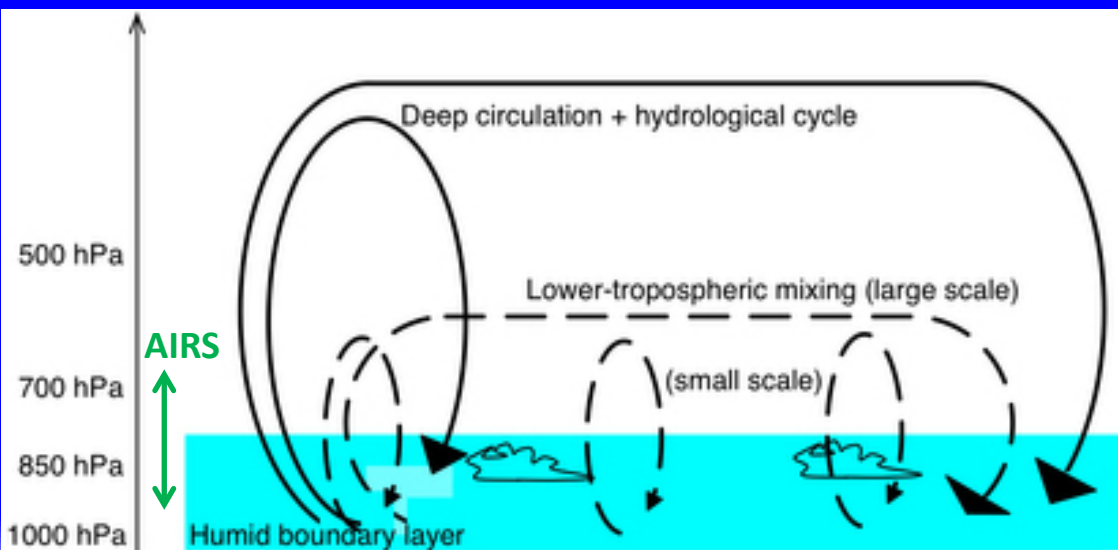
ATOMMS: routinely profile atmospheric structure to surface, sonde-like with better accuracy

- Resolve near surface temperature, stability, water vapor & cloud LWC structure**

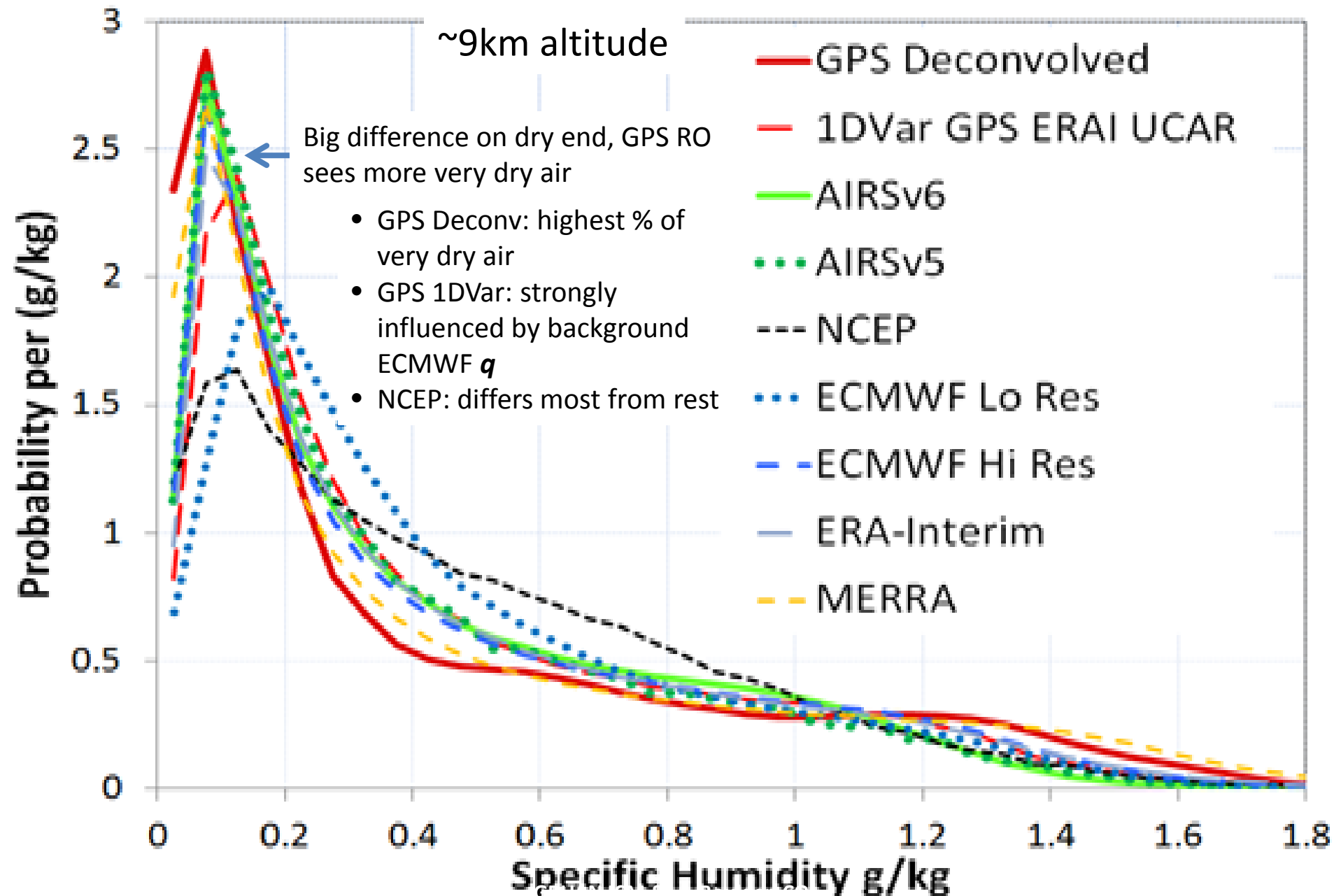


Sherwood et al. (2014) Reduction in Climate Uncertainty?

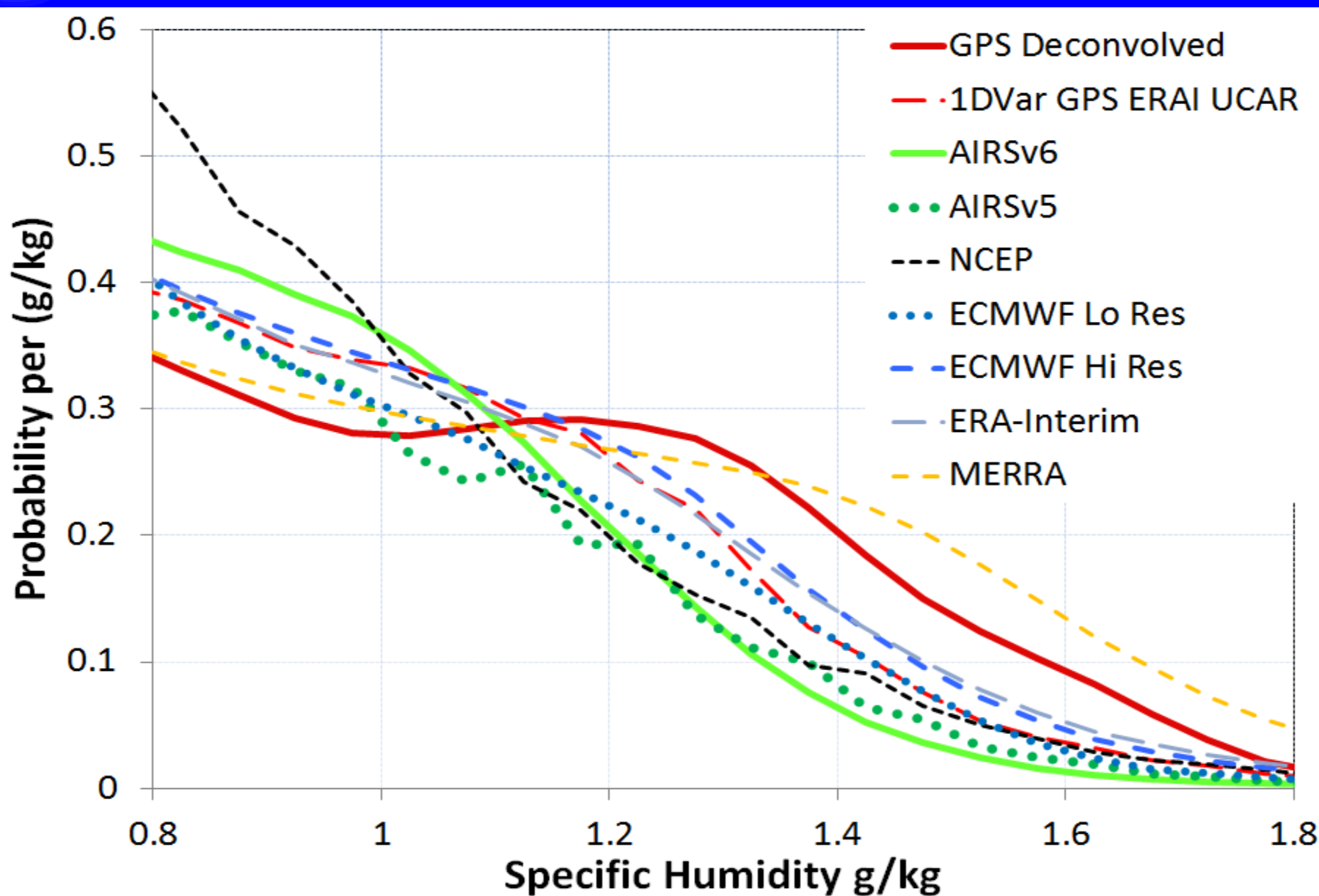
- As climate warms, models indicate stronger mixing => dehydrates BL
⇒ Reduces low cloud cover => lowers albedo => more SW absorption
- Increase in mixing & dehydration of low-cloud layer in warmer climate proportional to mixing strength in present climate
- Evaluated model mixing against “observations” (= MERRA analyses)
⇒ High climate sensitivity $> 3^{\circ}\text{C}$ for CO_2 doubling.



0.05 g/kg res. 346 hPa Specific Humidity 30S-30N 2007



346 hPa Low Latitude Comparison (2007)



Comparison of Estimates of Low Latitude Humidity Means

- Specific humidity: 30S-30N annual averages
- Means

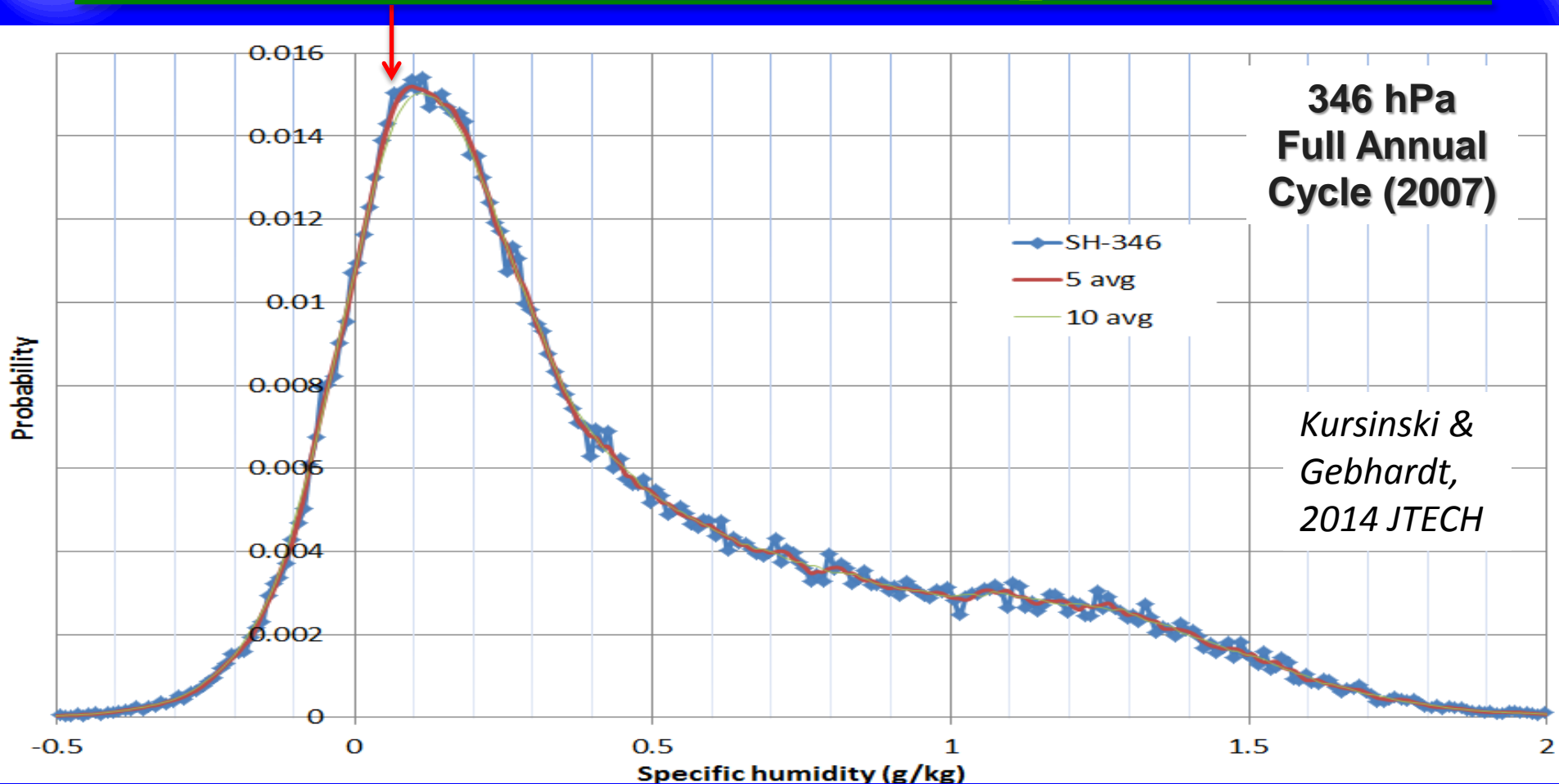
	GPS	AIRS v5	AIRS v6	ECWMF lo-res	ECMWF hi-res	MERRA	NCEP	Sat- Adv
346 mb	0.439	0.397	0.411	0.448	0.448	0.48	0.496	0.456
547 mb	2.22	2.12	2.12	2.29	2.14	2.43	1.98	2.51

- Fractional Differences Relative to GPS RO

	GPS	AIRS v5	AIRS v6	ECWMF lo-res	ECMWF hi-res	MERRA	NCEP	Sat- Adv
346 mb	0.0%	-9.6%	-6.4%	2.5%	2.5%	9.0%	13.5%	4.3%
547 mb	0.0%	-4.6%	-4.6%	3.2%	-3.6%	9.5%	-10.8%	13.1%

- Lots more going on than is captured in the means
 - MERRA histogram shapes closest to GPS but biased high in terms of mean

Constraining the GPS RO H₂O Vapor Bias



- 0.01 g/kg wide bins at 347 hPa => Sharp roll-off below 6th positive bin
- Expected due to coldest detrainment near 200 mb that returns to troposphere (Hartmann et al., 2001)
- Suggests **bias is no more than 0.03 g/kg** (Kursinski & Gebhardt 2014)